

ENGINEERING DOCUMENTATION

Coreless Brushless Motor

Dimensional & Integration Guide

DOCUMENT	REVISION / ISSUE	STATUS
DIG-ES-CM-BL03-M001	DRAFT-08 / 28 Aug 2026	Engineering Integration Reference

Integration Overview

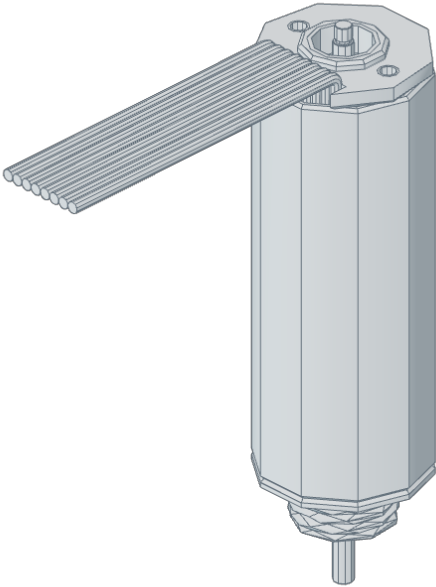
Compact electric motor for specified rotary actuation. This guide supports mounting, shaft, load-path, drive, thermal, cable and commissioning planning for ES-CM-BL03-M001.

Key Integration Facts

INTEGRATION ITEM	VALUE
Rated Torque	1.5 mNm
Rated Speed	28500 rpm
Continuous Rated Output Power	5 W
No-Load Rotational Speed	35000 rpm
Pole Pairs	1
Peak Current	3 A
Torque Constant	2.68 mNm/A
Continuous Rated Current	0.56 A

3D Orientation Reference

This axonometric reference provides a quick orientation check for the motor or actuator body, output interface and mounting relationship of ES-CM-BL03-M001.



Axonometric Orientation View

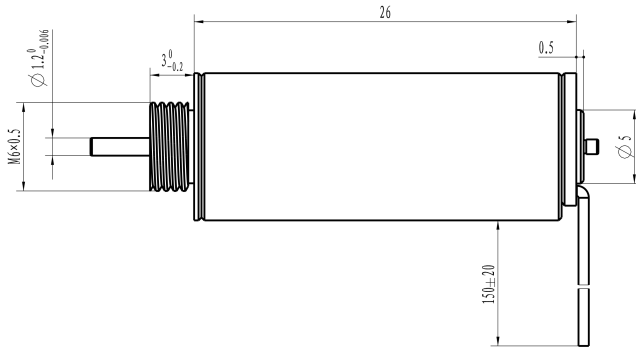
Orientation reference only. Use the exact-SKU parameter table and mechanical drawing for dimensions, hole geometry, fits and machining decisions.

Exact-SKU Interface Cross-Reference

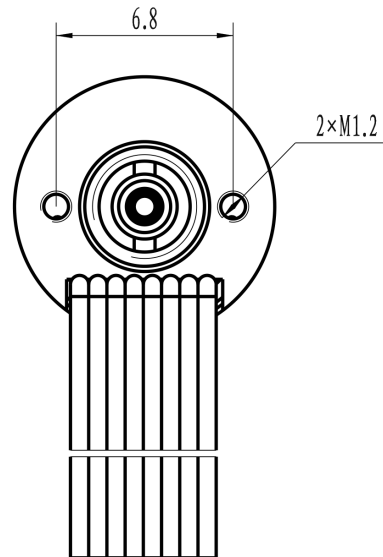
INTEGRATION TOPIC	EXACT-SKU REFERENCE
Motor envelope and output orientation	Motor Body Length: 26 mm. Confirm interface geometry, fits and installation details in the exact-SKU mechanical drawing.
Drive and motion boundaries	Rated Voltage: 12 V; Continuous Rated Current: 0.56 A; Rated Torque: 1.5 mNm; Rated Speed: 28500 rpm. Confirm interface geometry, fits and installation details in the exact-SKU mechanical drawing.
Installed load and thermal reference	Rotor Inertia: 0.026 gcm ² ; Weight: 14.3 g; Insulation Class: B; Duty Cycle: S2. Confirm interface geometry, fits and installation details in the exact-SKU mechanical drawing.

Product Structure & Views

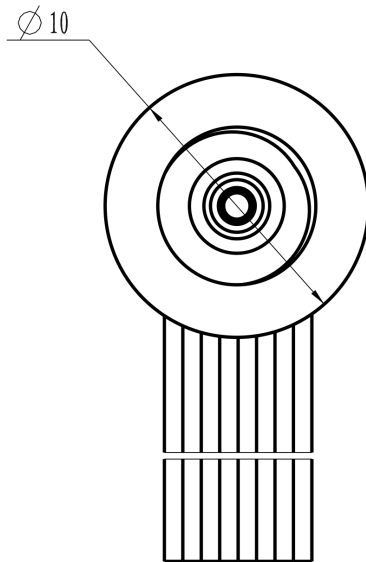
These views present product structure, mounting interfaces and relevant integration geometry for this SKU.



Mechanical View 1



Mechanical View 2



Mechanical View 3

VIEW	FIELD	VALUE
Mechanical View 1	Overall length	26 mm
	Shaft diameter with tolerance	$\Phi 2 - 0.006$ mm
	Threaded section length with tolerance	3 +0/-0.2 mm
	Right boss height	0.5 mm
	Thread specification	M6×0.5
	Right hole diameter	Φ mm
	Main body height with tolerance	150±20 mm
Mechanical View 2	Housing maximum width	6.8 mm
	Mounting hole specification and quantity	2 × M1.2 threaded holes
Mechanical View 3	Hole diameter	$\Phi 0$

Technical Specifications

PARAMETER	VALUE	UNIT
Rated Torque	1.5	mNm
Rated Speed	28500	rpm
Continuous Rated Output Power	5	W
No-Load Rotational Speed	35000	rpm
Pole Pairs	1	
Peak Current	3	A
Torque Constant	2.68	mNm/A
Continuous Rated Current	0.56	A
Insulation Class	B	
Dielectric strength	300VAC/1KHz/1mA/1s	VAC
Insulation Resistance	100 MΩ/300VDC	MΩ
No-load Current	0.065	A
Rated Voltage	12	V
Shaft material		
Weight	14.3	g
End-cap material		

Technical Specifications - Continued

PARAMETER	VALUE	UNIT
Mechanical Time Constant	1.63	ms
Rotor Inertia	0.026	gcm ²
Bearing type		
Motor Weight	14.3	g
Peak torque	7.15	mNm
Feedback method		
Winding connection		
Back-EMF Constant (Peak)	0.46	V/Krpm
Magnet material	NdFeB	
Motor Body Length	26	mm
Commutation angle	120	°
Housing-to-Ambient Thermal Resistance	10.6	K/W
Motor efficiency	67	%
Back-EMF constant (RMS)	0.28	V/Krpm
Line resistance	4.5	Ω
Maximum Winding Temperature	70	°C

Technical Specifications - Continued

PARAMETER	VALUE	UNIT
Housing Type	T	
Line inductance	0.15	mH
Ambient temperature	22.3	°C
Duty Cycle	S2	
Motor diameter	10	mm

Mounting, Shaft and Load Path

- Support the complete mounting face, preserve locating features and verify fastener engagement without distorting the housing.
- Align the shaft and coupling before tightening, and validate radial load, axial load, overhung distance, belt tension, inertia and shock for the installed mechanism.

Drive, Electrical and Motion Integration

- Coordinate supply, drive current limit, speed, torque and fault protection with the actual load and duty cycle.
- Use applicable wiring data for conductor identity, polarity, phase pairing, shielding and grounding; do not infer these from the product view.

Thermal, Cable and Commissioning Conditions

- Validate housing and winding temperature over the intended operating cycle, ambient condition, mounting heat path and enclosure airflow.
- Provide strain relief and service clearance, then commission at reduced energy and verify direction, current limits, motion response, temperature and fault behavior.

Integration Checklist

- | | |
|----|---|
| 01 | Confirm the exact-SKU drawing and parameter set. |
| 02 | Verify mounting geometry, locating features, shaft engagement, coupling alignment and service clearance. |
| 03 | Validate torque, speed, inertia, radial and axial loads, overhung distance and shock. |
| 04 | Set drive, current, motion, wiring, grounding and thermal boundaries from applicable product documentation. |
| 05 | Commission at reduced energy and verify direction, motion response, temperature and fault behavior. |

[View SKU Product Datasheet](#) [Request controlled 2D drawing](#) [Request controlled STEP review](#) [Request a Quote](#)

Engineering Use and Verification Notice

01. This Dimensional & Integration Guide applies only to EmbodyStack SKU ES-CM-BL03-M001 and is intended for dimensional evaluation and preliminary integration. It is not a applicable manufacturing drawing, motor or actuator application approval, wiring definition, drive-selection approval, machinery risk assessment, safety validation or production authorization. Before design freeze, installation or energization, verify all dimensions, mounting and locating features, moving envelopes, shaft or output geometry, permissible loads, alignment, supply and current limits, wiring, motion profile, duty cycle, thermal condition, cable routing, environmental boundaries, maintenance and fault response against the applicable EmbodyStack engineering data for this exact SKU. Validate the complete installed system under intended operating and fault conditions.