ENGINEERING DOCUMENTATION

Cup Component Set

Dimensional & Integration Guide

DOCUMENT	REVISION / ISSUE	STATUS
DIG-ES-HG-S01-F25-R30	DRAFT-08 / 28 Aug 2026	Engineering Integration Reference

Integration Overview

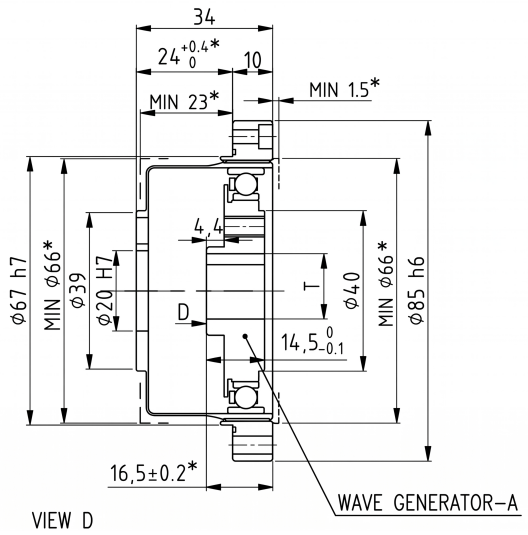
Cup Component Set for compact, coaxial, high-ratio rotary-axis integration. This guide supports interface planning, mounting alignment, duty validation, torsional behavior, lubrication, sealing and commissioning for ES-HG-S01-F25-R30.

Key Integration Facts

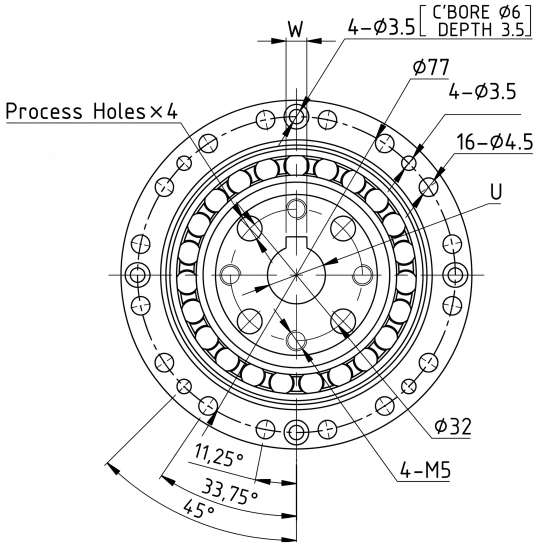
INTEGRATION ITEM	VALUE
Reduction Ratio	30
Frame Size	25

Product Structure & Views

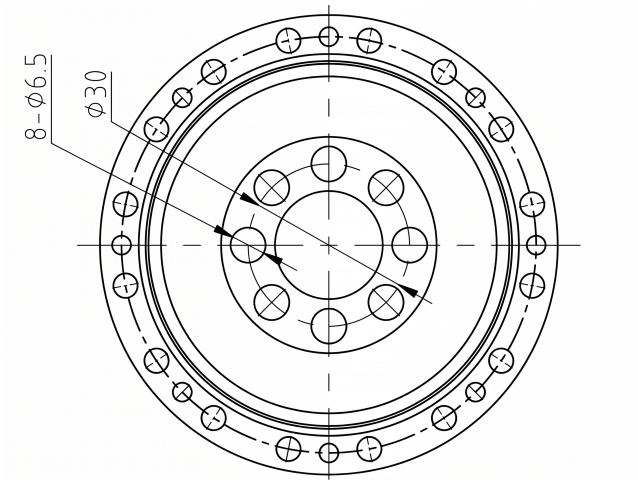
These views present the selected product structure, mounting interfaces and relevant integration geometry for this SKU.



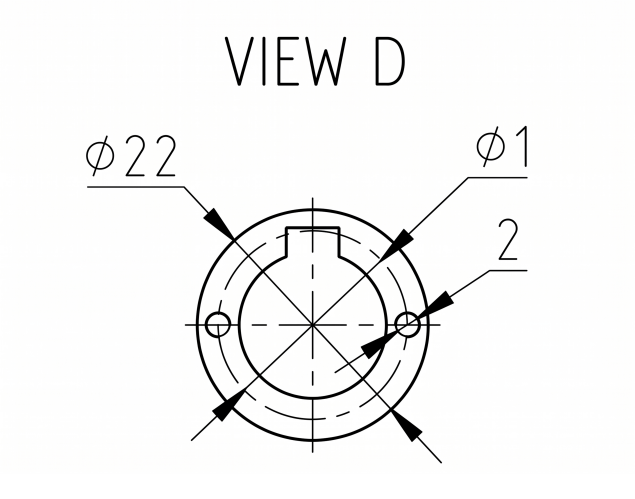
Mechanical View 1



Mechanical View 2



Mechanical View 3



Mechanical View 4

VIEW	FIELD	VALUE
Mechanical View 1	Top overall width	34 mm
	Upper step length with unilateral tolerance	24 mm +0.4/0
	Upper right step length	10 mm
	Minimum clearance	Minimum 1.5 mm
	Minimum length	Minimum 23 mm
	Outer diameter fit	Diameter 67 h7
	Minimum outside diameter	Minimum diameter 66 mm
	Diameter dimension	Diameter 39 mm
	Bore diameter fit	Diameter 20 H7
	Small step width	4.4 mm
	D view or datum marker	D
	Diameter dimension	Diameter 40 mm
	Outer diameter fit	Diameter 85 h6
	Axial height with unilateral tolerance	14.5 mm +0/-0.1
	Bottom length with symmetric tolerance	16.5 mm ±0.2
	Component label	Wave Generator-A
	T marker	T
	View identifier	View D
Mechanical View 2	Four counterbored holes	4 holes, through/pre-drill diameter Ø3.5, counterbore diameter Ø6, counterbore depth 3.5
	Width designation	Width designation W; numeric value not specified in this crop
	Outer diameter	Outer diameter Ø67
	Four diameter 3.5 holes	4 holes, diameter Ø3.5
	Process holes quantity	Process holes, quantity 4
	Sixteen diameter 4.5 holes	16 holes, diameter Ø4.5
	Feature designation U	Feature designation U; detailed value not specified in this crop
	Diameter 32	Diameter Ø32
	Angular spacing 11.25 degrees	11.25° angular dimension
	Four M5 threaded holes	4 × M5 threaded holes
	Angular spacing 33.75 degrees	33.75° angular dimension
	Angular spacing 45 degrees	45° angular dimension
Mechanical View 3	Mounting hole quantity and diameter	8 holes, diameter 6.5
	Central bore diameter	Diameter 30
Mechanical View 4	View identifier	View D
	Hole or circular feature diameter	Diameter 22 mm
	Local dimension value	2 mm
	Hole or circular feature diameter	Diameter 1 mm

Housing and Input Interface Dimensions

Housing Size: 25 **Reduction Ratio:** 30

WAVE GENERATOR	T (MM)	U	W
A11	12.8 +0.10	11 H7	4 JS9/P9
A14	16.3 +0.10	14 H7	5 JS9/P9

Note: Dimensions in mm unless otherwise specified. Refer to the dimensional drawing for feature locations and datum definitions.

Input Interface Design Guidance

- Confirm the selected series, frame size, ratio and product form before using dimensions or interface geometry.
- Design the input shaft, key, engagement and axial retention for the verified torque and assembly state.
- Reserve assembly, sealing, inspection and removal access around input, housing and output interfaces.

Mounting, Alignment and Fastener Control

- Keep mounting faces flat, clean and free of burrs, debris and coating buildup.
- Control concentricity, tilt and axial position of input and housing datums.
- Tighten fasteners in a staged diagonal sequence and verify free, even rotation during assembly.

Torque, Speed and Duty Boundaries

- Calculate torque and speed from acceleration, constant-speed, deceleration, dwell and reversal portions of the complete cycle.
- Treat start/stop peak and instantaneous maximum torque as transient boundaries.
- Validate life against actual torque, speed, shock frequency, lubrication, temperature, alignment and external loading.

Transmission Accuracy and Torsional Rigidity

- Installed positioning depends on reducer behavior, datum control, structural stiffness, motor and encoder errors and thermal growth.
- Use stiffness regions and transition torques when evaluating compliance, resonance, control gain and reversal.

Lubrication, Sealing and Thermal Control

- Use the specified lubricant, fill method and quantity for the exact configuration; do not mix incompatible lubricants.
- Provide compatible sealing at input, output and housing interfaces without distorting the reducer.
- Validate lubricant distribution and temperature for orientation, speed, load cycle and enclosure.
- Prevent chips, fibers, residue and moisture from entering gear or bearing cavities.

Output Bearing and External Load Path

- Calculate radial, axial and moment loads including offset, acceleration, gravity, process force, impact and emergency stops.
- Do not infer permissible external load from reducer torque capacity or frame size.
- Avoid forcing, impact, misalignment or host distortion through the output support during installation and operation.

Integration Checklist

01	Confirm the selected series, frame size, ratio and product form for this SKU.
02	Verify available dimensions and interface geometry without substituting a nearby configuration.
03	Check mounting-face flatness, concentricity, tilt, reliefs, cleanliness and support stiffness.
04	Verify input shaft, key, engagement length and axial retention.
05	Use staged diagonal tightening and verify free, even rotation.
06	Calculate average, start/stop peak and shock torque over the complete cycle.
07	Validate average and maximum input speed, design life and thermal condition.
08	Evaluate backlash, angular accuracy, hysteresis and stiffness for the control system.
09	Confirm lubricant, fill quantity, orientation, sealing and contamination controls.
10	Validate output radial, axial and moment loads using applicable bearing data.

View SKU Product Datasheet **Request controlled 2D drawing** **Request controlled STEP review** **Request a Quote**

Engineering Use and Verification Notice

01. This Dimensional & Integration Guide applies only to EmbodyStack SKU ES-HG-S01-F25-R30 and supports preliminary dimensional evaluation and integration. It is not a manufacturing drawing, reducer selection approval, bearing-load approval, lubrication specification, machinery risk assessment, safety validation or integration planning document. Before design freeze, assembly or commissioning, verify all dimensions, datum geometry, fits, interfaces, retention, fasteners, torque and speed duty, shock cases, torsional behavior, external loads, lubrication, sealing, temperature, contamination and maintenance requirements against the current EmbodyStack engineering data for this exact SKU. Validate the complete reducer, motor, host structure, output load, motion cycle, guarding, fault cases and applicable regulatory requirements under intended operating conditions.