

ENGINEERING DOCUMENTATION

Hat Component Set

Dimensional & Integration Guide

DOCUMENT	REVISION / ISSUE	STATUS
DIG-ES-HG-S02-F14-R100	DRAFT-08 / 28 Aug 2026	Engineering Integration Reference

Integration Overview

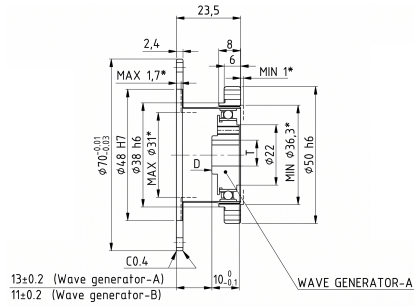
Hat Component Set for compact, coaxial, high-ratio rotary-axis integration. This guide supports interface planning, mounting alignment, duty validation, torsional behavior, lubrication, sealing and commissioning for ES-HG-S02-F14-R100.

Key Integration Facts

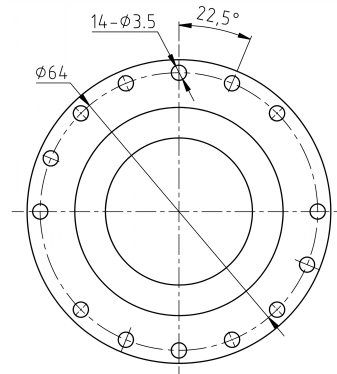
INTEGRATION ITEM	VALUE
Rated Torque	7.8 Nm
Instantaneous Maximum Torque	54 Nm
Start/Stop Peak Torque	28 Nm
Backlash	±0 arc sec
Reduction Ratio	100
Maximum Input Speed	8500 r/min
Frame Size	14
Weight	0.14 kg

Product Structure & Views

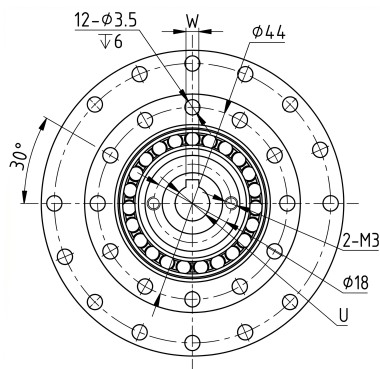
These views present the selected product structure, mounting interfaces and relevant integration geometry for this SKU.



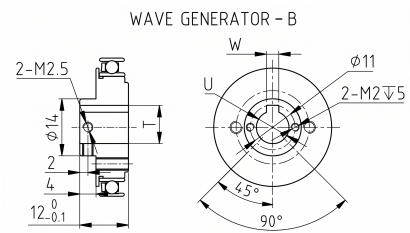
Mechanical View 1



Mechanical View 2

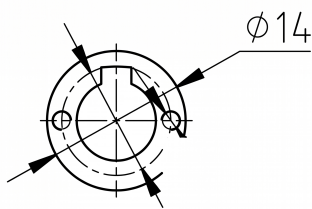


Mechanical View 3



Mechanical View 4

VIEW D



Mechanical View 5

VIEW	FIELD	VALUE
Mechanical View 1	Overall axial length	23.5
	Local axial step distance	2.4
	Upper right local width	8
	Upper right local width	6
	Minimum local clearance or step	Minimum 1
	Maximum local dimension	Maximum 1.7
	Minimum diameter	Minimum diameter 36.3
	Diameter	Diameter 22
	Fit diameter	Diameter 50 h6
	Fit diameter	Diameter 38 h6
	Bore fit diameter	Diameter 48 H7
	Diameter with bilateral negative deviations	Diameter 70, upper deviation -0.01, lower deviation -0.03
	Maximum diameter	Maximum diameter 31
	Parameter D	D, value not specified in this crop
	Chamfer	Chamfer C0.4
	Local axial dimension with unilateral tolerance	10, upper deviation 0, lower deviation -0.1
	Wave generator A dimension	13 ±0.2 for Wave generator-A
	Parameter T	T, value not specified
	Wave generator reference	Wave generator-Datum A
	Wave generator B dimension	11 ±0.2 for Wave generator-B
Mechanical View 2	Mounting hole diameter	14 mounting holes, Ø5 mm diameter
	Angular spacing between mounting holes	22.5° angular spacing
	Bolt circle diameter / Pitch circle diameter (PCD)	Ø4 mm bolt circle diameter
Mechanical View 3	Mounting hole quantity and diameter	12 holes, diameter 3.5 mm
	W marked width	W, value not specified in this crop
	Hole pitch circle diameter	Diameter 44 mm
	depth	6mm
	Angular spacing	30 degrees
	Threaded hole specification	2 threaded holes, M3
	Hole diameter	Diameter 18 mm
	U callout	U, value not specified in this crop
Mechanical View 4	View title	Wave generato-B
	Width symbol	W dimension symbol
	Diameter	Diameter 11 mm
	Threaded holes	2 x M2.5 threaded holes
	Threaded holes	2 x M2 threaded holes depth5mm
	Vertical dimension	14 mm
	Dimension symbol	U dimension symbol
	Step dimension	2 mm
	Step dimension	4 mm

VIEW	FIELD	VALUE
Angular position	45 degrees	
Width with tolerance	12 mm, +0 / -0.1	
Hole angular spacing	90 degrees	
Datum T	Datum T	

VIEW	FIELD	VALUE
Mechanical View 5	View D designation	View D
	Circular feature diameter	Φ4

Housing and Input Interface Dimensions

Housing Size: 14 Reduction Ratio: 100 Weight: 0.14 kg

WAVE GENERATOR	T (MM)	U	W
A8	9.4 +0.10	8 H7	3 JS9/P9
A11	12.8 +0.10	11 H7	4 JS9/P9
A14	16.3 +0.10	14 H7	5 JS9/P9

Note: Dimensions in mm unless otherwise specified. Refer to the dimensional drawing for feature locations and datum definitions.

Input Interface Design Guidance

- Confirm the selected series, frame size, ratio and product form before using dimensions or interface geometry.
- Design the input shaft, key, engagement and axial retention for the verified torque and assembly state.
- Reserve assembly, sealing, inspection and removal access around input, housing and output interfaces.

Mounting, Alignment and Fastener Control

- Keep mounting faces flat, clean and free of burrs, debris and coating buildup.
- Control concentricity, tilt and axial position of input and housing datums.
- Tighten fasteners in a staged diagonal sequence and verify free, even rotation during assembly.

Torque, Speed and Duty Boundaries

PARAMETER	VALUE	UNIT
Rated Torque	7.8	Nm
Allowable Average Torque	11	
Start/Stop Peak Torque	28	
Instantaneous Maximum Torque	54	
Maximum Input Speed	8500	r/min
Average Input Speed	3500	
Design Life	15000	h

- Calculate torque and speed from acceleration, constant-speed, deceleration, dwell and reversal portions of the complete cycle.
- Treat start/stop peak and instantaneous maximum torque as transient boundaries.
- Validate life against actual torque, speed, shock frequency, lubrication, temperature, alignment and external loading.

Torque, Speed and Life Boundaries

PARAMETER	VALUE	INTEGRATION REQUIREMENT
Rated Torque	7.8 Nm	Use as the selected continuous output rating under validated duty and thermal conditions.
Allowable Average Torque	11 Nm	Calculate the actual time-weighted output torque over the complete cycle.
Start/Stop Peak Torque	28 Nm	Transient start/stop boundary; include acceleration and deceleration events.
Instantaneous Maximum Torque	54 Nm	Short-duration shock boundary only; do not use as a normal operating point.
Maximum Input Speed	8500 r/min	Maximum input-speed boundary; also verify motor and thermal limits.
Average Input Speed	3500 r/min	Validate the time-weighted average input speed over the complete duty cycle.
Design Life	15000 h	Design reference only; actual life depends on torque, speed, shock, lubrication and installation.

Transmission Accuracy and Torsional Rigidity

PARAMETER	VALUE	UNIT
Backlash	20	arc sec

- Installed positioning depends on reducer behavior, datum control, structural stiffness, motor and encoder errors and thermal growth.
- Use stiffness regions and transition torques when evaluating compliance, resonance, control gain and reversal.

Lubrication, Sealing and Thermal Control

- Use the specified lubricant, fill method and quantity for the exact configuration; do not mix incompatible lubricants.
- Provide compatible sealing at input, output and housing interfaces without distorting the reducer.
- Validate lubricant distribution and temperature for orientation, speed, load cycle and enclosure.
- Prevent chips, fibers, residue and moisture from entering gear or bearing cavities.

Output Bearing and External Load Path

- Calculate radial, axial and moment loads including offset, acceleration, gravity, process force, impact and emergency stops.
- Do not infer permissible external load from reducer torque capacity or frame size.
- Avoid forcing, impact, misalignment or host distortion through the output support during installation and operation.

Integration Checklist

- 01 Confirm the selected series, frame size, ratio and product form for this SKU.
- 02 Verify available dimensions and interface geometry without substituting a nearby configuration.
- 03 Check mounting-face flatness, concentricity, tilt, reliefs, cleanliness and support stiffness.
- 04 Verify input shaft, key, engagement length and axial retention.
- 05 Use staged diagonal tightening and verify free, even rotation.
- 06 Calculate average, start/stop peak and shock torque over the complete cycle.
- 07 Validate average and maximum input speed, design life and thermal condition.
- 08 Evaluate backlash, angular accuracy, hysteresis and stiffness for the control system.
- 09 Confirm lubricant, fill quantity, orientation, sealing and contamination controls.
- 10 Validate output radial, axial and moment loads using applicable bearing data.

[View SKU Product Datasheet](#) [Request controlled 2D drawing](#) [Request controlled STEP review](#) [Request a Quote](#)

Engineering Use and Verification Notice

01. This Dimensional & Integration Guide applies only to EmbodyStack SKU ES-HG-S02-F14-R100 and supports preliminary dimensional evaluation and integration. It is not a manufacturing drawing, reducer selection approval, bearing-load approval, lubrication specification, machinery risk assessment, safety validation or integration planning document. Before design freeze, assembly or commissioning, verify all dimensions, datum geometry, fits, interfaces, retention, fasteners, torque and speed duty, shock cases, torsional behavior, external loads, lubrication, sealing, temperature, contamination and maintenance requirements against the current EmbodyStack engineering data for this exact SKU. Validate the complete reducer, motor, host structure, output load, motion cycle, guarding, fault cases and applicable regulatory requirements under intended operating conditions.