

ENGINEERING DOCUMENTATION

Hat Component Set

Dimensional & Integration Guide

DOCUMENT	REVISION / ISSUE	STATUS
DIG-ES-HG-S02-F17-R50	DRAFT-08 / 28 Aug 2026	Engineering Integration Reference

Integration Overview

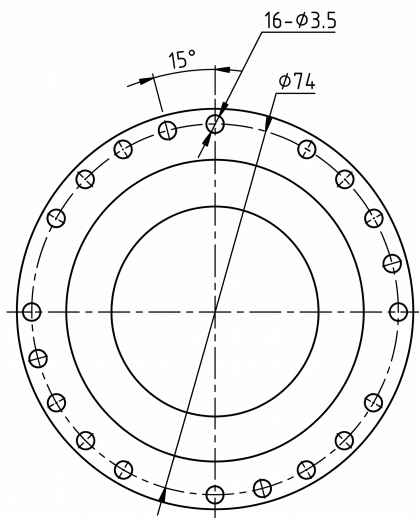
Hat Component Set for compact, coaxial, high-ratio rotary-axis integration. This guide supports interface planning, mounting alignment, duty validation, torsional behavior, lubrication, sealing and commissioning for ES-HG-S02-F17-R50.

Key Integration Facts

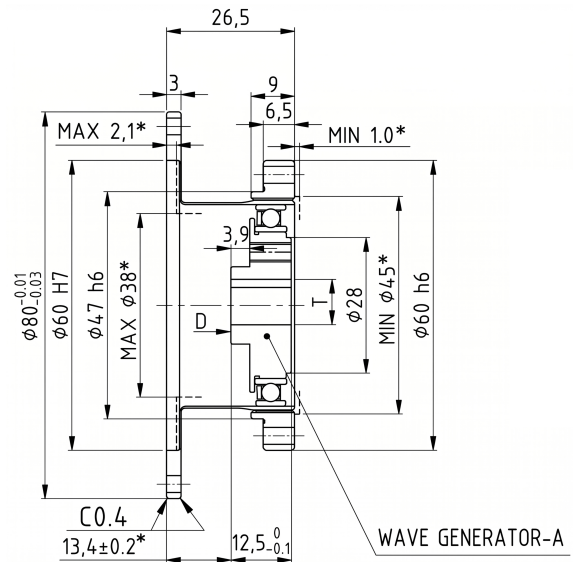
INTEGRATION ITEM	VALUE
Rated Torque	16 Nm
Instantaneous Maximum Torque	70 Nm
Start/Stop Peak Torque	34 Nm
Backlash	±0 arc sec
Reduction Ratio	50
Maximum Input Speed	7300 r/min
Frame Size	17
Weight	0.19 kg

Product Structure & Views

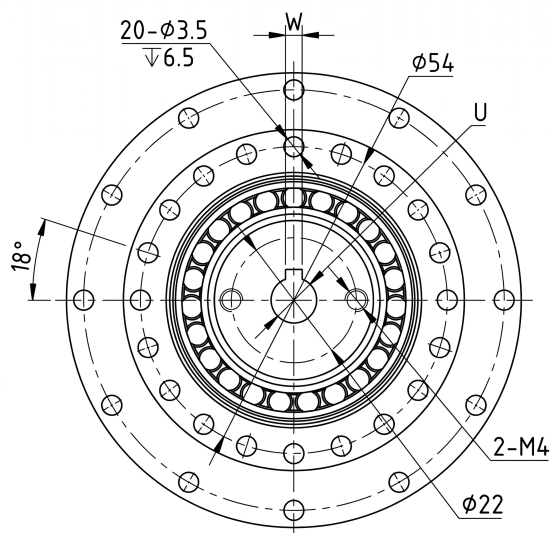
These views present the selected product structure, mounting interfaces and relevant integration geometry for this SKU.



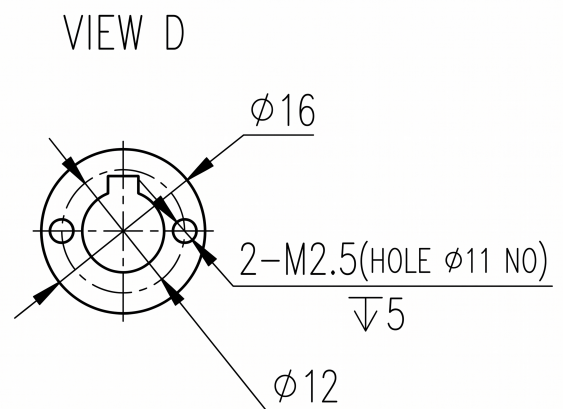
Mechanical View 1



Mechanical View 2



Mechanical View 3



Mechanical View 4

VIEW	FIELD	VALUE
Mechanical View 1	Mounting hole quantity and diameter	16 holes × Ø.5 mm
	Mounting hole angular pitch	15°
	Mounting hole bolt circle diameter (PCD)	Ø4 mm

VIEW	FIELD	VALUE
Mechanical View 2	Overall width	26.5 mm
	Left boss width	3 mm
	Right boss width	9 mm
	Inner groove width	6.5 mm
	Left side maximum height	MAX 2.1 mm (reference)
	Right side minimum height	MIN 1.0 mm (reference)
	Internal step height	3.9 mm
	Minimum outer diameter (right side)	MIN $\varnothing 5$ mm (reference)
	Maximum outer diameter (left side)	MAX $\varnothing 8$ mm (reference)
	Main shaft diameter with tolerance	$\varnothing 0$ H7
	Inner shaft diameter with tolerance	$\varnothing 7$ h6
	Outer shaft diameter with deviation	$\varnothing 0$ -0.01/-0.03
	T marking (undefined dimension)	Not specified
	Middle shaft section diameter	$\varnothing 8$ mm
	D marking (undefined dimension)	Not specified
	Right hole diameter with tolerance	$\varnothing 0$ mm h6
	Chamfer	C0.4 mm
	Bottom height dimension	13.4±0.2 mm (reference)
	Center height dimension	12.5 -0/-0.1
	Wave generator label	Wave Generator-A
Mechanical View 3	Mounting hole pattern	20 holes, $\varnothing 5$ mm
	Hole depth	6.5mm depth
	Dimension label W	Dimension W
	Outer diameter	$\varnothing 4$ mm
	Label U	Label U
	Angular spacing	18°
	Threaded holes	2× M4 threaded holes
	Reference circle diameter	$\varnothing 2$ mm
Mechanical View 4	View D	View D
	Center hole diameter	$\varnothing 6$
	M2.5 tapped hole specification	2×M2.5 tapped holes (no $\varnothing 1$ through hole)
	Surface roughness requirement	Ra 5
	Locating hole diameter	$\varnothing 2$

Housing and Input Interface Dimensions

Housing Size: 17 Reduction Ratio: 50 Weight: 0.19 kg

WAVE GENERATOR	T (MM)	U	W
A8	9.4 +0.10	8 H7	3 JS9/P9
A11	12.8 +0.10	11 H7	4 JS9/P9

Note: Dimensions in mm unless otherwise specified. Refer to the dimensional drawing for feature locations and datum definitions.

Input Interface Design Guidance

- Confirm the selected series, frame size, ratio and product form before using dimensions or interface geometry.
- Design the input shaft, key, engagement and axial retention for the verified torque and assembly state.
- Reserve assembly, sealing, inspection and removal access around input, housing and output interfaces.

Mounting, Alignment and Fastener Control

- Keep mounting faces flat, clean and free of burrs, debris and coating buildup.
- Control concentricity, tilt and axial position of input and housing datums.
- Tighten fasteners in a staged diagonal sequence and verify free, even rotation during assembly.

Torque, Speed and Duty Boundaries

PARAMETER	VALUE	UNIT
Rated Torque	16	Nm
Allowable Average Torque	26	
Start/Stop Peak Torque	34	
Instantaneous Maximum Torque	70	
Maximum Input Speed	7300	r/min
Average Input Speed	3500	
Design Life	10000	h

- Calculate torque and speed from acceleration, constant-speed, deceleration, dwell and reversal portions of the complete cycle.
- Treat start/stop peak and instantaneous maximum torque as transient boundaries.
- Validate life against actual torque, speed, shock frequency, lubrication, temperature, alignment and external loading.

Torque, Speed and Life Boundaries

PARAMETER	VALUE	INTEGRATION REQUIREMENT
Rated Torque	16 Nm	Use as the selected continuous output rating under validated duty and thermal conditions.
Allowable Average Torque	26 Nm	Calculate the actual time-weighted output torque over the complete cycle.
Start/Stop Peak Torque	34 Nm	Transient start/stop boundary; include acceleration and deceleration events.
Instantaneous Maximum Torque	70 Nm	Short-duration shock boundary only; do not use as a normal operating point.
Maximum Input Speed	7300 r/min	Maximum input-speed boundary; also verify motor and thermal limits.
Average Input Speed	3500 r/min	Validate the time-weighted average input speed over the complete duty cycle.
Design Life	10000 h	Design reference only; actual life depends on torque, speed, shock, lubrication and installation.

Transmission Accuracy and Torsional Rigidity

PARAMETER	VALUE	UNIT
Backlash	20	arc sec

- Installed positioning depends on reducer behavior, datum control, structural stiffness, motor and encoder errors and thermal growth.
- Use stiffness regions and transition torques when evaluating compliance, resonance, control gain and reversal.

Lubrication, Sealing and Thermal Control

- Use the specified lubricant, fill method and quantity for the exact configuration; do not mix incompatible lubricants.
- Provide compatible sealing at input, output and housing interfaces without distorting the reducer.
- Validate lubricant distribution and temperature for orientation, speed, load cycle and enclosure.
- Prevent chips, fibers, residue and moisture from entering gear or bearing cavities.

Output Bearing and External Load Path

- Calculate radial, axial and moment loads including offset, acceleration, gravity, process force, impact and emergency stops.
- Do not infer permissible external load from reducer torque capacity or frame size.
- Avoid forcing, impact, misalignment or host distortion through the output support during installation and operation.

Integration Checklist

- 01 Confirm the selected series, frame size, ratio and product form for this SKU.
- 02 Verify available dimensions and interface geometry without substituting a nearby configuration.
- 03 Check mounting-face flatness, concentricity, tilt, reliefs, cleanliness and support stiffness.
- 04 Verify input shaft, key, engagement length and axial retention.
- 05 Use staged diagonal tightening and verify free, even rotation.
- 06 Calculate average, start/stop peak and shock torque over the complete cycle.
- 07 Validate average and maximum input speed, design life and thermal condition.
- 08 Evaluate backlash, angular accuracy, hysteresis and stiffness for the control system.
- 09 Confirm lubricant, fill quantity, orientation, sealing and contamination controls.
- 10 Validate output radial, axial and moment loads using applicable bearing data.

[View SKU Product Datasheet](#) [Request controlled 2D drawing](#) [Request controlled STEP review](#) [Request a Quote](#)

Engineering Use and Verification Notice

01. This Dimensional & Integration Guide applies only to EmbodyStack SKU ES-HG-S02-F17-R50 and supports preliminary dimensional evaluation and integration. It is not a manufacturing drawing, reducer selection approval, bearing-load approval, lubrication specification, machinery risk assessment, safety validation or integration planning document. Before design freeze, assembly or commissioning, verify all dimensions, datum geometry, fits, interfaces, retention, fasteners, torque and speed duty, shock cases, torsional behavior, external loads, lubrication, sealing, temperature, contamination and maintenance requirements against the current EmbodyStack engineering data for this exact SKU. Validate the complete reducer, motor, host structure, output load, motion cycle, guarding, fault cases and applicable regulatory requirements under intended operating conditions.