

ENGINEERING DOCUMENTATION

# High-Torque Hat Component Set

Dimensional & Integration Guide

| DOCUMENT               | REVISION / ISSUE       | STATUS                            |
|------------------------|------------------------|-----------------------------------|
| DIG-ES-HG-S04-F25-R100 | DRAFT-08 / 26 Aug 2026 | Engineering Integration Reference |

## Integration Overview

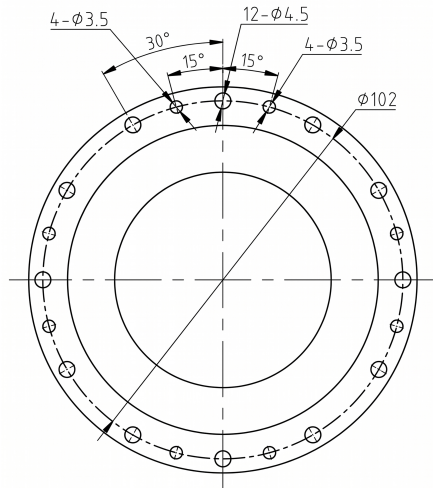
Hat-form harmonic gear component set requiring specified host housing, support-bearing and sealing integration for compact, coaxial, high-ratio rotary axes. This guide supports host-interface design, wave-generator input integration, mounting alignment, load-cycle validation, torsional behavior, lubrication, sealing and commissioning for ES-HG-S04-F25-R100.

## Key Integration Facts

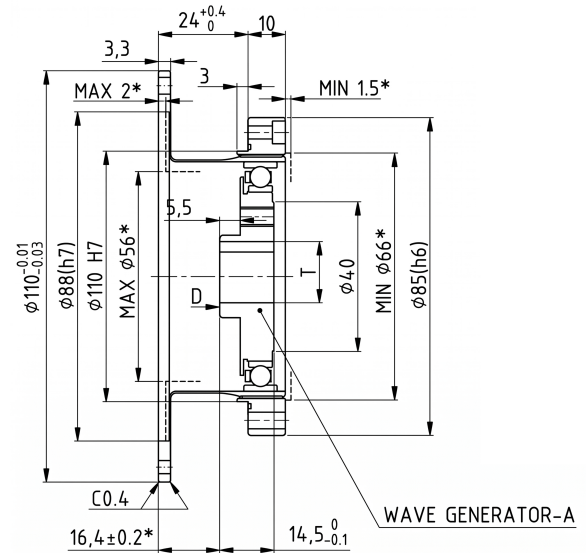
| INTEGRATION ITEM             | PUBLISHED VALUE |
|------------------------------|-----------------|
| Rated Torque                 | 87 Nm           |
| Instantaneous Maximum Torque | 369 Nm          |
| Start/Stop Peak Torque       | 204 Nm          |
| Backlash                     | ±20 arc sec     |
| Reduction Ratio              | 100             |
| Maximum Input Speed          | 5600 r/min      |
| Frame Size                   | 25              |
| Weight                       | 0.46 kg         |

## Product Structure & Views

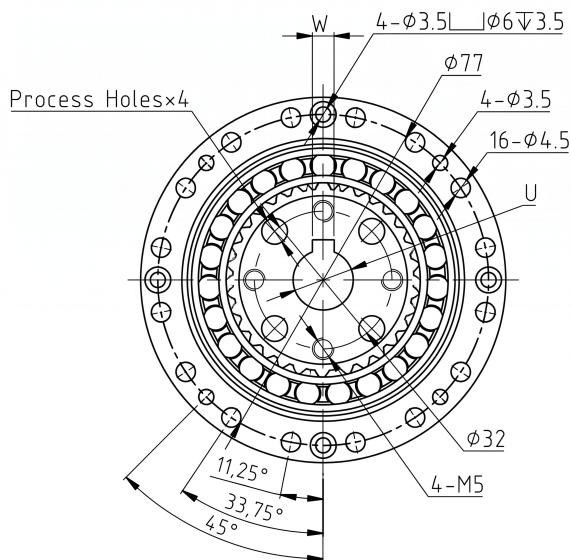
These views present the selected product structure, mounting interfaces and relevant integration geometry for this SKU.



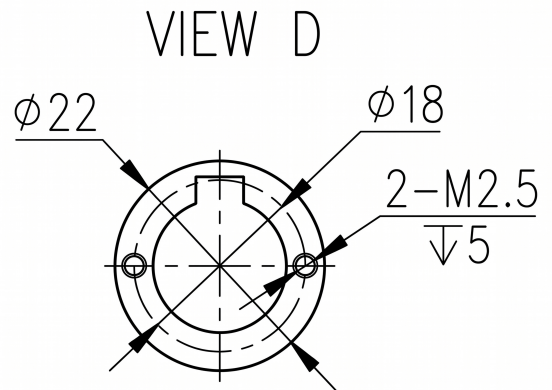
Mechanical View 1



Mechanical View 2



Mechanical View 3



Mechanical View 4

| VIEW              | FIELD                            | VALUE                                                   |
|-------------------|----------------------------------|---------------------------------------------------------|
| Mechanical View 1 | Diameter of 12 holes             | 12 holes, diameter 4.5                                  |
|                   | Diameter of left 4 holes         | 4 holes, diameter 3.5                                   |
|                   | Diameter of right 4 holes        | 4 holes, diameter 3.5                                   |
|                   | Hole angular spacing             | 30 degree angular spacing                               |
|                   | Left hole angular offset         | 15 degree angular offset                                |
|                   | Right hole angular offset        | 15 degree angular offset                                |
|                   | Bolt circle diameter             | Bolt circle diameter 102                                |
| Mechanical View 2 | Upper axial distance             | 24 +0.4/0                                               |
|                   | Adjacent upper axial distance    | 10                                                      |
|                   | Upper left local spacing         | 3.3                                                     |
|                   | Upper local thickness            | 3                                                       |
|                   | Minimum clearance                | Minimum 1.5                                             |
|                   | Maximum clearance                | Maximum 2                                               |
|                   | Middle local spacing             | 5.5                                                     |
|                   | Maximum outside diameter         | Maximum diameter 56                                     |
|                   | Minimum clearance diameter       | Minimum diameter 66                                     |
|                   | Shaft fit diameter               | Diameter 85 h6                                          |
|                   | Bore fit diameter                | Diameter 110 H7                                         |
|                   | Shaft fit diameter               | Diameter 88 h7                                          |
|                   | Shaft diameter                   | Diameter 40                                             |
|                   | Diameter tolerance               | Diameter 110 -0.01/-0.03                                |
|                   | Datum D                          | Datum D                                                 |
|                   | Chamfer                          | Chamfer C0.4                                            |
|                   | Component name                   | Wave generator-A                                        |
|                   | Bottom axial distance            | 14.5 0/-0.1                                             |
|                   | Left axial positioning dimension | 16.4±0.2*                                               |
|                   | Datum T                          | Datum T                                                 |
| Mechanical View 3 | W labeled width                  | W dimension value Not specified                         |
|                   | 4-hole counterbore/depth callout | 4 holes Ø3.5 with Ø6 counterbore or spotface, depth 3.5 |
|                   | Hole pitch circle diameter       | Ø77                                                     |
|                   | Process holes quantity           | Process holes quantity: 4                               |
|                   | 4 holes diameter                 | 4 holes Ø3.5                                            |
|                   | 16 holes diameter                | 16 holes Ø4.5                                           |
|                   | U labeled feature                | U value Not specified                                   |
|                   | Hole pitch circle diameter       | Ø32                                                     |
|                   | Angular spacing 11.25 degrees    | 11.25°                                                  |

| VIEW                          | FIELD                              | VALUE                               |
|-------------------------------|------------------------------------|-------------------------------------|
| 4 M5 threaded holes           | 4 M5 threaded holes                |                                     |
| Angular spacing 33.75 degrees | 33.75°                             |                                     |
| Angular spacing 45 degrees    | 45°                                |                                     |
| Mechanical View 4             | View designation                   | View D                              |
|                               | Diameter 22 circular feature       | Diameter 22 mm                      |
|                               | Diameter 18 circular feature       | Diameter 18 mm                      |
|                               | Two M2.5 threaded holes with depth | 2 × M2.5 threaded holes, depth 5 mm |

## Overall Dimensions and Input Interface

| PARAMETER                  | PUBLISHED VALUE       | UNIT |
|----------------------------|-----------------------|------|
| Frame Size                 | 25                    |      |
| Weight                     | 0.46                  | kg   |
| Wave Generator Dimension T | 12.8+0.10 / 16.3+0.10 | mm   |
| Wave Generator Bore U      | Ø1H7 / Ø4H7           |      |
| Wave Generator Keyway W    | 4JS9/P9 / 5JS9/P9     |      |

- Confirm the selected series, frame size and ratio before using dimensions or interface geometry. Do not substitute a nearby frame or product form.
- Design the input shaft, key, effective engagement and axial retention to transmit the verified torque without uncontrolled wave-generator axial movement.
- Reserve assembly, sealing, inspection and removal access around the input, housing and output interfaces.

## Mounting, Alignment and Fastener Control

- Keep mounting faces flat, clean and free of burrs, raised holes, debris and coating buildup. Confirm reliefs and chamfers prevent interference.
- Seat the fixed and flexible gear members in the host structure before inserting the wave generator. Do not force engagement in a misaligned condition.
- Control concentricity, tilt and axial position of the input and housing datums. Insert the wave generator smoothly without excessive force on its bearing.
- Tighten fasteners in a staged diagonal sequence using the applicable torque and locking specification. Verify free, even rotation during assembly.

## Torque, Speed and Duty Boundaries

| PARAMETER                    | PUBLISHED VALUE | UNIT  |
|------------------------------|-----------------|-------|
| Rated Torque                 | 87              | N·m   |
| Allowable Average Torque     | 140             | N·m   |
| Start/Stop Peak Torque       | 204             | N·m   |
| Instantaneous Maximum Torque | 369             | N·m   |
| Maximum Input Speed          | 5600            | r/min |
| Average Input Speed          | 3500            | r/min |
| Design Life                  | 15000           | h     |

- Calculate average torque and average input speed from the complete acceleration, constant-speed, deceleration, dwell and reversal cycle.
- Treat start/stop peak and instantaneous maximum torque as transient boundaries. Do not use either value as a continuous operating point.
- Validate design life against actual torque, speed, shock frequency, lubrication, temperature, alignment and external loading.

### Published Torque, Speed and Life Boundaries

| PARAMETER                    | PUBLISHED VALUE | INTEGRATION REQUIREMENT                                                                           |
|------------------------------|-----------------|---------------------------------------------------------------------------------------------------|
| Rated Torque                 | 87 N·m          | Use as the selected continuous output rating under validated duty and thermal conditions.         |
| Allowable Average Torque     | 140 N·m         | Calculate the actual time-weighted output torque over the complete cycle.                         |
| Start/Stop Peak Torque       | 204 N·m         | Transient start/stop boundary; include acceleration and deceleration events.                      |
| Instantaneous Maximum Torque | 369 N·m         | Short-duration shock boundary only; do not use as a normal operating point.                       |
| Maximum Input Speed          | 5600 r/min      | Maximum input-speed boundary; also verify motor and thermal limits.                               |
| Average Input Speed          | 3500 r/min      | Validate the time-weighted average input speed over the complete duty cycle.                      |
| Design Life                  | 15000 h         | Design reference only; actual life depends on torque, speed, shock, lubrication and installation. |

## Transmission Accuracy and Torsional Rigidity

| PARAMETER | PUBLISHED VALUE | UNIT    |
|-----------|-----------------|---------|
| Backlash  | ±0              | arc sec |

- Installed positioning performance depends on reducer behavior, datum control, fastener distortion, motor and encoder errors, host stiffness and thermal growth.
- Use the published stiffness regions and transition torques when evaluating compliance, resonance, control gain and direction reversal.

### Published Accuracy and Torsional Rigidity Boundaries

| PARAMETER | PUBLISHED VALUE | INTEGRATION REQUIREMENT                                                     |
|-----------|-----------------|-----------------------------------------------------------------------------|
| Backlash  | ±0 arc sec      | Validate at the selected measurement condition and installed preload state. |

## Lubrication, Sealing and Thermal Control

- Use only the current lubricant, fill method and quantity for the exact configuration. Do not mix incompatible lubricants.
- Provide compatible static and dynamic sealing at the input, output and housing interfaces without distorting the reducer or restricting motion.
- Validate lubricant distribution and temperature for the installed orientation, speed, load cycle and enclosure.
- Prevent chips, fibers, cleaning residue, moisture and other contamination from entering the gear or bearing cavities during assembly and service.

## Output Bearing and External Load Path

- Calculate radial, axial and moment loads at the output, including offset, acceleration, gravity, process force, impact and emergency-stop cases.
- Do not infer permissible external load from reducer torque capacity or frame size. Use applicable output-bearing data and safety criteria.
- Avoid forcing, impact, misalignment or host distortion through the output support bearing during installation and operation.

## Integration Checklist

- |    |                                                                                                          |
|----|----------------------------------------------------------------------------------------------------------|
| 01 | Confirm the drawing, published parameters and applicable assembly data identify this SKU.                |
| 02 | Verify series, frame size, ratio, product form and input-interface dimensions.                           |
| 03 | Check mounting-face flatness, concentricity, tilt, chamfers, reliefs, cleanliness and support stiffness. |
| 04 | Verify input shaft, key, engagement length and axial wave-generator retention.                           |
| 05 | Assemble the fixed and flexible gear members before inserting the wave generator.                        |
| 06 | Use staged diagonal tightening and verify free, even rotation throughout assembly.                       |
| 07 | Calculate average, start/stop peak and shock torque over the complete operating cycle.                   |
| 08 | Validate average and maximum input speed, design life and installed thermal condition.                   |
| 09 | Evaluate backlash, angular accuracy, hysteresis and stiffness regions for the control system.            |
| 10 | Confirm exact lubricant, fill quantity, orientation, sealing and contamination controls.                 |
| 11 | Validate output radial, axial and moment loads using applicable bearing data.                            |
| 12 | Include specified 2D, STEP, assembly, lubrication and bearing-load data in integration planning.         |

[View SKU Product Datasheet](#)[Request controlled 2D drawing](#)[Request controlled STEP review](#)[Request a Quote](#)

## Engineering Use and Verification Notice

01. This Dimensional & Integration Guide applies only to EmbodyStack SKU ES-HG-S04-F25-R100 and is intended for dimensional evaluation and preliminary integration. It is not a applicable manufacturing drawing, reducer selection approval, bearing-load approval, lubrication specification, machinery risk assessment, safety validation or integration planning document and must not be used as the sole basis for machining, shaft or key manufacture, fastener selection, sealing, lubricant filling or final integration. Before design freeze, assembly or commissioning, verify all dimensions, datum geometry, fits, shaft and key interfaces, wave-generator retention, fastener engagement and tightening controls, torque and speed duty, shock cases, torsional accuracy and rigidity, external output loads, lubrication, sealing, temperature, contamination and maintenance requirements against the applicable EmbodyStack engineering data for this exact SKU. Where this guide and applicable product documentation differ, the applicable product documentation governs. Validate the complete reducer, motor, host structure, output load, motion cycle, guarding, fault cases and applicable regulatory requirements under intended operating conditions.