ENGINEERING DOCUMENTATION

High-Torque Hat Unit Type I

Dimensional & Integration Guide

DOCUMENT	REVISION / ISSUE	STATUS
DIG-ES-HG-S07-F17-R80	DRAFT-08 / 28 Aug 2026	Engineering Integration Reference

Integration Overview

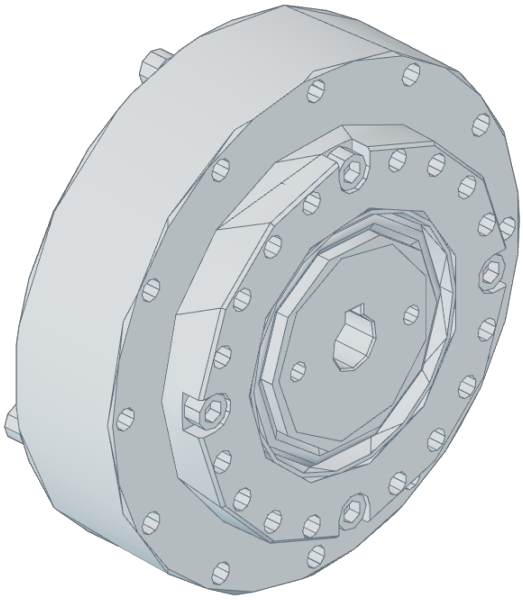
High-Torque Hat Unit Type I for compact, coaxial, high-ratio rotary-axis integration. This guide supports interface planning, mounting alignment, duty validation, torsional behavior, lubrication, sealing and commissioning for ES-HG-S07-F17-R80.

Key Integration Facts

INTEGRATION ITEM	VALUE
Rated Torque	29 N·m
Instantaneous Maximum Torque	113 N·m
Start/Stop Peak Torque	56 N·m
Reduction Ratio	80
Maximum Input Speed	7300 r/min
Frame Size	17
Weight	0.54 kg

3D Orientation Reference

This axonometric reference provides a quick orientation check for the reducer body, input interface and mounting relationship of ES-HG-S07-F17-R80.



Axonometric Orientation View

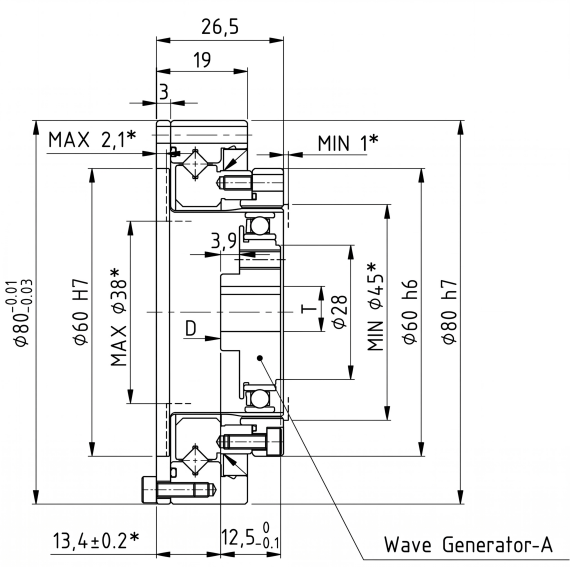
Orientation reference only. Use the exact-SKU parameter table and mechanical drawing for dimensions, hole geometry, fits and machining decisions.

Exact-SKU Interface Cross-Reference

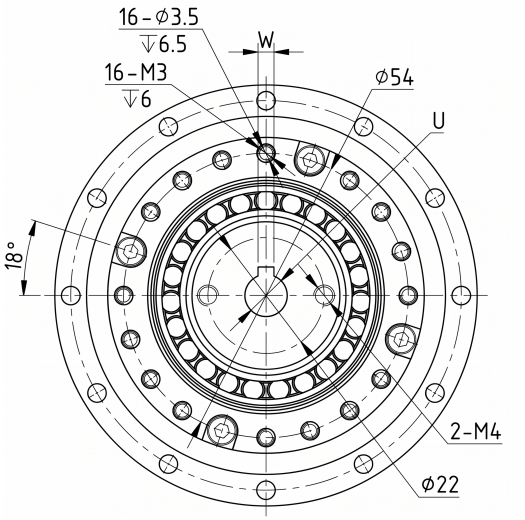
INTEGRATION TOPIC	EXACT-SKU REFERENCE
Reducer envelope and configuration	Frame Size: 17; Reduction Ratio: 80; Weight: 0.54 kg. Confirm hole geometry, datum features and fits in the exact-SKU mechanical drawing.
Torque and speed boundaries	Rated Torque: 29 N·m; Start/Stop Peak Torque: 56 N·m; Instantaneous Maximum Torque: 113 N·m; Maximum Input Speed: 7300 r/min. Confirm hole geometry, datum features and fits in the exact-SKU mechanical drawing.
Input and mounting interfaces	Wave Generator options A8 and A11 are defined in the housing and input interface matrix. Confirm hole geometry, datum features and fits in the exact-SKU mechanical drawing.

Product Structure & Views

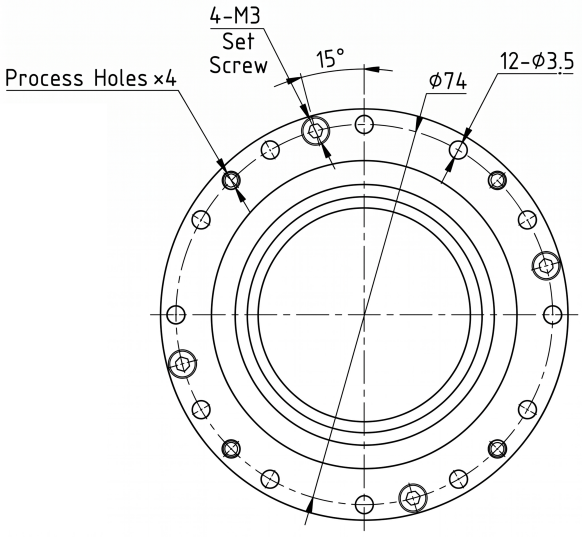
These views present the selected product structure, mounting interfaces and relevant integration geometry for this SKU.



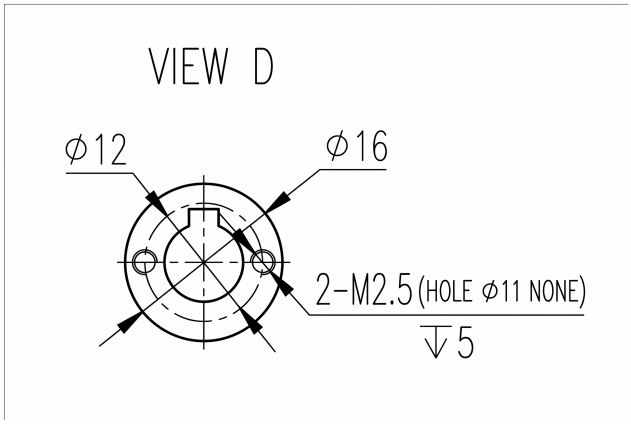
Mechanical View 1



Mechanical View 2



Mechanical View 3



Mechanical View 4

VIEW	FIELD	VALUE
Mechanical View 1	Top overall width	26.5
	Top inner width	19
	Local step width	3
	Maximum clearance or step dimension	MAX 2.1*
	Minimum clearance or step dimension	MIN 1*
	Local horizontal offset	3.9
	Maximum outside diameter limit	MAX Ø38*
	Minimum outside diameter limit	MIN Ø45*
	Diameter 28	Ø28
	Diameter 60 H7 fit	Ø60 H7
	Diameter 80 h7 fit	Ø80 h7
	Diameter 80 with lower deviation	Ø80 +0/-0.03
	Datum D	Datum D
	Bottom local length	12.5 +0/-0.1
	Bottom local length	13.4 ±0.2*
	Component label	Wave Generator-A
	Diameter 60 h6 fit	Ø60 h6
	Datum T	Datum T
Mechanical View 2	16 hole diameter	16 holes, diameter 3.5 mm
	Additional depth or counterbore-related value for 16 diameter 3.5 holes	Depth/counterbore-style value 6.5 mm associated with 16- ⌀3.5 callout
	16 M3 threaded holes	16 threaded holes, M3
	Depth for 16 M3 threaded holes	Depth 6 mm associated with 16-M3 holes
	Diameter 54 circular feature	Diameter 54 mm
	Feature label U	Feature identifier U
	Angular dimension	18 degrees
	2 M4 mounting threaded holes	2 threaded holes, M4
	Hole diameter 22	Diameter 22 mm
	Datum identifier	W
Mechanical View 3	Set screw thread callout	4× M3 set screws
	Angular spacing	15 degrees
	Mounting hole quantity and diameter	12 holes, diameter 3.5
	Process hole quantity	4 process holes; diameter not specified in this crop
	Bolt circle diameter	Diameter 74 bolt circle
Mechanical View 4	View label	View D
	Right hole diameter	Diameter 16
	Left hole diameter	Diameter 12
	Threaded hole quantity and size	2 × M2.5 threaded holes; ⌀1 hole none
	Hole depth or depth callout	Depth-style callout 5

Housing and Input Interface Dimensions

Housing Size: 17 **Reduction Ratio:** 80 **Weight:** 0.54 kg

WAVE GENERATOR	T (MM)	U	W
A8	9.4 +0.10	8 H7	3 JS9/P9
A11	12.8 +0.10	11 H7	4 JS9/P9

Note: Dimensions in mm unless otherwise specified. Refer to the dimensional drawing for feature locations and datum definitions.

Input Interface Design Guidance

- Confirm the selected series, frame size, ratio and product form before using dimensions or interface geometry.
- Design the input shaft, key, engagement and axial retention for the verified torque and assembly state.
- Reserve assembly, sealing, inspection and removal access around input, housing and output interfaces.

Mounting, Alignment and Fastener Control

- Keep mounting faces flat, clean and free of burrs, debris and coating buildup.
- Control concentricity, tilt and axial position of input and housing datums.
- Tighten fasteners in a staged diagonal sequence and verify free, even rotation during assembly.

Torque, Speed and Duty Boundaries

PARAMETER	VALUE	UNIT
Rated Torque	29	N·m
Allowable Average Torque	35	
Start/Stop Peak Torque	56	
Instantaneous Maximum Torque	113	
Starting Torque	4.4	
Maximum Input Speed	7300	r/min
Average Input Speed	3500	
Design Life	15000	h

- Calculate torque and speed from acceleration, constant-speed, deceleration, dwell and reversal portions of the complete cycle.
- Treat start/stop peak and instantaneous maximum torque as transient boundaries.
- Validate life against actual torque, speed, shock frequency, lubrication, temperature, alignment and external loading.

Torque, Speed and Life Boundaries

PARAMETER	VALUE	INTEGRATION REQUIREMENT
Rated Torque	29 N·m	Use as the selected continuous output rating under validated duty and thermal conditions.
Allowable Average Torque	35 N·m	Calculate the actual time-weighted output torque over the complete cycle.
Start/Stop Peak Torque	56 N·m	Transient start/stop boundary; include acceleration and deceleration events.
Instantaneous Maximum Torque	113 N·m	Short-duration shock boundary only; do not use as a normal operating point.
Maximum Input Speed	7300 r/min	Maximum input-speed boundary; also verify motor and thermal limits.
Average Input Speed	3500 r/min	Validate the time-weighted average input speed over the complete duty cycle.
Design Life	15000 h	Design reference only; actual life depends on torque, speed, shock, lubrication and installation.

Transmission Accuracy and Torsional Rigidity

PARAMETER	VALUE	UNIT
Angle Transmission Accuracy	1.5	arcmin
Hysteresis Loss	1	
Torsional Rigidity K1	1	×10⁴N·m/rad
Torsional Rigidity K2	1.4	
Torsional Rigidity K3	1.6	
Torsional Rigidity T1	3.9	N·m
Torsional Rigidity T2	12	

- Installed positioning depends on reducer behavior, datum control, structural stiffness, motor and encoder errors and thermal growth.
- Use stiffness regions and transition torques when evaluating compliance, resonance, control gain and reversal.

Lubrication, Sealing and Thermal Control

- Use the specified lubricant, fill method and quantity for the exact configuration; do not mix incompatible lubricants.
- Provide compatible sealing at input, output and housing interfaces without distorting the reducer.
- Validate lubricant distribution and temperature for orientation, speed, load cycle and enclosure.
- Prevent chips, fibers, residue and moisture from entering gear or bearing cavities.

Output Bearing and External Load Path

- Calculate radial, axial and moment loads including offset, acceleration, gravity, process force, impact and emergency stops.
- Do not infer permissible external load from reducer torque capacity or frame size.
- Avoid forcing, impact, misalignment or host distortion through the output support during installation and operation.

Integration Checklist

01	Confirm the selected series, frame size, ratio and product form for this SKU.
02	Verify available dimensions and interface geometry without substituting a nearby configuration.
03	Check mounting-face flatness, concentricity, tilt, reliefs, cleanliness and support stiffness.
04	Verify input shaft, key, engagement length and axial retention.
05	Use staged diagonal tightening and verify free, even rotation.
06	Calculate average, start/stop peak and shock torque over the complete cycle.
07	Validate average and maximum input speed, design life and thermal condition.
08	Evaluate backlash, angular accuracy, hysteresis and stiffness for the control system.
09	Confirm lubricant, fill quantity, orientation, sealing and contamination controls.
10	Validate output radial, axial and moment loads using applicable bearing data.

View SKU Product Datasheet **Request controlled 2D drawing** **Request controlled STEP review** **Request a Quote**

Engineering Use and Verification Notice

01. This Dimensional & Integration Guide applies only to EmbodyStack SKU ES-HG-S07-F17-R80 and supports preliminary dimensional evaluation and integration. It is not a manufacturing drawing, reducer selection approval, bearing-load approval, lubrication specification, machinery risk assessment, safety validation or integration planning document. Before design freeze, assembly or commissioning, verify all dimensions, datum geometry, fits, interfaces, retention, fasteners, torque and speed duty, shock cases, torsional behavior, external loads, lubrication, sealing, temperature, contamination and maintenance requirements against the current EmbodyStack engineering data for this exact SKU. Validate the complete reducer, motor, host structure, output load, motion cycle, guarding, fault cases and applicable regulatory requirements under intended operating conditions.