ENGINEERING DOCUMENTATION

High-Torque Hat Unit Type I

Dimensional & Integration Guide

DOCUMENT	REVISION / ISSUE	STATUS
DIG-ES-HG-S07-F25-R80	DRAFT-08 / 26 Aug 2026	Engineering Integration Reference

Integration Overview

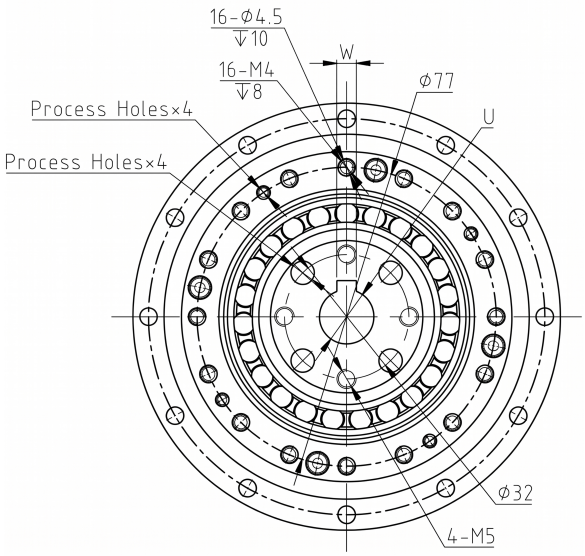
Hat-form harmonic gear gear unit with integrated product interfaces for the selected configuration for compact, coaxial, high-ratio rotary axes. This guide supports host-interface design, wave-generator input integration, mounting alignment, load-cycle validation, torsional behavior, lubrication, sealing and commissioning for ES-HG-S07-F25-R80.

Key Integration Facts

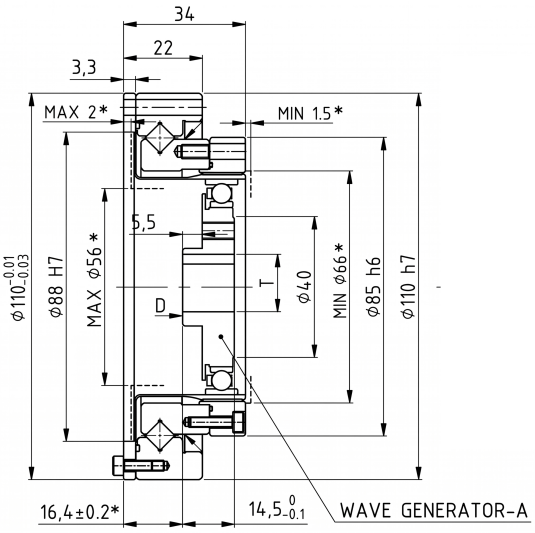
INTEGRATION ITEM	PUBLISHED VALUE
Rated Torque	82 N·m
Instantaneous Maximum Torque	332 N·m
Start/Stop Peak Torque	178 N·m
Reduction Ratio	80
Maximum Input Speed	5600 r/min
Frame Size	25
Weight	1.22 kg

Product Structure & Views

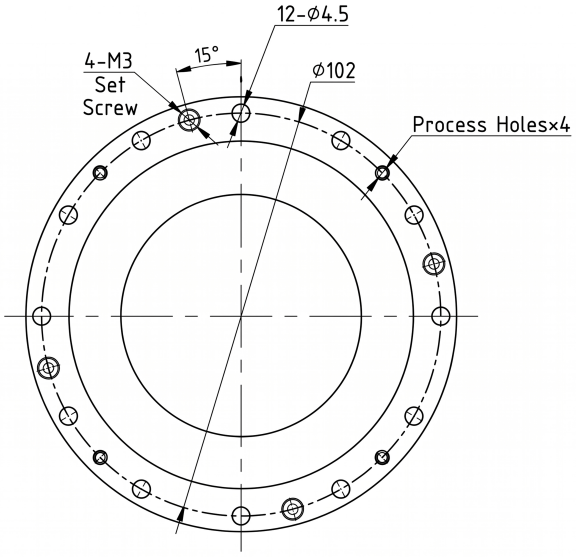
These views present the selected product structure, mounting interfaces and relevant integration geometry for this SKU.



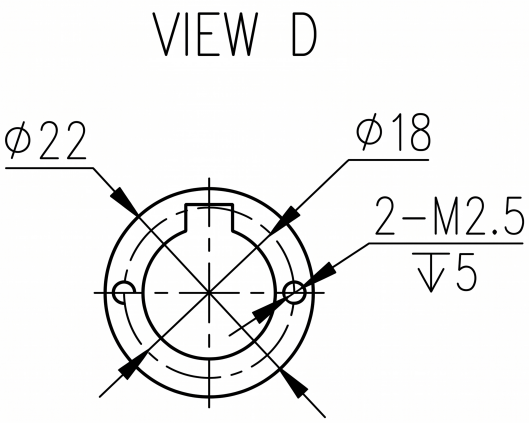
Mechanical View 1



Mechanical View 2



Mechanical View 3



Mechanical View 4

VIEW	FIELD	VALUE
Mechanical View 1	Mounting hole diameter	16 holes, ϕ4.5 mm
	Mounting hole depth	10 mm depth
	Mounting thread specification	16 holes, M4 thread
	Thread depth	8 mm depth
	Process holes (first group)	4 process holes
	Process holes (second group)	4 process holes
	Dimension reference label W	Reference dimension W
	Outer diameter	ϕ77 mm
	Dimension reference label U	Reference dimension U
	Center hole diameter	ϕ32 mm
	Center mounting thread	4 holes, M5 thread
Mechanical View 2	Upper overall length	34 mm
	Upper local length	22 mm
	Left small step distance	3.3 mm
	Maximum clearance or step dimension	Maximum 2 mm, starred note applies
	Minimum clearance or step dimension	Minimum 1.5 mm, starred note applies
	Local axial distance	5.5 mm
	Maximum outside diameter	Maximum diameter 56 mm, starred note applies
	Mounting diameter with negative tolerance	Diameter 110 mm, upper deviation -0.01 mm, lower deviation -0.03 mm
	Bore or fit diameter	Diameter 88 mm, H7 tolerance class
	D reference label	D
	T reference label	T
	Shaft diameter	Diameter 40 mm
	Minimum diameter	Minimum diameter 66 mm, starred note applies
	Fit shaft diameter	Diameter 85 mm, h6 tolerance class
	Fit outside diameter	Diameter 110 mm, h7 tolerance class
	Bottom axial dimension with unilateral tolerance	14.5 mm, upper deviation 0 mm, lower deviation -0.1 mm
	Component label	Wave Generator-A
Mechanical View 3	Mounting hole quantity and diameter	12 holes, diameter 4.5 mm
	Bolt circle diameter	Pitch circle diameter 102 mm
	Angular spacing or angular position	15 degrees
	Set screw threaded holes	4 M3 set screw threaded holes
	Process hole quantity	4 process holes; hole diameter not specified in this crop
Mechanical View 4	View D designation	View D
	Diameter 22 callout	Diameter 22 mm

VIEW	FIELD	VALUE
Diameter 18 callout	Diameter 18 mm	
Threaded hole quantity and size	2 × M2.5 threaded holes	
Threaded hole depth	Depth 5 mm	

Overall Dimensions and Input Interface

PARAMETER	PUBLISHED VALUE	UNIT
Frame Size	25	
Weight	1.22	kg
Wave Generator Dimension T	16.3+0.10 / 12.8+0.10	mm
Wave Generator Bore U	ϕ11H7 / ϕ14H7	
Wave Generator Keyway W	5JS9/P9 / 4JS9/P9	

- Confirm the selected series, frame size and ratio before using dimensions or interface geometry. Do not substitute a nearby frame or product form.
- Design the input shaft, key, effective engagement and axial retention to transmit the verified torque without uncontrolled wave-generator axial movement.
- Reserve assembly, sealing, inspection and removal access around the input, housing and output interfaces.

Mounting, Alignment and Fastener Control

- Keep mounting faces flat, clean and free of burrs, raised holes, debris and coating buildup. Confirm reliefs and chamfers prevent interference.
- Seat the fixed and flexible gear members in the host structure before inserting the wave generator. Do not force engagement in a misaligned condition.
- Control concentricity, tilt and axial position of the input and housing datums. Insert the wave generator smoothly without excessive force on its bearing.
- Tighten fasteners in a staged diagonal sequence using the applicable torque and locking specification. Verify free, even rotation during assembly.

Torque, Speed and Duty Boundaries

PARAMETER	PUBLISHED VALUE	UNIT
Rated Torque	82	N·m
Allowable Average Torque	113	N·m
Start/Stop Peak Torque	178	N·m
Instantaneous Maximum Torque	332	N·m
Starting Torque	10	N·m
Maximum Input Speed	5600	r/min
Average Input Speed	3500	r/min
Design Life	15000	h

- Calculate average torque and average input speed from the complete acceleration, constant-speed, deceleration, dwell and reversal cycle.
- Treat start/stop peak and instantaneous maximum torque as transient boundaries. Do not use either value as a continuous operating point.
- Validate design life against actual torque, speed, shock frequency, lubrication, temperature, alignment and external loading.

Published Torque, Speed and Life Boundaries

PARAMETER	PUBLISHED VALUE	INTEGRATION REQUIREMENT
Rated Torque	82 N·m	Use as the selected continuous output rating under validated duty and thermal conditions.
Allowable Average Torque	113 N·m	Calculate the actual time-weighted output torque over the complete cycle.
Start/Stop Peak Torque	178 N·m	Transient start/stop boundary; include acceleration and deceleration events.
Instantaneous Maximum Torque	332 N·m	Short-duration shock boundary only; do not use as a normal operating point.
Maximum Input Speed	5600 r/min	Maximum input-speed boundary; also verify motor and thermal limits.
Average Input Speed	3500 r/min	Validate the time-weighted average input speed over the complete duty cycle.
Design Life	15000 h	Design reference only; actual life depends on torque, speed, shock, lubrication and installation.

Transmission Accuracy and Torsional Rigidity

PARAMETER	PUBLISHED VALUE	UNIT
Angle Transmission Accuracy	1	arcmin
Hysteresis Loss	1	arcmin
Torsional Rigidity K1	3.1	×10⁴N·m/rad
Torsional Rigidity K2	5	×10⁴N·m/rad
Torsional Rigidity K3	5.7	×10⁴N·m/rad
Torsional Rigidity T1	14	N·m
Torsional Rigidity T2	48	N·m

- Installed positioning performance depends on reducer behavior, datum control, fastener distortion, motor and encoder errors, host stiffness and thermal growth.
- Use the published stiffness regions and transition torques when evaluating compliance, resonance, control gain and direction reversal.

Published Accuracy and Torsional Rigidity Boundaries

PARAMETER	PUBLISHED VALUE	INTEGRATION REQUIREMENT
Angle Transmission Accuracy	1 arcmin	Installed system accuracy also depends on datum, encoder, motor and structural errors.
Hysteresis Loss	1 arcmin	Include in direction-reversal and closed-loop positioning evaluation.
Torsional Rigidity K1	3.1 ×10⁴N·m/rad	Applies to the published low-torque stiffness region.
Torsional Rigidity K2	5 ×10⁴N·m/rad	Applies to the published intermediate stiffness region.
Torsional Rigidity K3	5.7 ×10⁴N·m/rad	Applies to the published upper stiffness region.
Torsional Rigidity T1	14 N·m	Published transition torque for stiffness-region interpretation.
Torsional Rigidity T2	48 N·m	Published transition torque for stiffness-region interpretation.

Lubrication, Sealing and Thermal Control

- Use only the current lubricant, fill method and quantity for the exact configuration. Do not mix incompatible lubricants.
- Provide compatible static and dynamic sealing at the input, output and housing interfaces without distorting the reducer or restricting motion.
- Validate lubricant distribution and temperature for the installed orientation, speed, load cycle and enclosure.
- Prevent chips, fibers, cleaning residue, moisture and other contamination from entering the gear or bearing cavities during assembly and service.

Output Bearing and External Load Path

- Calculate radial, axial and moment loads at the output, including offset, acceleration, gravity, process force, impact and emergency-stop cases.
- Do not infer permissible external load from reducer torque capacity or frame size. Use applicable output-bearing data and safety criteria.
- Avoid forcing, impact, misalignment or host distortion through the output support bearing during installation and operation.

Integration Checklist

01	Confirm the drawing, published parameters and applicable assembly data identify this SKU.
02	Verify series, frame size, ratio, product form and input-interface dimensions.
03	Check mounting-face flatness, concentricity, tilt, chamfers, reliefs, cleanliness and support stiffness.
04	Verify input shaft, key, engagement length and axial wave-generator retention.
05	Assemble the fixed and flexible gear members before inserting the wave generator.
06	Use staged diagonal tightening and verify free, even rotation throughout assembly.
07	Calculate average, start/stop peak and shock torque over the complete operating cycle.
08	Validate average and maximum input speed, design life and installed thermal condition.
09	Evaluate backlash, angular accuracy, hysteresis and stiffness regions for the control system.
10	Confirm exact lubricant, fill quantity, orientation, sealing and contamination controls.
11	Validate output radial, axial and moment loads using applicable bearing data.
12	Include specified 2D, STEP, assembly, lubrication and bearing-load data in integration planning.

View SKU Product Datasheet **Request controlled 2D drawing** **Request controlled STEP review** **Request a Quote**

Engineering Use and Verification Notice

01. This Dimensional & Integration Guide applies only to EmbodyStack SKU ES-HG-S07-F25-R80 and is intended for dimensional evaluation and preliminary integration. It is not a applicable manufacturing drawing, reducer selection approval, bearing-load approval, lubrication specification, machinery risk assessment, safety validation or integration planning document and must not be used as the sole basis for machining, shaft or key manufacture, fastener selection, sealing, lubricant filling or final integration. Before design freeze, assembly or commissioning, verify all dimensions, datum geometry, fits, shaft and key interfaces, wave-generator retention, fastener engagement and tightening controls, torque and speed duty, shock cases, torsional accuracy and rigidity, external output loads, lubrication, sealing, temperature, contamination and maintenance requirements against the applicable EmbodyStack engineering data for this exact SKU. Where this guide and applicable product documentation differ, the applicable product documentation governs. Validate the complete reducer, motor, host structure, output load, motion cycle, guarding, fault cases and applicable regulatory requirements under intended operating conditions.