

ENGINEERING DOCUMENTATION

High-Torque Hat Unit Type I

Dimensional & Integration Guide

DOCUMENT	REVISION / ISSUE	STATUS
DIG-ES-HG-S07-F45-R100	DRAFT-08 / 26 Aug 2026	Engineering Integration Reference

Integration Overview

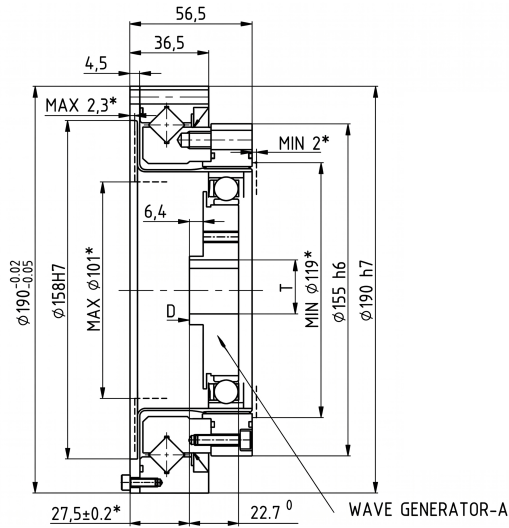
Hat-form harmonic gear gear unit with integrated product interfaces for the selected configuration for compact, coaxial, high-ratio rotary axes. This guide supports host-interface design, wave-generator input integration, mounting alignment, load-cycle validation, torsional behavior, lubrication, sealing and commissioning for ES-HG-S07-F45-R100.

Key Integration Facts

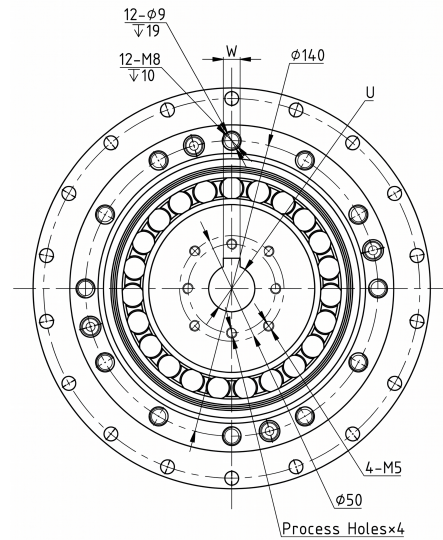
INTEGRATION ITEM	PUBLISHED VALUE
Rated Torque	459 Nm
Instantaneous Maximum Torque	2041 Nm
Start/Stop Peak Torque	982 Nm
Reduction Ratio	100
Maximum Input Speed	3800 r/min
Frame Size	45
Weight	6.5 kg

Product Structure & Views

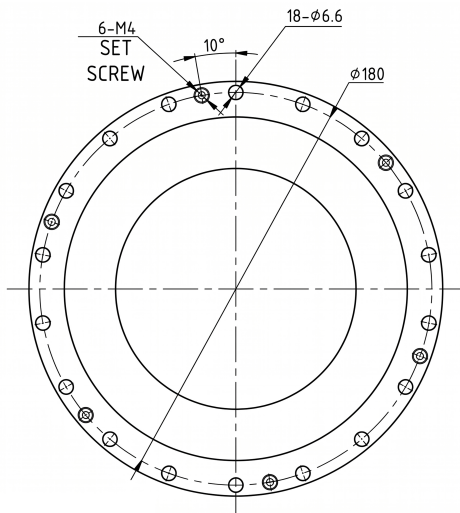
These views present the selected product structure, mounting interfaces and relevant integration geometry for this SKU.



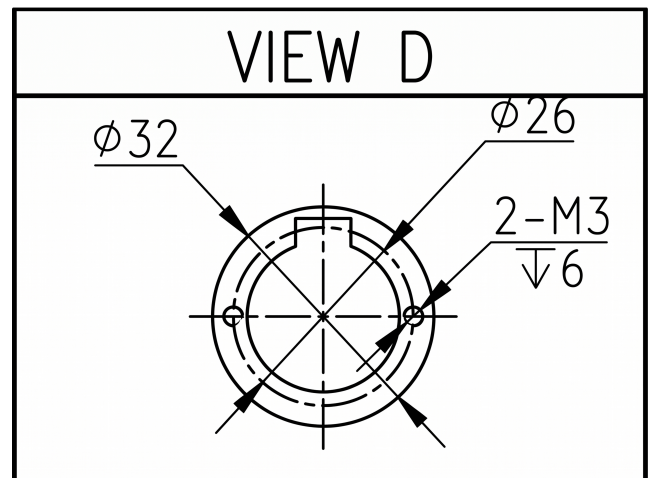
Mechanical View 1



Mechanical View 2



Mechanical View 3



Mechanical View 4

VIEW	FIELD	VALUE
Mechanical View 1	Top overall width	56.5
	Top inner width	36.5
	Upper left step offset	4.5
	Maximum clearance or protrusion	MAX 2.3
	Minimum clearance or protrusion	MIN 2
	Local transverse distance	6.4
	Left diameter with deviations	Diameter 190, upper deviation -0.02, lower deviation -0.05
	Fit diameter	Diameter 158 H7
	Maximum diameter	MAX diameter 101
	Minimum diameter	MIN diameter 119
	Fit diameter	Diameter 155 h6
	Fit diameter	Diameter 190 h7
	Datum or local identifier D	D
	Datum or local identifier T	T
	Bottom mounting offset	27.5 ±0.2
	Bottom local distance with upper deviation	22.7, upper deviation 0, lower deviation Not specified
	Component label	Wave Generator-A
Mechanical View 2	12 through holes diameter and counterbore depth	12 holes, diameter 9, depth 19
	12 M8 threaded holes and depth	12 M8 threaded holes, depth 10
	Width designation W	W, value not specified in this crop
	Diameter 140	Diameter 140
	Position designation U	U, value not specified in this crop
	M5 Tapped Holes	4-M5
	Hole Pitch Circle Diameter	Ø50
	Process Holes	Process Holes ×4
Mechanical View 3	Through hole quantity and diameter	18 holes, diameter 6.6 mm
	Set screw quantity and thread size	6 M4 set screws
	Angular spacing	10 degrees
	Bolt circle diameter	Pitch circle diameter 180 mm
Mechanical View 4	View designation	View D
	Outer diameter	Diameter 32 mm
	Hole pitch circle diameter	Diameter 26 mm
	Threaded hole specification	2 × M3 threaded holes
	Depth-style value for M3 threaded holes	D/depth-style value 6 mm associated with 2-M3

Overall Dimensions and Input Interface

PARAMETER	PUBLISHED VALUE	UNIT
Frame Size	45	
Weight	6.5	kg
Wave Generator Dimension T	21.8+0.10 / 24.8+0.10 / 25.3+0.10	mm
Wave Generator Bore U	$\varnothing 2H7 / \varnothing 9H7$	
Wave Generator Keyway W	8JS9/P9 / 6JS9/P9	

- Confirm the selected series, frame size and ratio before using dimensions or interface geometry. Do not substitute a nearby frame or product form.
- Design the input shaft, key, effective engagement and axial retention to transmit the verified torque without uncontrolled wave-generator axial movement.
- Reserve assembly, sealing, inspection and removal access around the input, housing and output interfaces.

Mounting, Alignment and Fastener Control

- Keep mounting faces flat, clean and free of burrs, raised holes, debris and coating buildup. Confirm reliefs and chamfers prevent interference.
- Seat the fixed and flexible gear members in the host structure before inserting the wave generator. Do not force engagement in a misaligned condition.
- Control concentricity, tilt and axial position of the input and housing datums. Insert the wave generator smoothly without excessive force on its bearing.
- Tighten fasteners in a staged diagonal sequence using the applicable torque and locking specification. Verify free, even rotation during assembly.

Torque, Speed and Duty Boundaries

PARAMETER	PUBLISHED VALUE	UNIT
Rated Torque	459	N·m
Allowable Average Torque	650	N·m
Start/Stop Peak Torque	982	N·m
Instantaneous Maximum Torque	2041	N·m
Starting Torque	47	N·m
Maximum Input Speed	3800	r/min
Average Input Speed	3000	r/min
Design Life	15000	h

- Calculate average torque and average input speed from the complete acceleration, constant-speed, deceleration, dwell and reversal cycle.
- Treat start/stop peak and instantaneous maximum torque as transient boundaries. Do not use either value as a continuous operating point.
- Validate design life against actual torque, speed, shock frequency, lubrication, temperature, alignment and external loading.

Published Torque, Speed and Life Boundaries

PARAMETER	PUBLISHED VALUE	INTEGRATION REQUIREMENT
Rated Torque	459 N·m	Use as the selected continuous output rating under validated duty and thermal conditions.
Allowable Average Torque	650 N·m	Calculate the actual time-weighted output torque over the complete cycle.
Start/Stop Peak Torque	982 N·m	Transient start/stop boundary; include acceleration and deceleration events.
Instantaneous Maximum Torque	2041 N·m	Short-duration shock boundary only; do not use as a normal operating point.
Maximum Input Speed	3800 r/min	Maximum input-speed boundary; also verify motor and thermal limits.
Average Input Speed	3000 r/min	Validate the time-weighted average input speed over the complete duty cycle.
Design Life	15000 h	Design reference only; actual life depends on torque, speed, shock, lubrication and installation.

Transmission Accuracy and Torsional Rigidity

PARAMETER	PUBLISHED VALUE	UNIT
Angle Transmission Accuracy	1	arcmin
Hysteresis Loss	1	arcmin
Torsional Rigidity K1	18	$\times 10^4 \text{Nm/rad}$
Torsional Rigidity K2	29	$\times 10^4 \text{Nm/rad}$
Torsional Rigidity K3	33	$\times 10^4 \text{Nm/rad}$
Torsional Rigidity T1	76	Nm
Torsional Rigidity T2	275	Nm

- Installed positioning performance depends on reducer behavior, datum control, fastener distortion, motor and encoder errors, host stiffness and thermal growth.
- Use the published stiffness regions and transition torques when evaluating compliance, resonance, control gain and direction reversal.

Published Accuracy and Torsional Rigidity Boundaries

PARAMETER	PUBLISHED VALUE	INTEGRATION REQUIREMENT
Angle Transmission Accuracy	1 arcmin	Installed system accuracy also depends on datum, encoder, motor and structural errors.
Hysteresis Loss	1 arcmin	Include in direction-reversal and closed-loop positioning evaluation.
Torsional Rigidity K1	$18 \times 10^4 \text{Nm/rad}$	Applies to the published low-torque stiffness region.
Torsional Rigidity K2	$29 \times 10^4 \text{Nm/rad}$	Applies to the published intermediate stiffness region.
Torsional Rigidity K3	$33 \times 10^4 \text{Nm/rad}$	Applies to the published upper stiffness region.
Torsional Rigidity T1	76 Nm	Published transition torque for stiffness-region interpretation.
Torsional Rigidity T2	275 Nm	Published transition torque for stiffness-region interpretation.

Lubrication, Sealing and Thermal Control

- Use only the current lubricant, fill method and quantity for the exact configuration. Do not mix incompatible lubricants.
- Provide compatible static and dynamic sealing at the input, output and housing interfaces without distorting the reducer or restricting motion.
- Validate lubricant distribution and temperature for the installed orientation, speed, load cycle and enclosure.
- Prevent chips, fibers, cleaning residue, moisture and other contamination from entering the gear or bearing cavities during assembly and service.

Output Bearing and External Load Path

- Calculate radial, axial and moment loads at the output, including offset, acceleration, gravity, process force, impact and emergency-stop cases.
- Do not infer permissible external load from reducer torque capacity or frame size. Use applicable output-bearing data and safety criteria.
- Avoid forcing, impact, misalignment or host distortion through the output support bearing during installation and operation.

Integration Checklist

- | | |
|----|--|
| 01 | Confirm the drawing, published parameters and applicable assembly data identify this SKU. |
| 02 | Verify series, frame size, ratio, product form and input-interface dimensions. |
| 03 | Check mounting-face flatness, concentricity, tilt, chamfers, reliefs, cleanliness and support stiffness. |
| 04 | Verify input shaft, key, engagement length and axial wave-generator retention. |
| 05 | Assemble the fixed and flexible gear members before inserting the wave generator. |
| 06 | Use staged diagonal tightening and verify free, even rotation throughout assembly. |
| 07 | Calculate average, start/stop peak and shock torque over the complete operating cycle. |
| 08 | Validate average and maximum input speed, design life and installed thermal condition. |
| 09 | Evaluate backlash, angular accuracy, hysteresis and stiffness regions for the control system. |
| 10 | Confirm exact lubricant, fill quantity, orientation, sealing and contamination controls. |
| 11 | Validate output radial, axial and moment loads using applicable bearing data. |
| 12 | Include specified 2D, STEP, assembly, lubrication and bearing-load data in integration planning. |

[View SKU Product Datasheet](#) [Request controlled 2D drawing](#) [Request controlled STEP review](#) [Request a Quote](#)

Engineering Use and Verification Notice

01. This Dimensional & Integration Guide applies only to EmbodyStack SKU ES-HG-S07-F45-R100 and is intended for dimensional evaluation and preliminary integration. It is not a applicable manufacturing drawing, reducer selection approval, bearing-load approval, lubrication specification, machinery risk assessment, safety validation or integration planning document and must not be used as the sole basis for machining, shaft or key manufacture, fastener selection, sealing, lubricant filling or final integration. Before design freeze, assembly or commissioning, verify all dimensions, datum geometry, fits, shaft and key interfaces, wave-generator retention, fastener engagement and tightening controls, torque and speed duty, shock cases, torsional accuracy and rigidity, external output loads, lubrication, sealing, temperature, contamination and maintenance requirements against the applicable EmbodyStack engineering data for this exact SKU. Where this guide and applicable product documentation differ, the applicable product documentation governs. Validate the complete reducer, motor, host structure, output load, motion cycle, guarding, fault cases and applicable regulatory requirements under intended operating conditions.