

ENGINEERING DOCUMENTATION

High-Torque Shaft-Input Gear Unit

Dimensional & Integration Guide

DOCUMENT	REVISION / ISSUE	STATUS
DIG-ES-HG-S10-F14-R120	DRAFT-08 / 28 Aug 2026	Engineering Integration Reference

Integration Overview

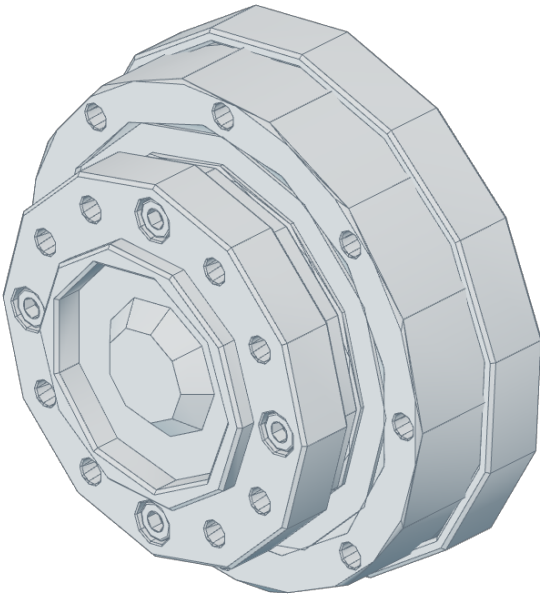
High-Torque Shaft-Input Gear Unit for compact, coaxial, high-ratio rotary-axis integration. This guide supports interface planning, mounting alignment, duty validation, torsional behavior, lubrication, sealing and commissioning for ES-HG-S10-F14-R120.

Key Integration Facts

INTEGRATION ITEM	VALUE
Reduction Ratio	120
Frame Size	14

3D Orientation Reference

This axonometric reference provides a quick orientation check for the reducer body, input interface and mounting relationship of ES-HG-S10-F14-R120.



Axonometric Orientation View

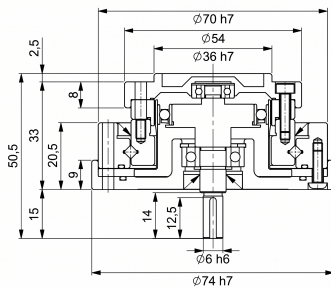
Orientation reference only. Use the exact-SKU parameter table and mechanical drawing for dimensions, hole geometry, fits and machining decisions.

Exact-SKU Interface Cross-Reference

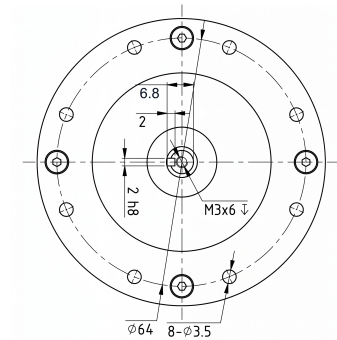
INTEGRATION TOPIC	EXACT-SKU REFERENCE
Reducer envelope and configuration	Frame Size: 14; Reduction Ratio: 120. Confirm hole geometry, datum features and fits in the exact-SKU mechanical drawing.
Torque and speed boundaries	Confirm this interface from the exact-SKU mechanical drawing.
Input and mounting interfaces	Confirm this interface from the exact-SKU mechanical drawing.

Product Structure & Views

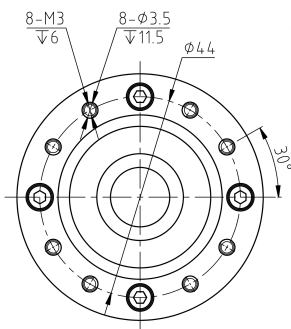
These views present the selected product structure, mounting interfaces and relevant integration geometry for this SKU.



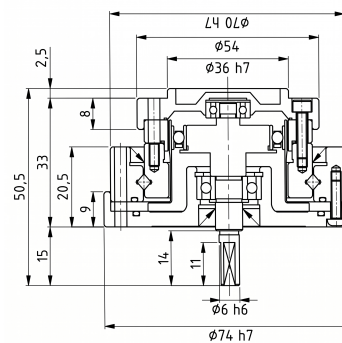
Mechanical View 2



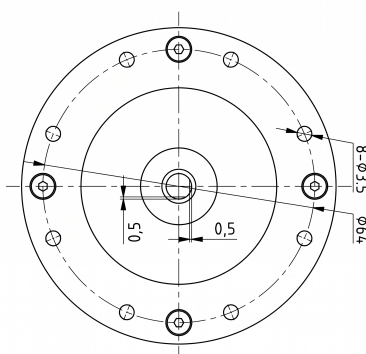
Mechanical View 3



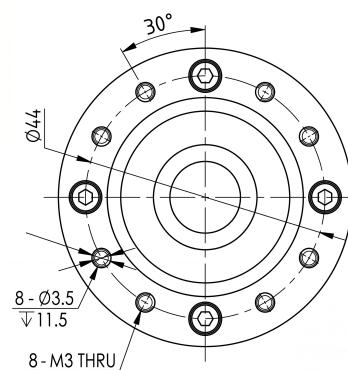
Mechanical View 4



Mechanical View 6



Mechanical View 7



Mechanical View 8

VIEW	FIELD	VALUE
Mechanical View 2	Outer diameter	Diameter 70 h7
	Intermediate step diameter	Diameter 54
	Upper small offset	2.5
	Inner bearing fit diameter	Diameter 36 h7
	Local height	8
	Middle vertical dimension	33
	Middle vertical dimension	20.5
	Overall vertical dimension	50.5
	Bottom local height	9
	Lower vertical dimension	15
	Bottom center height	14
	Bottom right height	12.5
	Bottom shaft diameter	Diameter 6 h6
	Maximum outside diameter	Diameter 74 h7
Mechanical View 3	Local offset dimension	6.8
	Keyway local width	2
	Keyway width tolerance class	2 h8
	Threaded hole specification	M3 thread, 6 mm depth/length
	Mounting hole pitch circle diameter	PCD $\varnothing 4$
	Mounting through-hole quantity and diameter	8 holes, $\varnothing 5$ each
Mechanical View 4	Threaded mounting holes and depth	8× M3 threaded holes, depth 6
	Hole diameter and depth	8× diameter 3.5 holes, depth 11.5
	Circular feature diameter	Diameter 44
	Angular callout	30 degrees
Mechanical View 6	Outer diameter fit	Diameter 70 h7
	Intermediate diameter	Diameter 54
	Step offset dimension	2.5
	Inner diameter fit	Diameter 36 h7
	Local height dimension	8
	Vertical dimension	33
	Overall height dimension	50.5
	Partial height dimension	20.5
	Local width dimension	9
	Local dimension	5
	Lower height dimension	14
	Lower height dimension	11
	Small shaft diameter fit	Diameter 6 h6
	Outer diameter fit	Diameter 74 h7
Mechanical View 7	Equally spaced mounting hole quantity and diameter	8 holes, diameter 3.5 mm
	Central slot or step offset dimension	0.5 mm

VIEW	FIELD	VALUE
Central slot or step width dimension	0.5 mm	
Hole Pitch Circle Diameter	Ø4	

VIEW	FIELD	VALUE
Mechanical View 8	Angular spacing of mounting hole pattern	30 degrees angular spacing
	Mounting hole pitch circle diameter	Pitch circle diameter 44
	Quantity and hole diameter	8 holes, diameter 0.5
	Hole depth or counterbore depth	Depth 11.5
	Threaded through holes	8× M3 through threaded holes

Overall Dimensions and Input Interface

PARAMETER	VALUE	UNIT
Frame Size	14	
Reduction Ratio	120	

Input Interface Design Guidance

- Confirm the selected series, frame size, ratio and product form before using dimensions or interface geometry.
- Design the input shaft, key, engagement and axial retention for the verified torque and assembly state.
- Reserve assembly, sealing, inspection and removal access around input, housing and output interfaces.

Mounting, Alignment and Fastener Control

- Keep mounting faces flat, clean and free of burrs, debris and coating buildup.
- Control concentricity, tilt and axial position of input and housing datums.
- Tighten fasteners in a staged diagonal sequence and verify free, even rotation during assembly.

Torque, Speed and Duty Boundaries

- Calculate torque and speed from acceleration, constant-speed, deceleration, dwell and reversal portions of the complete cycle.
- Treat start/stop peak and instantaneous maximum torque as transient boundaries.
- Validate life against actual torque, speed, shock frequency, lubrication, temperature, alignment and external loading.

Transmission Accuracy and Torsional Rigidity

PARAMETER	VALUE	UNIT
Angle Transmission Accuracy	1.5	arcmin
Hysteresis Loss	1	
Torsional Rigidity K1	0.47	×10 ⁴ Nm/rad
Torsional Rigidity K2	0.61	
Torsional Rigidity K3	0.71	
Torsional Rigidity T1	2	Nm
Torsional Rigidity T2	6.9	

- Installed positioning depends on reducer behavior, datum control, structural stiffness, motor and encoder errors and thermal growth.
- Use stiffness regions and transition torques when evaluating compliance, resonance, control gain and reversal.

Lubrication, Sealing and Thermal Control

- Use the specified lubricant, fill method and quantity for the exact configuration; do not mix incompatible lubricants.
- Provide compatible sealing at input, output and housing interfaces without distorting the reducer.
- Validate lubricant distribution and temperature for orientation, speed, load cycle and enclosure.
- Prevent chips, fibers, residue and moisture from entering gear or bearing cavities.

Output Bearing and External Load Path

- Calculate radial, axial and moment loads including offset, acceleration, gravity, process force, impact and emergency stops.
- Do not infer permissible external load from reducer torque capacity or frame size.
- Avoid forcing, impact, misalignment or host distortion through the output support during installation and operation.

Integration Checklist

- 01 Confirm the selected series, frame size, ratio and product form for this SKU.
- 02 Verify available dimensions and interface geometry without substituting a nearby configuration.
- 03 Check mounting-face flatness, concentricity, tilt, reliefs, cleanliness and support stiffness.
- 04 Verify input shaft, key, engagement length and axial retention.
- 05 Use staged diagonal tightening and verify free, even rotation.
- 06 Calculate average, start/stop peak and shock torque over the complete cycle.
- 07 Validate average and maximum input speed, design life and thermal condition.
- 08 Evaluate backlash, angular accuracy, hysteresis and stiffness for the control system.
- 09 Confirm lubricant, fill quantity, orientation, sealing and contamination controls.
- 10 Validate output radial, axial and moment loads using applicable bearing data.

[View SKU Product Datasheet](#) [Request controlled 2D drawing](#) [Request controlled STEP review](#) [Request a Quote](#)

Engineering Use and Verification Notice

01. This Dimensional & Integration Guide applies only to EmbodyStack SKU ES-HG-S10-F14-R120 and supports preliminary dimensional evaluation and integration. It is not a manufacturing drawing, reducer selection approval, bearing-load approval, lubrication specification, machinery risk assessment, safety validation or integration planning document. Before design freeze, assembly or commissioning, verify all dimensions, datum geometry, fits, interfaces, retention, fasteners, torque and speed duty, shock cases, torsional behavior, external loads, lubrication, sealing, temperature, contamination and maintenance requirements against the current EmbodyStack engineering data for this exact SKU. Validate the complete reducer, motor, host structure, output load, motion cycle, guarding, fault cases and applicable regulatory requirements under intended operating conditions.