

ENGINEERING DOCUMENTATION

Lightweight Cup Unit Type I

Dimensional & Integration Guide

DOCUMENT	REVISION / ISSUE	STATUS
DIG-ES-HG-S11-F20-R30	DRAFT-08 / 28 Aug 2026	Engineering Integration Reference

Integration Overview

Lightweight Cup Unit Type I for compact, coaxial, high-ratio rotary-axis integration. This guide supports interface planning, mounting alignment, duty validation, torsional behavior, lubrication, sealing and commissioning for ES-HG-S11-F20-R30.

Key Integration Facts

INTEGRATION ITEM	VALUE
Reduction Ratio	30
Frame Size	20

VIEW	FIELD	VALUE
Mechanical View 1	Upper overall width	41
	Upper inner width	38
	Local step dimensions	5.5 and 10
	Upper right leader callout	O-67x2
	Upper left local width	12.5
	Upper left small step dimension	0.5
	Left outer diameter fit	Diameter 72 h7
	Left diameter	Diameter 70
	Left diameter	Diameter 45
	Bore diameter fit	Diameter 14 H7
	Bore diameter	Diameter 10
	Local width	9
	Datum or label D	D
	Datum or label T	T
	Right diameter	Diameter 33
	Right outer diameter fit	Diameter 56 h7
	Right outer diameter	Diameter 93
	Lower left leader callout	O-40x1
	Axial dimension with symmetric tolerance	11 +/- 0.2
	Component name	Wave Generator-A
	Axial dimension with unilateral tolerance	13.5 +0/-0.1
	Bottom width	23
	Feature dimension	3.10 mm
	Flange thickness	4 mm
	Bottom step height	4 mm
Mechanical View 2	Threaded hole quantity and thread size	8 x M5 threaded holes
	Width designation	W, numeric value not specified in this crop
	Through-hole quantity and diameter	8 x Ø5.5 holes
	Diameter 82 feature	Ø82
	Threaded hole quantity and thread size	4 x M4 threaded holes
	Diameter 27 feature	Ø27
	Orientation reference mark	Orientation reference "U"
Mechanical View 3	A-side mounting threaded hole quantity and thread size	8 x M6 threaded holes
	Mounting hole pitch circle diameter	Diameter 32
Mechanical View 4	View direction	View D
	Central diameter	Diameter 18 mm
	Outer diameter	Diameter 22 mm
	Threaded hole quantity and size	2 x M2.5 threaded holes
	Hole depth	Depth 5 mm

Housing and Input Interface Dimensions

Housing Size: 20 Reduction Ratio: 30

WAVE GENERATOR	T (MM)	U	W
A8	9.4 +0.10	8 H7	3 JS9/P9
A11	12.8 +0.10	11 H7	4 JS9/P9
A14	16.3 +0.10	14 H7	5 JS9/P9

Note: Dimensions in mm unless otherwise specified. Refer to the dimensional drawing for feature locations and datum definitions.

Input Interface Design Guidance

- Confirm the selected series, frame size, ratio and product form before using dimensions or interface geometry.
- Design the input shaft, key, engagement and axial retention for the verified torque and assembly state.
- Reserve assembly, sealing, inspection and removal access around input, housing and output interfaces.

Mounting, Alignment and Fastener Control

- Keep mounting faces flat, clean and free of burrs, debris and coating buildup.
- Control concentricity, tilt and axial position of input and housing datums.
- Tighten fasteners in a staged diagonal sequence and verify free, even rotation during assembly.

Torque, Speed and Duty Boundaries

- Calculate torque and speed from acceleration, constant-speed, deceleration, dwell and reversal portions of the complete cycle.
- Treat start/stop peak and instantaneous maximum torque as transient boundaries.
- Validate life against actual torque, speed, shock frequency, lubrication, temperature, alignment and external loading.

Transmission Accuracy and Torsional Rigidity

- Installed positioning depends on reducer behavior, datum control, structural stiffness, motor and encoder errors and thermal growth.
- Use stiffness regions and transition torques when evaluating compliance, resonance, control gain and reversal.

Lubrication, Sealing and Thermal Control

- Use the specified lubricant, fill method and quantity for the exact configuration; do not mix incompatible lubricants.
- Provide compatible sealing at input, output and housing interfaces without distorting the reducer.
- Validate lubricant distribution and temperature for orientation, speed, load cycle and enclosure.
- Prevent chips, fibers, residue and moisture from entering gear or bearing cavities.

Output Bearing and External Load Path

- Calculate radial, axial and moment loads including offset, acceleration, gravity, process force, impact and emergency stops.
- Do not infer permissible external load from reducer torque capacity or frame size.
- Avoid forcing, impact, misalignment or host distortion through the output support during installation and operation.

Integration Checklist

- | | |
|----|---|
| 01 | Confirm the selected series, frame size, ratio and product form for this SKU. |
| 02 | Verify available dimensions and interface geometry without substituting a nearby configuration. |
| 03 | Check mounting-face flatness, concentricity, tilt, reliefs, cleanliness and support stiffness. |
| 04 | Verify input shaft, key, engagement length and axial retention. |
| 05 | Use staged diagonal tightening and verify free, even rotation. |
| 06 | Calculate average, start/stop peak and shock torque over the complete cycle. |
| 07 | Validate average and maximum input speed, design life and thermal condition. |
| 08 | Evaluate backlash, angular accuracy, hysteresis and stiffness for the control system. |
| 09 | Confirm lubricant, fill quantity, orientation, sealing and contamination controls. |
| 10 | Validate output radial, axial and moment loads using applicable bearing data. |

[View SKU Product Datasheet](#) [Request controlled 2D drawing](#) [Request controlled STEP review](#) [Request a Quote](#)

Engineering Use and Verification Notice

01. This Dimensional & Integration Guide applies only to EmbodyStack SKU ES-HG-S11-F20-R30 and supports preliminary dimensional evaluation and integration. It is not a manufacturing drawing, reducer selection approval, bearing-load approval, lubrication specification, machinery risk assessment, safety validation or integration planning document. Before design freeze, assembly or commissioning, verify all dimensions, datum geometry, fits, interfaces, retention, fasteners, torque and speed duty, shock cases, torsional behavior, external loads, lubrication, sealing, temperature, contamination and maintenance requirements against the current EmbodyStack engineering data for this exact SKU. Validate the complete reducer, motor, host structure, output load, motion cycle, guarding, fault cases and applicable regulatory requirements under intended operating conditions.