

## ENGINEERING DOCUMENTATION

# Standard Cup Unit Type I

## Dimensional &amp; Integration Guide

| DOCUMENT              | REVISION / ISSUE       | STATUS                            |
|-----------------------|------------------------|-----------------------------------|
| DIG-ES-HG-S22-F25-R80 | DRAFT-08 / 26 Aug 2026 | Engineering Integration Reference |

## Integration Overview

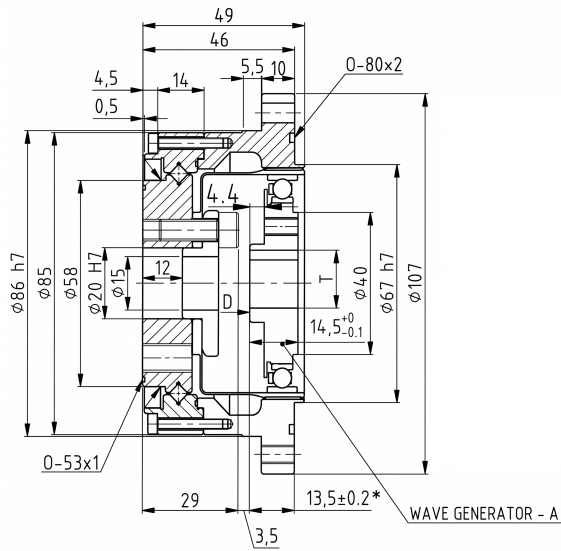
Cup-form harmonic gear gear unit with integrated product interfaces for the selected configuration for compact, coaxial, high-ratio rotary axes. This guide supports host-interface design, wave-generator input integration, mounting alignment, load-cycle validation, torsional behavior, lubrication, sealing and commissioning for ES-HG-S22-F25-R80.

## Key Integration Facts

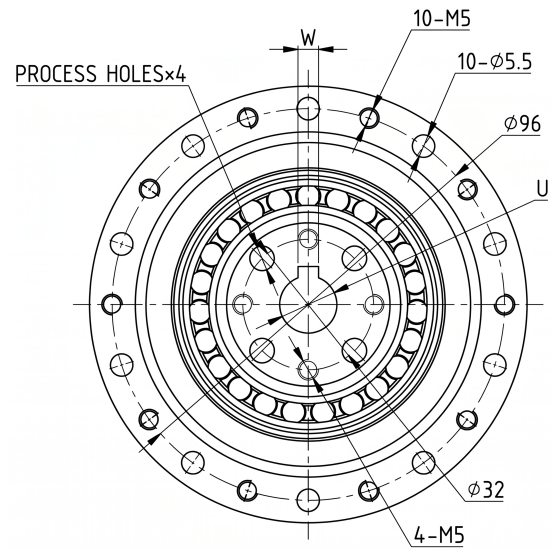
| INTEGRATION ITEM             | PUBLISHED VALUE |
|------------------------------|-----------------|
| Rated Torque                 | 63 Nm           |
| Instantaneous Maximum Torque | 255 Nm          |
| Start/Stop Peak Torque       | 137 Nm          |
| Backlash                     | ±0 arc sec      |
| Reduction Ratio              | 80              |
| Maximum Input Speed          | 5600 r/min      |
| Frame Size                   | 25              |
| Weight                       | 1.46 kg         |

## Product Structure & Views

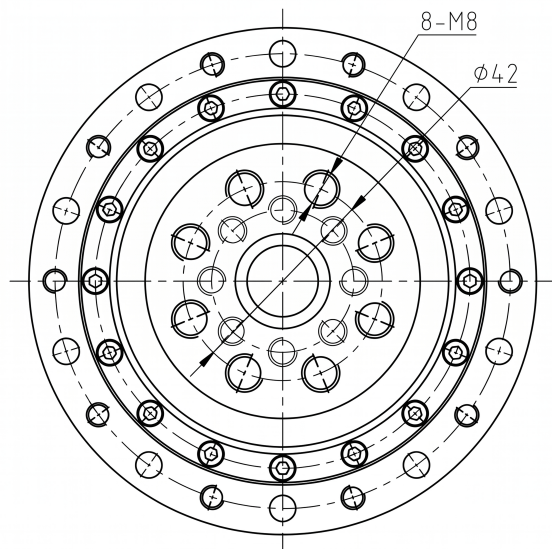
These views present the selected product structure, mounting interfaces and relevant integration geometry for this SKU.



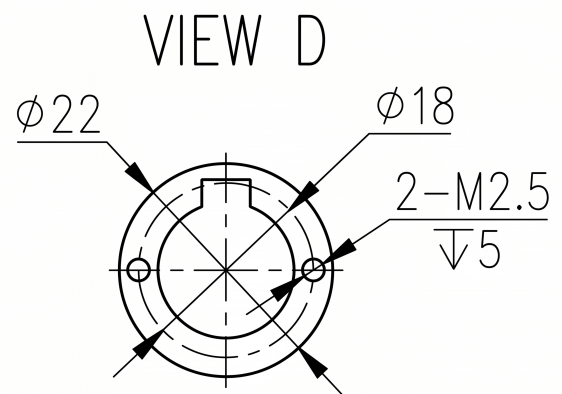
Mechanical View 1



Mechanical View 2



Mechanical View 3



Mechanical View 4

| VIEW              | FIELD                                           | VALUE                                                           |
|-------------------|-------------------------------------------------|-----------------------------------------------------------------|
| Mechanical View 1 | Overall axial length                            | 49 mm                                                           |
|                   | Axial length 2                                  | 46 mm                                                           |
|                   | Thread or tooth profile specification           | 0-80x2                                                          |
|                   | Axial segment length 5.5                        | 5.5 mm                                                          |
|                   | Axial segment length 10                         | 10 mm                                                           |
|                   | Axial segment length 4.5                        | 4.5 mm                                                          |
|                   | Axial segment length 14                         | 14 mm                                                           |
|                   | Axial segment length 0.5                        | 0.5 mm                                                          |
|                   | Outer diameter $\varnothing 6$ h7               | $\varnothing 6$ h7                                              |
|                   | Outer diameter $\varnothing 5$                  | $\varnothing 5$ mm                                              |
|                   | Outer diameter $\varnothing 8$                  | $\varnothing 8$ mm                                              |
|                   | Bore diameter $\varnothing 0$ H7                | $\varnothing 0$ H7                                              |
|                   | Bore diameter $\varnothing 5$                   | $\varnothing 5$ mm                                              |
|                   | Axial segment length 12                         | 12 mm                                                           |
|                   | Groove depth or step 4.4                        | 4.4 mm                                                          |
|                   | Datum D (left view)                             | Datum D                                                         |
|                   | Label T                                         | T                                                               |
|                   | Outer diameter $\varnothing 0$                  | $\varnothing 0$ mm                                              |
|                   | Outer diameter $\varnothing 7$ h7               | $\varnothing 7$ h7                                              |
|                   | Maximum outer diameter $\varnothing 07$         | $\varnothing 07$ mm                                             |
|                   | Axial dimension 14.5 +0/-0.1                    | 14.5 +0/-0.1 mm                                                 |
|                   | Datum D (right view)                            | Datum D                                                         |
|                   | Thread or spline specification 0-53x1           | 0-53x1                                                          |
|                   | Axial length 29                                 | 29 mm                                                           |
|                   | Axial dimension 13.5±0.2 (reference/special)    | 13.5 ±0.2 mm *                                                  |
|                   | Axial segment length 3.5                        | 3.5 mm                                                          |
|                   | Component label - Wave Generator A              | Wave Generator - A                                              |
| Mechanical View 2 | M5 threaded hole quantity                       | 10 × M5 threaded holes                                          |
|                   | Local width label                               | Width identified as W; numeric value not specified in this crop |
|                   | 5.5 mm mounting hole quantity                   | 10 × $\varnothing 5.5$ holes                                    |
|                   | Process hole quantity note                      | Process holes ×4                                                |
|                   | Diameter 96 circular feature                    | $\varnothing 6$                                                 |
|                   | U label                                         | U label; numeric value not specified                            |
|                   | Diameter 32 circular feature                    | $\varnothing 2$                                                 |
|                   | M5 threaded hole quantity                       | 4 × M5 threaded holes                                           |
| Mechanical View 3 | Threaded mounting hole quantity and thread size | 8 × M8 threaded holes                                           |

| VIEW                                | FIELD                                  | VALUE                   |
|-------------------------------------|----------------------------------------|-------------------------|
| Mounting hole pitch circle diameter | Diameter 42                            |                         |
| Mechanical View 4                   | View identification                    | View D                  |
|                                     | Outer diameter dimension               | Diameter 22 mm          |
|                                     | Inner diameter dimension               | Diameter 18 mm          |
|                                     | Threaded hole quantity and thread size | 2 × M2.5 threaded holes |
|                                     | Hole depth                             | Depth 5 mm              |

## Overall Dimensions and Input Interface

| PARAMETER                  | PUBLISHED VALUE       | UNIT |
|----------------------------|-----------------------|------|
| Frame Size                 | 25                    |      |
| Weight                     | 1.46                  | kg   |
| Wave Generator Dimension T | 12.8+0.10 / 16.3+0.10 | mm   |
| Wave Generator Bore U      | Ø4H7 / Ø1H7           |      |
| Wave Generator Keyway W    | 4JS9/P9 / 5JS9/P9     |      |

- Confirm the selected series, frame size and ratio before using dimensions or interface geometry. Do not substitute a nearby frame or product form.
- Design the input shaft, key, effective engagement and axial retention to transmit the verified torque without uncontrolled wave-generator axial movement.
- Reserve assembly, sealing, inspection and removal access around the input, housing and output interfaces.

## Mounting, Alignment and Fastener Control

- Keep mounting faces flat, clean and free of burrs, raised holes, debris and coating buildup. Confirm reliefs and chamfers prevent interference.
- Seat the fixed and flexible gear members in the host structure before inserting the wave generator. Do not force engagement in a misaligned condition.
- Control concentricity, tilt and axial position of the input and housing datums. Insert the wave generator smoothly without excessive force on its bearing.
- Tighten fasteners in a staged diagonal sequence using the applicable torque and locking specification. Verify free, even rotation during assembly.

## Torque, Speed and Duty Boundaries

| PARAMETER                    | PUBLISHED VALUE | UNIT  |
|------------------------------|-----------------|-------|
| Rated Torque                 | 63              | N·m   |
| Allowable Average Torque     | 87              | N·m   |
| Start/Stop Peak Torque       | 137             | N·m   |
| Instantaneous Maximum Torque | 255             | N·m   |
| Maximum Input Speed          | 5600            | r/min |
| Average Input Speed          | 3500            | r/min |
| Design Life                  | 15000           | h     |

- Calculate average torque and average input speed from the complete acceleration, constant-speed, deceleration, dwell and reversal cycle.
- Treat start/stop peak and instantaneous maximum torque as transient boundaries. Do not use either value as a continuous operating point.
- Validate design life against actual torque, speed, shock frequency, lubrication, temperature, alignment and external loading.

### Published Torque, Speed and Life Boundaries

| PARAMETER                    | PUBLISHED VALUE | INTEGRATION REQUIREMENT                                                                           |
|------------------------------|-----------------|---------------------------------------------------------------------------------------------------|
| Rated Torque                 | 63 N·m          | Use as the selected continuous output rating under validated duty and thermal conditions.         |
| Allowable Average Torque     | 87 N·m          | Calculate the actual time-weighted output torque over the complete cycle.                         |
| Start/Stop Peak Torque       | 137 N·m         | Transient start/stop boundary; include acceleration and deceleration events.                      |
| Instantaneous Maximum Torque | 255 N·m         | Short-duration shock boundary only; do not use as a normal operating point.                       |
| Maximum Input Speed          | 5600 r/min      | Maximum input-speed boundary; also verify motor and thermal limits.                               |
| Average Input Speed          | 3500 r/min      | Validate the time-weighted average input speed over the complete duty cycle.                      |
| Design Life                  | 15000 h         | Design reference only; actual life depends on torque, speed, shock, lubrication and installation. |

## Transmission Accuracy and Torsional Rigidity

| PARAMETER | PUBLISHED VALUE | UNIT    |
|-----------|-----------------|---------|
| Backlash  | ±0              | arc sec |

- Installed positioning performance depends on reducer behavior, datum control, fastener distortion, motor and encoder errors, host stiffness and thermal growth.
- Use the published stiffness regions and transition torques when evaluating compliance, resonance, control gain and direction reversal.

### Published Accuracy and Torsional Rigidity Boundaries

| PARAMETER | PUBLISHED VALUE | INTEGRATION REQUIREMENT                                                     |
|-----------|-----------------|-----------------------------------------------------------------------------|
| Backlash  | ±0 arc sec      | Validate at the selected measurement condition and installed preload state. |

## Lubrication, Sealing and Thermal Control

- Use only the current lubricant, fill method and quantity for the exact configuration. Do not mix incompatible lubricants.
- Provide compatible static and dynamic sealing at the input, output and housing interfaces without distorting the reducer or restricting motion.
- Validate lubricant distribution and temperature for the installed orientation, speed, load cycle and enclosure.
- Prevent chips, fibers, cleaning residue, moisture and other contamination from entering the gear or bearing cavities during assembly and service.

## Output Bearing and External Load Path

- Calculate radial, axial and moment loads at the output, including offset, acceleration, gravity, process force, impact and emergency-stop cases.
- Do not infer permissible external load from reducer torque capacity or frame size. Use applicable output-bearing data and safety criteria.
- Avoid forcing, impact, misalignment or host distortion through the output support bearing during installation and operation.

## Integration Checklist

- |    |                                                                                                          |
|----|----------------------------------------------------------------------------------------------------------|
| 01 | Confirm the drawing, published parameters and applicable assembly data identify this SKU.                |
| 02 | Verify series, frame size, ratio, product form and input-interface dimensions.                           |
| 03 | Check mounting-face flatness, concentricity, tilt, chamfers, reliefs, cleanliness and support stiffness. |
| 04 | Verify input shaft, key, engagement length and axial wave-generator retention.                           |
| 05 | Assemble the fixed and flexible gear members before inserting the wave generator.                        |
| 06 | Use staged diagonal tightening and verify free, even rotation throughout assembly.                       |
| 07 | Calculate average, start/stop peak and shock torque over the complete operating cycle.                   |
| 08 | Validate average and maximum input speed, design life and installed thermal condition.                   |
| 09 | Evaluate backlash, angular accuracy, hysteresis and stiffness regions for the control system.            |
| 10 | Confirm exact lubricant, fill quantity, orientation, sealing and contamination controls.                 |
| 11 | Validate output radial, axial and moment loads using applicable bearing data.                            |
| 12 | Include specified 2D, STEP, assembly, lubrication and bearing-load data in integration planning.         |

[View SKU Product Datasheet](#)[Request controlled 2D drawing](#)[Request controlled STEP review](#)[Request a Quote](#)

## Engineering Use and Verification Notice

**01.** This Dimensional & Integration Guide applies only to EmbodyStack SKU ES-HG-S22-F25-R80 and is intended for dimensional evaluation and preliminary integration. It is not a applicable manufacturing drawing, reducer selection approval, bearing-load approval, lubrication specification, machinery risk assessment, safety validation or integration planning document and must not be used as the sole basis for machining, shaft or key manufacture, fastener selection, sealing, lubricant filling or final integration. Before design freeze, assembly or commissioning, verify all dimensions, datum geometry, fits, shaft and key interfaces, wave-generator retention, fastener engagement and tightening controls, torque and speed duty, shock cases, torsional accuracy and rigidity, external output loads, lubrication, sealing, temperature, contamination and maintenance requirements against the applicable EmbodyStack engineering data for this exact SKU. Where this guide and applicable product documentation differ, the applicable product documentation governs. Validate the complete reducer, motor, host structure, output load, motion cycle, guarding, fault cases and applicable regulatory requirements under intended operating conditions.