ENGINEERING DOCUMENTATION

24-60 V Compact Servo Drive

Dimensional & Integration Guide

DOCUMENT	REVISION / ISSUE	STATUS
DIG-ES-SD-C01-S010-V008	DRAFT-08 / 29 Aug 2026	Engineering Integration Reference

Integration Overview

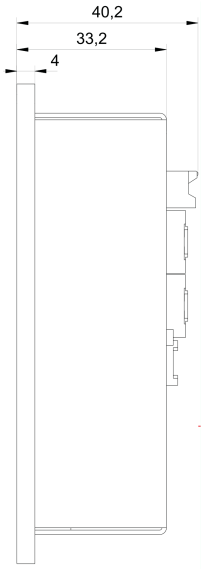
Compact low-voltage servo drive for cabinet-integrated motion control. This guide supports panel mounting, thermal planning, power and braking integration, signal routing, communication commissioning and enclosure boundary definition for ES-SD-C01-S010-V008.

Key Integration Facts

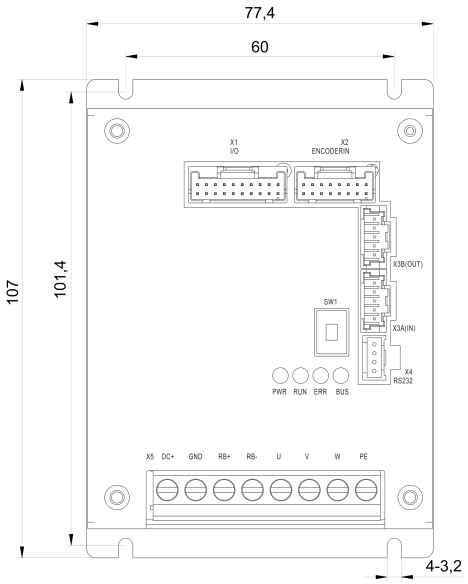
INTEGRATION ITEM	VALUE
Continuous Output Current Without Auxiliary Heatsink	13 Arms
Peak Output Current	80 A peak
Servo Drive AC Supply Voltage	24 to 70 VDC
Logic Supply Voltage	24 VDC
Communication Protocol	RS232; EtherCAT; CoE CiA 402; Pulse
Weight	0.393 kg
Protection Class	IP20
Operating Temperature	0 to 40 °C

Product Structure & Views

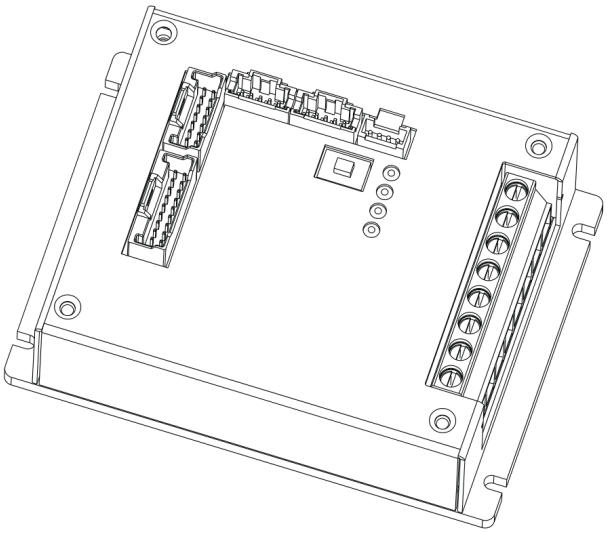
These views present product structure, mounting interfaces and relevant integration geometry for this SKU.



Mechanical View 1



Mechanical View 2



Mechanical View 3

VIEW	FIELD	VALUE
Mechanical View 1	Overall length	40.2 mm
	Internal width	33.2 mm
	Left protrusion length	4 mm
Mechanical View 2	Overall width	77.4 mm
	Inner width	60 mm
	Left side height	107 mm
	Mounting height	101.4 mm
	Bottom mounting holes pattern	4 holes, 3.2 mm diameter

Overall Dimensions and Panel Mounting

PARAMETER	VALUE	UNIT
Weight	0.393	kg
Installation Orientation	Vertical	

- Mount the drive to a rigid, flat panel so the housing is not twisted and the thermal path remains repeatable.
- Use only a installation orientation and confirm connector access, conductor bend radius and service removal space before releasing the panel layout.
- Keep terminal and connector approach zones accessible without forcing cables against adjacent devices or the enclosure.

Thermal Management and Clearance

PARAMETER	VALUE	UNIT
Continuous Output Current Without Auxiliary Heatsink	13	Arms
Operating Temperature	0 to 40	°C

- Preserve natural or forced airflow around the drive and do not obstruct heat-transfer surfaces with cable bundles, covers or adjacent heat sources.
- Validate continuous current, auxiliary heat sinking, enclosure temperature, altitude and duty cycle together; use applicable derating data when any boundary is approached.
- Separate the drive from braking resistors, power supplies and other concentrated heat sources unless the complete thermal design has been verified.

Power, Braking and Protective Integration

PARAMETER	VALUE	UNIT
Servo Drive AC Supply Voltage	24 to 70	VDC
Logic Supply Voltage	24	
Logic Supply Current	1	A
Peak Output Current	80	A peak
Braking Absorption Voltage	73 ±2 V	VDC
Overvoltage Alarm Voltage	86 ±2 V	
Undervoltage Alarm Voltage	18 ±2 V	
Protection Functions	Overvoltage; Undervoltage; Motor overtemperature (PT); Short circuit; Drive overtemperature	

- Before energization, verify power and logic supply ranges, polarity, protective devices, conductor ratings and discharge state against applicable terminal documentation.
- Size and locate any external braking element for the actual regenerative energy, duty cycle and enclosure thermal conditions; keep hot components clear of wiring and heat-sensitive devices.

Electrical Boundaries

BOUNDARY	VALUE	INTEGRATION REQUIREMENT
Power input	24 to 70 VDC	Coordinate the host supply, wiring and protective strategy with this exact-SKU boundary.
Peak output current	80 A peak	
Braking absorption threshold	73 ±2 V VDC	
Overvoltage alarm threshold	86 ±2 V VDC	
Undervoltage alarm threshold	18 ±2 V VDC	

I/O, Feedback and Communication Interfaces

PARAMETER	VALUE	UNIT
Communication Protocol	RS232; EtherCAT; CoE CiA 402; Pulse	
Control Method	RS232, EtherCAT and pulse	
Digital I/O	4 digital inputs; 2 digital outputs; 1 brake output	
Digital Input Count	4	
Digital Output Count	2	
Analog Input Count	1	
Analog Input Range	-10 to +10	V
Pulse Input Voltage	3.3 to 24	VDC
Feedback Signal Support	2500 P/R incremental differential 5 V encoder; Magnetic encoder	
Brake Output Current	500	mA

- Do not infer terminal or connector pin assignments from this guide. Use the applicable wiring and communication documentation for the exact SKU.
- Confirm voltage levels, input type, output loading, pulse frequency, feedback protocol and communication termination against the connected controller and motor.
- Commission one command and feedback path at a time, then verify direction, scaling, status handling and fault response before enabling coordinated motion.

Grounding, EMC and Cable Routing

- Bond the drive, mounting panel and enclosure through a low-impedance protective and functional grounding architecture sized for the installation.
- Route power and motor conductors separately from encoder, analog, pulse and communication wiring; cross dissimilar cable groups only where necessary.
- Terminate shields and cable clamps using the qualified EMC architecture, with short low-impedance connections and defined cabinet entry.

Operating and Enclosure Conditions

PARAMETER	VALUE	UNIT
Protection Class	IP20	
Installation Environment	Dry, dust-free enclosed location such as an electrical cabinet	
Operating Temperature	0 to 40	°C
Installation Orientation	Vertical	

- Treat the component and terminal ratings as local boundaries. The host enclosure must provide the required access control, ingress protection, contamination control and thermal environment.

Ingress and Enclosure Boundaries

BOUNDARY	CONDITION	INTEGRATION REQUIREMENT
Drive housing	IP20	Do not treat the component rating as the protection rating of the completed control assembly.
Power terminal zone	Verify terminal-zone protection	Contain access within the host enclosure and maintain required electrical clearances and service controls.
Host electrical enclosure	Dry, dust-free enclosed location such as an electrical cabinet	Validate enclosure ingress protection, contamination control, thermal management and cable entry for the installed environment.

Commissioning and Safety Functions

- Before power-up, inspect mounting, protective bonding, terminal torque, conductor routing, polarity, motor and feedback compatibility, and enclosure clearances.
- Commission with the mechanism unloaded or restrained as appropriate, conservative current and motion limits, and a verified stop path before normal operation.
- Any safety input or safe-torque function used by the selected configuration must be integrated and validated as part of the machine safety design; this guide does not define safety performance or terminal assignments.

Integration Checklist

01	Confirm that the 2D drawing, parameter set and applicable wiring data all identify ES-SD-C01-S010-V008.
02	Verify housing dimensions, mounting points, orientation, connector approach and service removal space.
03	Confirm enclosure protection, contamination control, ambient temperature, altitude and thermal derating requirements.
04	Verify power and logic supply ranges, polarity, protective devices, conductor ratings and discharge controls.
05	Validate continuous and peak current requirements together with auxiliary heat sinking and the machine duty cycle.
06	Confirm braking-energy handling, resistor rating, placement, guarding and thermal separation where applicable.
07	Verify motor, brake and feedback compatibility before connecting the load.
08	Confirm digital, analog, pulse and communication interface levels, loading, addressing and termination.
09	Complete protective bonding, shield termination and power-versus-signal cable segregation.
10	Validate safe-state behavior, stop path and any safety function within the complete machine safety design.
11	Commission under defined motion limits and verify direction, scaling, feedback, status and fault response.
12	Request current 2D, STEP, terminal, wiring and communication data before integration planning.

View SKU Product Datasheet **Request controlled 2D drawing** **Request controlled STEP review** **Request a Quote**

Engineering Use and Verification Notice

01. This Dimensional & Integration Guide applies only to EmbodyStack SKU ES-SD-C01-S010-V008 and is intended for dimensional evaluation and preliminary integration. It is not a specified installation manual, wiring diagram, terminal assignment, safety manual or manufacturing drawing and must not be used as the sole basis for panel fabrication, conductor sizing, protective-device selection, braking-resistor design, safety validation or integration planning. Before design freeze or energization, verify dimensions, mounting orientation, ventilation and derating requirements, power and logic supply limits, terminal assignments, conductor and protective bonding requirements, motor and feedback compatibility, braking-energy management, communication settings, safe-state behavior, enclosure protection and environmental limits against the applicable EmbodyStack engineering data for this exact SKU. Where this guide and applicable product documentation differ, the applicable product documentation governs. Validate the complete machine under its intended supply conditions, load cycle, fault cases, environment and applicable regulatory requirements.