ENGINEERING DOCUMENTATION

Rotary Servo Motor

Dimensional & Integration Guide

DOCUMENT	REVISION / ISSUE	STATUS
DIG-ES-SM-A01-060S-T0P64NM-200W-004	DRAFT-08 / 27 Aug 2026	Engineering Integration Reference

Integration Overview

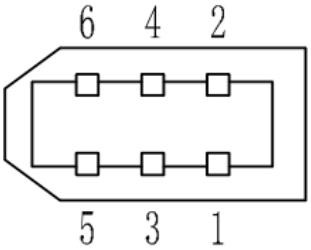
Closed-loop rotary servo motor for specified motion axes. This guide supports mechanical mounting, shaft and coupling integration, feedback and brake planning, cable routing, thermal validation and staged commissioning.

Key Integration Facts

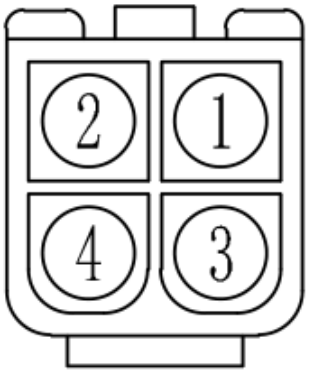
INTEGRATION ITEM	PUBLISHED VALUE
Rated Torque	0.64 N·m
Rated Speed	3000 rpm
Flange Size	60 mm

Product Structure & Views

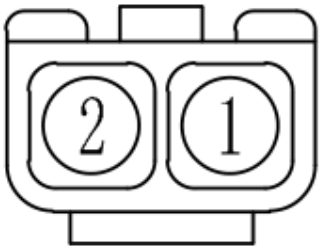
These views present product structure, mounting interfaces and relevant integration geometry for this SKU.



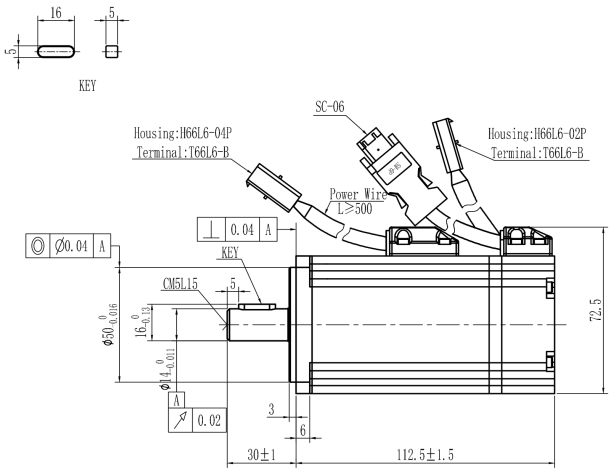
Mechanical View 2



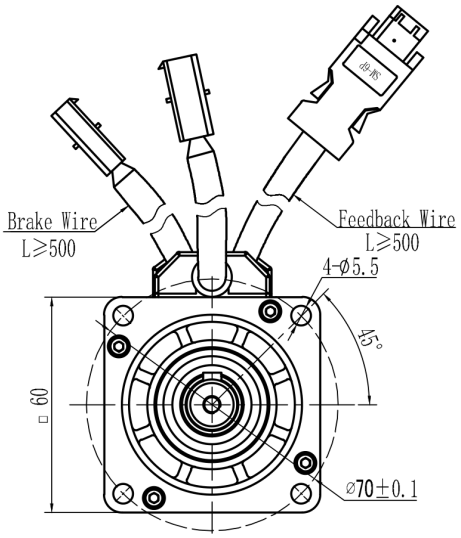
Mechanical View 4



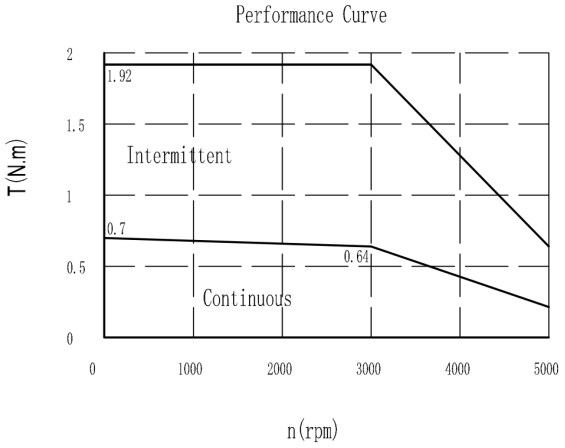
Mechanical View 6



Mechanical View 7



Mechanical View 8



Mechanical View 11

VIEW	FIELD	VALUE
Mechanical View 2	SC-06 Connector Pin 6	Pin 6
	SC-06 Connector Pin 4	Pin 4
	SC-06 Connector Pin 2	Pin 2
	SC-06 Connector Pin 5	Pin 5
	SC-06 Connector Pin 3	Pin 3
	SC-06 Connector Pin 1	Pin 1
Mechanical View 4	Connector Terminal Number - Position 2	Terminal position 2
	Connector Terminal Number - Position 1	Terminal position 1
	Connector Terminal Number - Position 4	Terminal position 4
	Connector Terminal Number - Position 3	Terminal position 3
Mechanical View 6	Connector pin number	Pin 2
	Connector pin number	Pin 1
Mechanical View 7	Keyway width	16 mm
	Keyway depth	5 mm
	Power connector housing	H66L6-04P
	Power connector terminal	T66L6-B
	Encoder connector housing	H66L6-02P
	Encoder connector terminal	T66L6-B
	Power wire minimum length	≥500 mm
	Position tolerance	0.04 relative to datum A
	Concentricity tolerance	0.04 relative to datum A
	Key specification	CM5L15
	Keyway width	5 mm
	Shaft diameter	⌀50 0/-0.016 mm
	Keyway width	16 0/-0.13 mm
	Hole diameter	⌀14 0/-0.011 mm
	Datum reference	Datum A
	Parallelism tolerance	↗ 0.02 mm
	Axial dimension	3 mm
	Axial dimension	6 mm
	Flange thickness or axial dimension	30±1 mm
	Overall length	112.5±1.5 mm
	Center height	72.5 mm
	Key Width	5 mm
Mechanical View 8	Brake Wire Cable	Brake Wire
	Brake Wire Minimum Length	L ≥500 mm

VIEW	FIELD	VALUE
Feedback Wire Cable	Feedback Wire	
Feedback Wire Minimum Length	L ≥500 mm	
Mounting Hole Pattern	4 holes × Ø5.5 mm	
Mounting Hole Angular Position	45°	
Flange Square Dimension	60 mm × 60 mm square	
Mounting Hole PCD (Pitch Circle Diameter)	Ø70 ± 0.1 mm	
Mechanical View 11	Intermittent Operation Peak Torque	1.92 N.m
	Continuous Operation Starting Torque	0.7 N.m
	Continuous Operation Torque at ~3000 rpm	0.641 N.m
	Rated Speed Range	0 - 5000 rpm
	Torque scale values	Torque axis scale values: 0, 0.5, 1, 1.5, 2
	Intermittent operating region	Intermittent operation region
	Continuous operating region	Continuous operation region
	Speed axis label	Rotational speed n in rpm
	Torque axis label	Torque T in N.m

Overall Dimensions and Mounting Interface

PARAMETER	PUBLISHED VALUE	UNIT
Flange Size	60	mm

- Confirm the mounting face, locating feature, shaft geometry, fastener engagement and removal clearance against the applicable exact-SKU drawing.
- Mount the motor on a flat, rigid interface and avoid using fasteners to pull a misaligned assembly into position.

Shaft, Coupling and Load Path

PARAMETER	PUBLISHED VALUE	UNIT
Rotor Inertia	0.204	kg·cm²

- Align the driven shaft and coupling before tightening; validate radial, axial and moment loads against applicable bearing-load data.
- Do not hammer, uncontrolled press-fit or transmit installation force through the motor bearings.

Electrical, Feedback and Brake Integration

PARAMETER	PUBLISHED VALUE	UNIT
Position Feedback Device	17-bit multi-turn communication magnetic absolute encoder	

- Use only the current winding, feedback, brake and connector definitions for this exact SKU.
- Verify drive compatibility, polarity, current limits, feedback direction and brake sequencing before enabling torque.

Thermal, Duty and Environmental Conditions

PARAMETER	PUBLISHED VALUE	UNIT
Rated Torque	0.64	N·m
Operating Temperature	20 40□	°C

- Validate winding and housing temperature under the installed duty cycle, ambient condition, mounting heat path and enclosure airflow.
- Published peak values are transient boundaries and must not be treated as continuous operating ratings.

Cable Routing, Grounding and EMC

PARAMETER	PUBLISHED VALUE	UNIT
Position Feedback Device	17-bit multi-turn communication magnetic absolute encoder	

- Provide strain relief and bend radius through the full machine motion envelope.
- Separate motor power, brake and feedback wiring and terminate shields according to the specified system grounding architecture.

Commissioning and Motion Validation

PARAMETER	PUBLISHED VALUE	UNIT
Rated Speed	3000	rpm
Rated Torque	0.64	N·m

- Commission at low energy with the transmission unloaded or safely restrained, then confirm direction, feedback polarity, brake final integration, current limit and fault response.
- Validate the complete axis through intended acceleration, speed, load, stop and fault cycles during integration planning.

Integration Checklist

01	Confirm the exact SKU, 2D drawing and applicable wiring data.
02	Verify mounting, shaft, coupling, alignment, fasteners and removal clearance.
03	Validate radial and axial loads, inertia, acceleration and credible shock cases.
04	Confirm drive, winding, feedback, brake and connector compatibility.
05	Set current, speed, acceleration and thermal limits from the installed duty cycle.
06	Verify cable routing, shielding, grounding, strain relief and bend radius.
07	Commission at low energy before validating the full machine cycle.

View SKU Product Datasheet Request controlled 2D drawing Request controlled STEP review Request a Quote

Engineering Use and Verification Notice

01. This Dimensional & Integration Guide applies only to EmbodyStack SKU ES-SM-A01-060S-T0P64NM-200W-004 and is intended for dimensional evaluation and preliminary integration. It is not a applicable manufacturing drawing, wiring definition, application approval, machinery risk assessment, safety validation or integration planning document. Before design freeze, machining, wiring or energization, verify all dimensions, tolerances, mounting and locating features, load boundaries, electrical interfaces, thermal conditions, cabling, grounding, protection, commissioning and applicable regulatory requirements against the applicable EmbodyStack engineering data for this exact SKU. Where this guide and applicable product documentation differ, the applicable product documentation governs. Validate the complete installed system under intended duty cycles, loads, accelerations, environmental conditions and credible fault cases.