

ENGINEERING DOCUMENTATION

Rotary Servo Motor

Dimensional & Integration Guide

DOCUMENT	REVISION / ISSUE	STATUS
DIG-ES-SM-A01-060S-T1P27NM-400W-002	DRAFT-08 / 27 Aug 2026	Engineering Integration Reference

Integration Overview

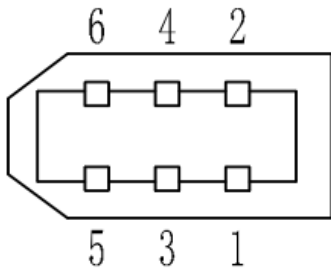
Closed-loop rotary servo motor for specified motion axes. This guide supports mechanical mounting, shaft and coupling integration, feedback and brake planning, cable routing, thermal validation and staged commissioning.

Key Integration Facts

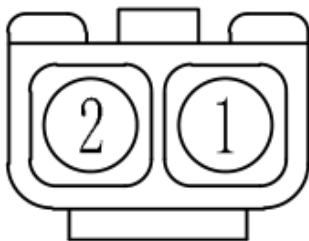
INTEGRATION ITEM	PUBLISHED VALUE
Rated Torque	1.27 N·m
Rated Speed	3000 rpm
Flange Size	60 mm

Product Structure & Views

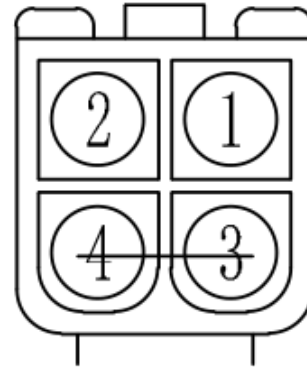
These views present product structure, mounting interfaces and relevant integration geometry for this SKU.



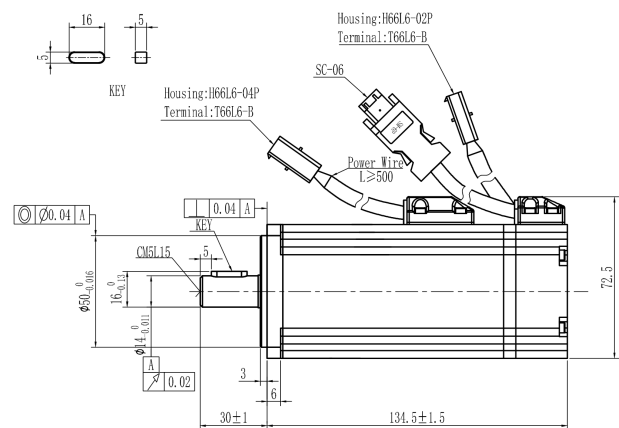
Mechanical View 2



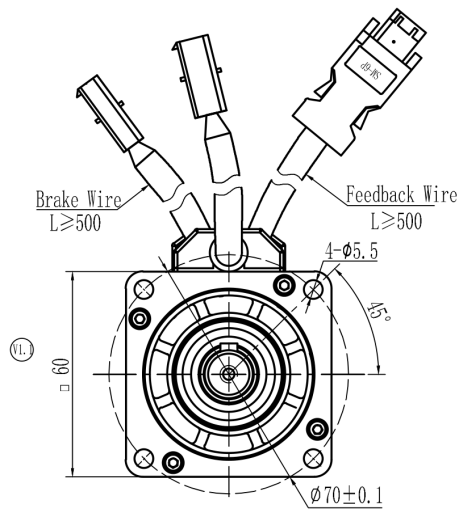
Mechanical View 6



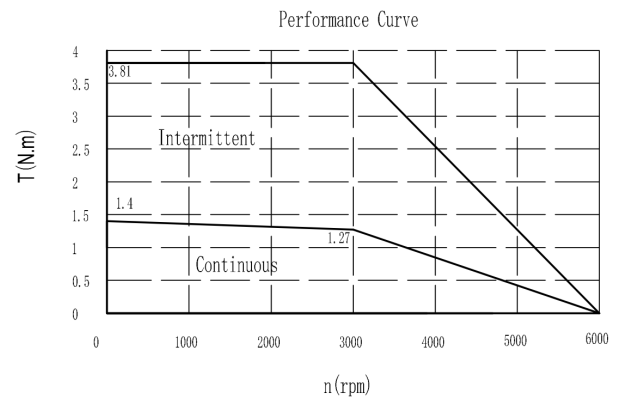
Mechanical View 4



Mechanical View 7



Mechanical View 8



Mechanical View 11

VIEW	FIELD	VALUE
Mechanical View 2	Pin number - top row left	Pin 6
	Pin number - top row center	Pin 4
	Pin number - top row right	Pin 2
	Pin number - bottom row left	Pin 5
	Pin number - bottom row center	Pin 3
	Pin number - bottom row right	Pin 1
Mechanical View 4	Connector Hole Position No.1	Hole 1
	Connector Hole Position No.2	Hole 2
	Connector Hole Position No.3	Hole 3
	Connector Hole Position No.4	Hole 4
Mechanical View 6	Connector Pin Number	Pin 2
	Connector Pin Number	Pin 1
Mechanical View 7	Power wire designation	Power Wire
	Power wire minimum length	≥500
	Shaft diameter	Ø50 0/-0.016
	Shaft extension length	16 0/-0.13
	Keyway hole diameter	Ø14 0/-0.011
	Keyway depth	5
	Shaft end face position tolerance	Position tolerance Ø0.04 relative to datum A
	Keyway perpendicularity tolerance	Perpendicularity 0.04 relative to datum A
	Datum A	Datum A
	Shaft end face runout	0.02
	Front mounting face width	3
	Front mounting face height	6
	Front section length	30±1
	Overall motor length	134.5±1.5
	Motor outer diameter	72.5
	Keyway depth or height	5 mm
	Keyway width	5 mm
Mechanical View 8	Feedback wire label	Feedback Wire
	Brake wire label	Brake Wire
	Feedback wire minimum length	L≥500
	Brake wire minimum length	L≥500
	Mounting hole diameter and quantity	4×Φ.5
	Square envelope dimension	160
	Flange bolt circle diameter	Ø0±0.1

VIEW	FIELD	VALUE
Drawing version	V1.1	
Hole angular distribution	45°	
Mechanical View 11	Chart title	Performance Curve
	Torque axis	Torque T in N.m
	Speed axis	Rotational speed n in rpm
	Torque scale values	Torque scale from 0 to 4 N.m in 0.5 increments
	Speed scale values	Speed scale from 0 to 6000 rpm in 1000 rpm increments
	Intermittent operating region	Intermittent operation curve region
	Continuous operating region	Continuous operation curve region
	Peak torque callout	3.81 N.m
	Continuous torque left callout	1.4 N.m
	Rated torque callout	1.27 N.m

Overall Dimensions and Mounting Interface

PARAMETER	PUBLISHED VALUE	UNIT
Flange Size	60	mm

- Confirm the mounting face, locating feature, shaft geometry, fastener engagement and removal clearance against the applicable exact-SKU drawing.
- Mount the motor on a flat, rigid interface and avoid using fasteners to pull a misaligned assembly into position.

Shaft, Coupling and Load Path

PARAMETER	PUBLISHED VALUE	UNIT
Rotor Inertia	0.384	kgcm ²

- Align the driven shaft and coupling before tightening; validate radial, axial and moment loads against applicable bearing-load data.
- Do not hammer, uncontrolled press-fit or transmit installation force through the motor bearings.

Electrical, Feedback and Brake Integration

PARAMETER	PUBLISHED VALUE	UNIT
Position Feedback Device	Single-turn communication magnetic encoder	

- Use only the current winding, feedback, brake and connector definitions for this exact SKU.
- Verify drive compatibility, polarity, current limits, feedback direction and brake sequencing before enabling torque.

Thermal, Duty and Environmental Conditions

PARAMETER	PUBLISHED VALUE	UNIT
Rated Torque	1.27	Nm
Operating Temperature	20 40	°C

- Validate winding and housing temperature under the installed duty cycle, ambient condition, mounting heat path and enclosure airflow.
- Published peak values are transient boundaries and must not be treated as continuous operating ratings.

Cable Routing, Grounding and EMC

PARAMETER	PUBLISHED VALUE	UNIT
Position Feedback Device	Single-turn communication magnetic encoder	

- Provide strain relief and bend radius through the full machine motion envelope.
- Separate motor power, brake and feedback wiring and terminate shields according to the specified system grounding architecture.

Commissioning and Motion Validation

PARAMETER	PUBLISHED VALUE	UNIT
Rated Speed	3000	rpm
Rated Torque	1.27	Nm

- Commission at low energy with the transmission unloaded or safely restrained, then confirm direction, feedback polarity, brake final integration, current limit and fault response.
- Validate the complete axis through intended acceleration, speed, load, stop and fault cycles during integration planning.

Integration Checklist

- | | |
|----|--|
| 01 | Confirm the exact SKU, 2D drawing and applicable wiring data. |
| 02 | Verify mounting, shaft, coupling, alignment, fasteners and removal clearance. |
| 03 | Validate radial and axial loads, inertia, acceleration and credible shock cases. |
| 04 | Confirm drive, winding, feedback, brake and connector compatibility. |
| 05 | Set current, speed, acceleration and thermal limits from the installed duty cycle. |
| 06 | Verify cable routing, shielding, grounding, strain relief and bend radius. |
| 07 | Commission at low energy before validating the full machine cycle. |

[View SKU Product Datasheet](#) [Request controlled 2D drawing](#) [Request controlled STEP review](#) [Request a Quote](#)

Engineering Use and Verification Notice

01. This Dimensional & Integration Guide applies only to EmbodyStack SKU ES-SM-A01-060S-T1P27NM-400W-002 and is intended for dimensional evaluation and preliminary integration. It is not a applicable manufacturing drawing, wiring definition, application approval, machinery risk assessment, safety validation or integration planning document. Before design freeze, machining, wiring or energization, verify all dimensions, tolerances, mounting and locating features, load boundaries, electrical interfaces, thermal conditions, cabling, grounding, protection, commissioning and applicable regulatory requirements against the applicable EmbodyStack engineering data for this exact SKU. Where this guide and applicable product documentation differ, the applicable product documentation governs. Validate the complete installed system under intended duty cycles, loads, accelerations, environmental conditions and credible fault cases.