ENGINEERING DOCUMENTATION

Rotary Servo Motor

Dimensional & Integration Guide

DOCUMENT	REVISION / ISSUE	STATUS
DIG-ES-SM-A01-130D-T14P33NM-3000W-006	DRAFT-08 / 27 Aug 2026	Engineering Integration Reference

Integration Overview

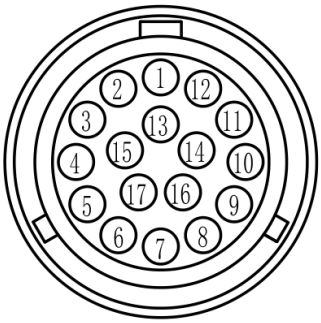
Closed-loop rotary servo motor for specified motion axes. This guide supports mechanical mounting, shaft and coupling integration, feedback and brake planning, cable routing, thermal validation and staged commissioning.

Key Integration Facts

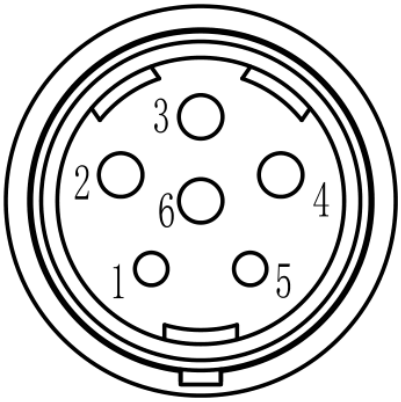
INTEGRATION ITEM	PUBLISHED VALUE
Rated Torque	14.33 N·m
Rated Speed	2000 rpm
Flange Size	130 mm

Product Structure & Views

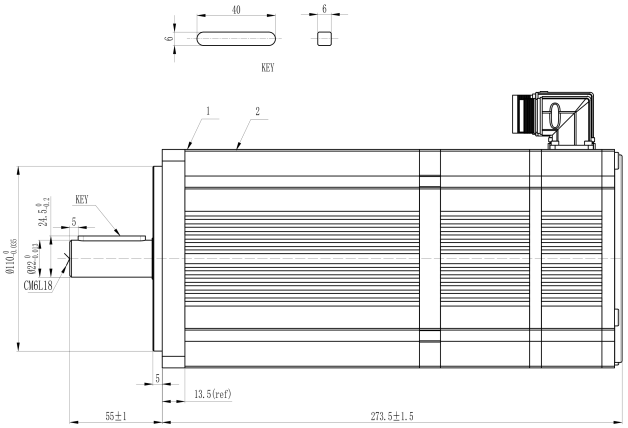
These views present product structure, mounting interfaces and relevant integration geometry for this SKU.



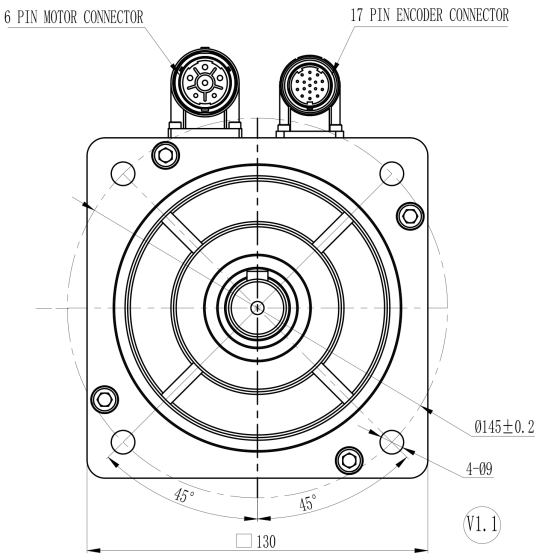
Mechanical View 3



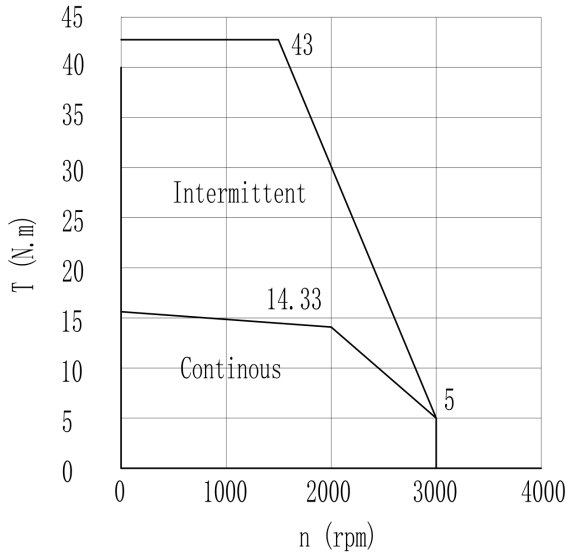
Mechanical View 5



Mechanical View 6



Mechanical View 7



Mechanical View 9

VIEW	FIELD	VALUE
Mechanical View 3	Pin number 1	Pin 1
	Pin number 12	Pin 12
	Pin number 2	Pin 2
	Pin number 3	Pin 3
	Pin number 13	Pin 13
	Pin number 15	Pin 15
	Pin number 14	Pin 14
	Pin number 10	Pin 10
	Pin number 4	Pin 4
	Pin number 16	Pin 16
	Pin number 17	Pin 17
	Pin number 9	Pin 9
	Pin number 5	Pin 5
	Pin number 8	Pin 8
	Pin number 6	Pin 6
	Pin number 7	Pin 7
	Pin number 11	Pin 11
	Connector pin label 1	Pin 1
Mechanical View 5	Connector pin number 3	Pin 3
	Connector pin number 4	Pin 4
	Connector pin number 6	Pin 6
	Connector pin number 1	Pin 1
	Connector pin number 5	Pin 5
	Connector pin number 2	Pin 2
Mechanical View 6	Keyway length	40 mm
	Keyway width	6 mm
	Keyway label	KEY
	Part number callout	2
	Part number callout	1
	Shaft section length	24.5 mm +0/-0.2
	Keyway depth	5 mm
	Mounting flange diameter	Φ10 mm +0/-0.035
	Shaft diameter	Φ2 mm +0/-0.013
	Radial offset	13.5 mm (reference)
	Front section length	55 mm ±1
	Overall length	273.5 mm ±1.5

VIEW	FIELD	VALUE
Mounting hole or feature dimension	5	
Mechanical View 7	6 PIN MOTOR CONNECTOR	6-pin motor connector
	17 PIN ENCODER CONNECTOR	17-pin encoder connector
	Mounting hole bolt circle diameter	Ø145±0.2 mm
	Mounting hole count and diameter	4 holes × Ø9 mm
	Mounting hole angular position 1	45°
	Mounting hole angular position 2	45°
	Square flange dimension	130 mm × 130 mm square
	Drawing version	V1.1
Mechanical View 9	Torque axis label	T (N.m)
	Intermittent operation maximum torque start	43 N.m
	Intermittent operation label	Intermittent
	Rated torque annotation	14.33 N.m
	Continuous operation label	Continuous
	Speed axis label	n (rpm)
	Torque scale values	0,5, 10, 15, 20, 25, 30, 35, 40, 45
	Speed scale values	0, 1000, 2000, 3000, 4000 rpm

Overall Dimensions and Mounting Interface

PARAMETER	PUBLISHED VALUE	UNIT
Flange Size	130	mm

- Confirm the mounting face, locating feature, shaft geometry, fastener engagement and removal clearance against the applicable exact-SKU drawing.
- Mount the motor on a flat, rigid interface and avoid using fasteners to pull a misaligned assembly into position.

Shaft, Coupling and Load Path

PARAMETER	PUBLISHED VALUE	UNIT
Rotor Inertia	31	kg·cm²

- Align the driven shaft and coupling before tightening; validate radial, axial and moment loads against applicable bearing-load data.
- Do not hammer, uncontrolled press-fit or transmit installation force through the motor bearings.

Electrical, Feedback and Brake Integration

PARAMETER	PUBLISHED VALUE	UNIT
Position Feedback Device	Single-turn communication optical encoder	

- Use only the current winding, feedback, brake and connector definitions for this exact SKU.
- Verify drive compatibility, polarity, current limits, feedback direction and brake sequencing before enabling torque.

Thermal, Duty and Environmental Conditions

PARAMETER	PUBLISHED VALUE	UNIT
Rated Torque	14.33	N·m
Operating Temperature	20 40	°C

- Validate winding and housing temperature under the installed duty cycle, ambient condition, mounting heat path and enclosure airflow.
- Published peak values are transient boundaries and must not be treated as continuous operating ratings.

Cable Routing, Grounding and EMC

PARAMETER	PUBLISHED VALUE	UNIT
Position Feedback Device	Single-turn communication optical encoder	

- Provide strain relief and bend radius through the full machine motion envelope.
- Separate motor power, brake and feedback wiring and terminate shields according to the specified system grounding architecture.

Commissioning and Motion Validation

PARAMETER	PUBLISHED VALUE	UNIT
Rated Speed	2000	rpm
Rated Torque	14.33	N·m

- Commission at low energy with the transmission unloaded or safely restrained, then confirm direction, feedback polarity, brake final integration, current limit and fault response.
- Validate the complete axis through intended acceleration, speed, load, stop and fault cycles during integration planning.

Integration Checklist

01	Confirm the exact SKU, 2D drawing and applicable wiring data.
02	Verify mounting, shaft, coupling, alignment, fasteners and removal clearance.
03	Validate radial and axial loads, inertia, acceleration and credible shock cases.
04	Confirm drive, winding, feedback, brake and connector compatibility.
05	Set current, speed, acceleration and thermal limits from the installed duty cycle.
06	Verify cable routing, shielding, grounding, strain relief and bend radius.
07	Commission at low energy before validating the full machine cycle.

View SKU Product Datasheet Request controlled 2D drawing Request controlled STEP review Request a Quote

Engineering Use and Verification Notice

01. This Dimensional & Integration Guide applies only to EmbodyStack SKU ES-SM-A01-130D-T14P33NM-3000W-006 and is intended for dimensional evaluation and preliminary integration. It is not a applicable manufacturing drawing, wiring definition, application approval, machinery risk assessment, safety validation or integration planning document. Before design freeze, machining, wiring or energization, verify all dimensions, tolerances, mounting and locating features, load boundaries, electrical interfaces, thermal conditions, cabling, grounding, protection, commissioning and applicable regulatory requirements against the applicable EmbodyStack engineering data for this exact SKU. Where this guide and applicable product documentation differ, the applicable product documentation governs. Validate the complete installed system under intended duty cycles, loads, accelerations, environmental conditions and credible fault cases.