

ENGINEERING DOCUMENTATION

Rotary Servo Motor

Dimensional & Integration Guide

DOCUMENT	REVISION / ISSUE	STATUS
DIG-ES-SM-A01-130D-T9P55NM-1000W-001	DRAFT-08 / 27 Aug 2026	Engineering Integration Reference

Integration Overview

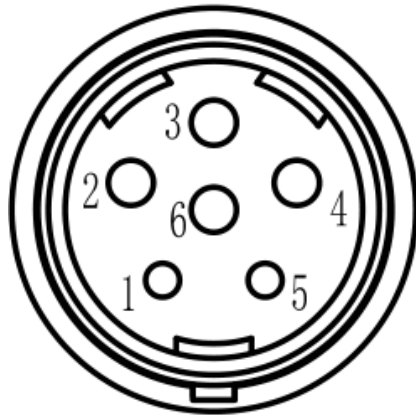
Closed-loop rotary servo motor for specified motion axes. This guide supports mechanical mounting, shaft and coupling integration, feedback and brake planning, cable routing, thermal validation and staged commissioning.

Key Integration Facts

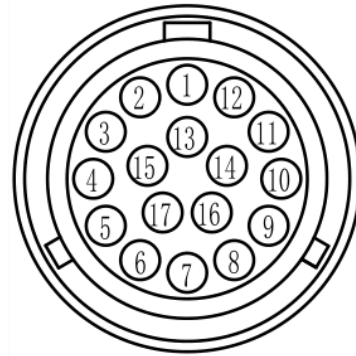
INTEGRATION ITEM	PUBLISHED VALUE
Rated Torque	9.55 N·m
Rated Speed	1000 rpm
Flange Size	130 mm

Product Structure & Views

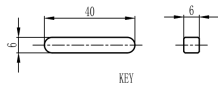
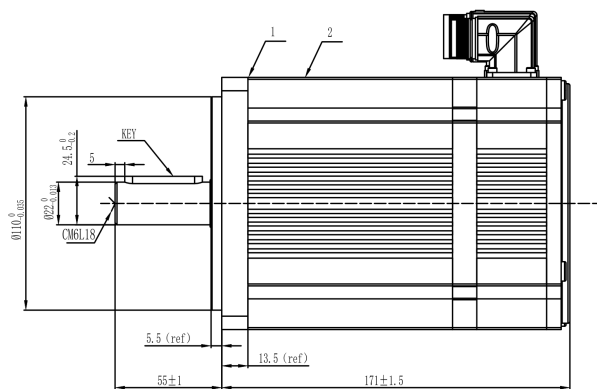
These views present product structure, mounting interfaces and relevant integration geometry for this SKU.



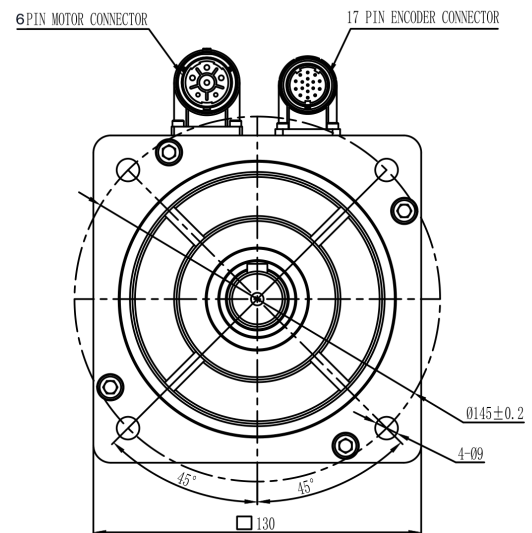
Mechanical View 3



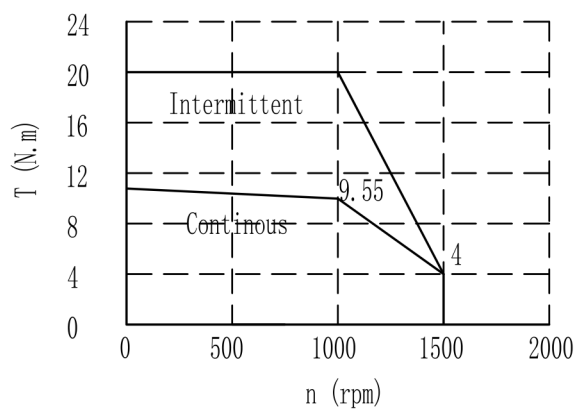
Mechanical View 4



Mechanical View 5



Mechanical View 6



Mechanical View 8

VIEW	FIELD	VALUE
Mechanical View 3	Connector pin label 1	Pin 1
	Connector pin label 2	Pin 2
	Connector pin label 3	Pin 3
	Connector pin label 4	Pin 4
	Connector pin label 5	Pin 5
	Connector pin label 6	Pin 6
Mechanical View 4	Connector face pin numbering	Visible connector face pin labels detected by OCR: 1, 2, 3, 4, 5, 6, 8, 9, 10, 12, 13, 14, 15, 16, 17. Pin count text is Not specified in OCR for this crop.
Mechanical View 5	Key length	Key length 40 mm
	Key width	Key width 6 mm
	Key thickness	Key thickness 6 mm
	Key label	Key feature identified
	Part callout 1	Item callout 1
	Part callout 2	Item callout 2
	Shaft keyway label	Shaft keyway feature identified
	Shaft shoulder dimension	24.5 mm, upper deviation 0, lower deviation -0.2
	Shaft keyway width	Keyway width 5 mm
	Shaft diameter	Diameter 22 mm, upper deviation 0, lower deviation -0.013
	Mounting pilot diameter	Diameter 110 mm, upper deviation 0, lower deviation -0.035
	Shaft end thread specification	CM6L18 thread callout
	Reference clearance dimension	5.5 mm reference
	Reference axial dimension	13.5 mm reference
	Motor body axial length	171 mm ±1.5
	Shaft extension length	55 mm ±1
Mechanical View 6	Encoder connector	17-pin encoder connector
	Motor connector	6-pin motor connector
	Mounting hole pitch circle diameter	Diameter 145 ±0.2
	Mounting hole quantity and diameter	4 holes, diameter 9
	Mounting hole angular position	Mounting holes located at 45 degrees from centerline on both sides
	Square flange outside dimension	Square 130
Mechanical View 8	Intermittent maximum torque	Intermittent torque region (upper curve)
	Continuous operating torque	Continuous torque region (lower curve)
	Rated torque at rated speed	9.55 N.m
	Curve endpoint torque	4 N.m
	Torque Scale	0-24 N.m
	Motor Speed Scale	0-2000 rpm

VIEW	FIELD	VALUE
X-axis label (Speed)	n (rpm)	
Y-axis label (Torque)	T (Nm)	

Overall Dimensions and Mounting Interface

PARAMETER	PUBLISHED VALUE	UNIT
Flange Size	130	mm

- Confirm the mounting face, locating feature, shaft geometry, fastener engagement and removal clearance against the applicable exact-SKU drawing.
- Mount the motor on a flat, rigid interface and avoid using fasteners to pull a misaligned assembly into position.

Shaft, Coupling and Load Path

PARAMETER	PUBLISHED VALUE	UNIT
Rotor Inertia	17.82	kgcm ²

- Align the driven shaft and coupling before tightening; validate radial, axial and moment loads against applicable bearing-load data.
- Do not hammer, uncontrolled press-fit or transmit installation force through the motor bearings.

Electrical, Feedback and Brake Integration

PARAMETER	PUBLISHED VALUE	UNIT
Position Feedback Device	Single-turn communication magnetic encoder	

- Use only the current winding, feedback, brake and connector definitions for this exact SKU.
- Verify drive compatibility, polarity, current limits, feedback direction and brake sequencing before enabling torque.

Thermal, Duty and Environmental Conditions

PARAMETER	PUBLISHED VALUE	UNIT
Rated Torque	9.55	Nm
Operating Temperature	20 40	°C

- Validate winding and housing temperature under the installed duty cycle, ambient condition, mounting heat path and enclosure airflow.
- Published peak values are transient boundaries and must not be treated as continuous operating ratings.

Cable Routing, Grounding and EMC

PARAMETER	PUBLISHED VALUE	UNIT
Position Feedback Device	Single-turn communication magnetic encoder	

- Provide strain relief and bend radius through the full machine motion envelope.
- Separate motor power, brake and feedback wiring and terminate shields according to the specified system grounding architecture.

Commissioning and Motion Validation

PARAMETER	PUBLISHED VALUE	UNIT
Rated Speed	1000	rpm
Rated Torque	9.55	Nm

- Commission at low energy with the transmission unloaded or safely restrained, then confirm direction, feedback polarity, brake final integration, current limit and fault response.
- Validate the complete axis through intended acceleration, speed, load, stop and fault cycles during integration planning.

Integration Checklist

- | | |
|----|--|
| 01 | Confirm the exact SKU, 2D drawing and applicable wiring data. |
| 02 | Verify mounting, shaft, coupling, alignment, fasteners and removal clearance. |
| 03 | Validate radial and axial loads, inertia, acceleration and credible shock cases. |
| 04 | Confirm drive, winding, feedback, brake and connector compatibility. |
| 05 | Set current, speed, acceleration and thermal limits from the installed duty cycle. |
| 06 | Verify cable routing, shielding, grounding, strain relief and bend radius. |
| 07 | Commission at low energy before validating the full machine cycle. |

[View SKU Product Datasheet](#) [Request controlled 2D drawing](#) [Request controlled STEP review](#) [Request a Quote](#)

Engineering Use and Verification Notice

01. This Dimensional & Integration Guide applies only to EmbodyStack SKU ES-SM-A01-130D-T9P55NM-1000W-001 and is intended for dimensional evaluation and preliminary integration. It is not a applicable manufacturing drawing, wiring definition, application approval, machinery risk assessment, safety validation or integration planning document. Before design freeze, machining, wiring or energization, verify all dimensions, tolerances, mounting and locating features, load boundaries, electrical interfaces, thermal conditions, cabling, grounding, protection, commissioning and applicable regulatory requirements against the applicable EmbodyStack engineering data for this exact SKU. Where this guide and applicable product documentation differ, the applicable product documentation governs. Validate the complete installed system under intended duty cycles, loads, accelerations, environmental conditions and credible fault cases.