

ENGINEERING DOCUMENTATION

# Rotary Servo Motor

## Dimensional & Integration Guide

| DOCUMENT                             | REVISION / ISSUE       | STATUS                            |
|--------------------------------------|------------------------|-----------------------------------|
| DIG-ES-SM-A01-130D-T9P55NM-2000W-002 | DRAFT-08 / 27 Aug 2026 | Engineering Integration Reference |

### Integration Overview

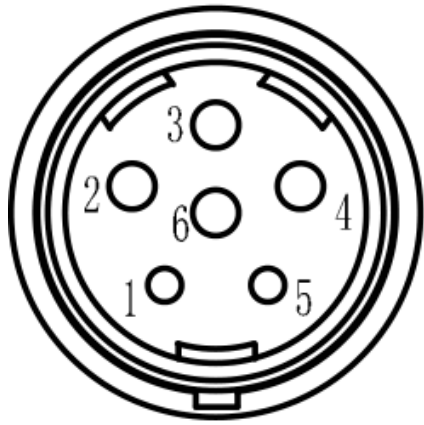
Closed-loop rotary servo motor for specified motion axes. This guide supports mechanical mounting, shaft and coupling integration, feedback and brake planning, cable routing, thermal validation and staged commissioning.

### Key Integration Facts

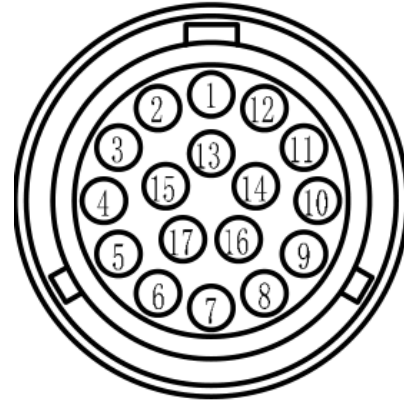
| INTEGRATION ITEM | PUBLISHED VALUE |
|------------------|-----------------|
| Rated Torque     | 9.55 N·m        |
| Rated Speed      | 2000 rpm        |
| Flange Size      | 130 mm          |

## Product Structure & Views

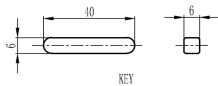
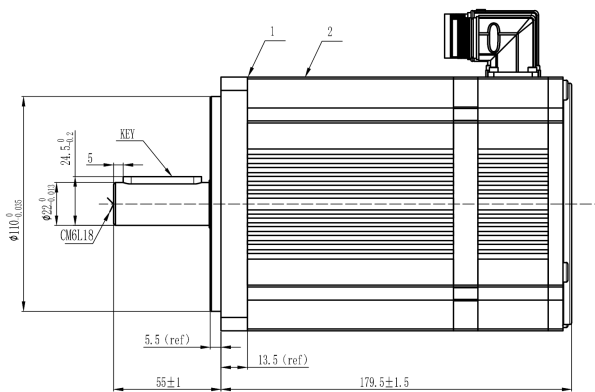
These views present product structure, mounting interfaces and relevant integration geometry for this SKU.



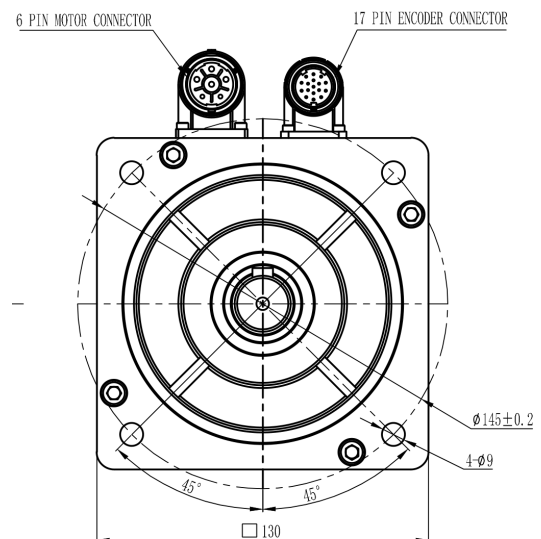
Mechanical View 4



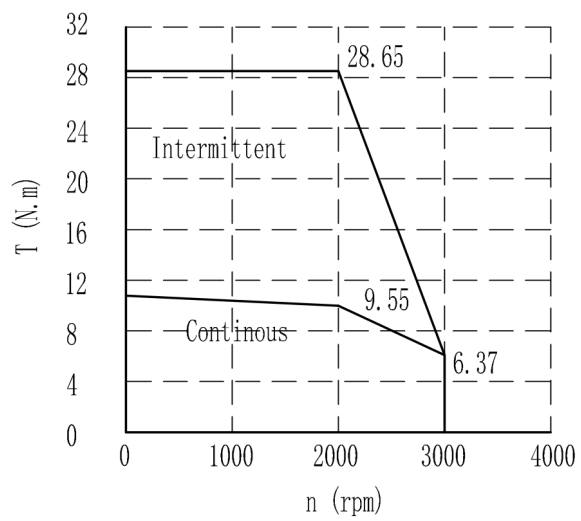
Mechanical View 5



Mechanical View 6



Mechanical View 7



Mechanical View 9

| VIEW              | FIELD                                        | VALUE               |
|-------------------|----------------------------------------------|---------------------|
| Mechanical View 4 | Pin 1 number                                 | Pin 1               |
|                   | Pin 2 number                                 | Pin 2               |
|                   | Pin 3 number                                 | Pin 3               |
|                   | Pin 4 number                                 | Pin 4               |
|                   | Pin 5 number                                 | Pin 5               |
|                   | Pin 6 number                                 | Pin 6               |
| Mechanical View 5 | Pin 1                                        | Pin 1               |
|                   | Pin 2                                        | Pin 2               |
|                   | Pin 3                                        | Pin 3               |
|                   | Pin 4                                        | Pin 4               |
|                   | Pin 5                                        | Pin 5               |
|                   | Pin 6                                        | Pin 6               |
|                   | Pin 7                                        | Pin 7               |
|                   | Pin 8                                        | Pin 8               |
|                   | Pin 9                                        | Pin 9               |
|                   | Pin 10                                       | Pin 10              |
|                   | Pin 11                                       | Pin 11              |
|                   | Pin 12                                       | Pin 12              |
|                   | Pin 13                                       | Pin 13              |
|                   | Pin 14                                       | Pin 14              |
|                   | Pin 15                                       | Pin 15              |
|                   | Pin 16                                       | Pin 16              |
|                   | Pin 17                                       | Pin 17              |
| Mechanical View 6 | Key length                                   | 40 mm               |
|                   | Key width                                    | 6 mm                |
|                   | Key depth                                    | 6 mm                |
|                   | Key label                                    | KEY                 |
|                   | Position marker 2                            | 2                   |
|                   | Position marker 1                            | 1                   |
|                   | Shaft length with negative tolerance         | 24.5 0/-0.2 mm      |
|                   | Key depth                                    | 5 mm                |
|                   | Shaft diameter with negative tolerance       | ∅20 0/-0.013 mm     |
|                   | Motor outer diameter with negative tolerance | ∅10 0/-0.035 mm     |
|                   | Front end reference dimension                | 5.5 mm (reference)  |
|                   | Connector mounting reference dimension       | 13.5 mm (reference) |
|                   | Front section total length                   | 55±1 mm             |

| VIEW               | FIELD                                      | VALUE                                           |
|--------------------|--------------------------------------------|-------------------------------------------------|
| Motor total length | 179.5±1.5 mm                               |                                                 |
| Mechanical View 7  | 17-pin encoder connector                   | 17-pin encoder connector                        |
|                    | 6-pin motor connector                      | 6-pin motor connector                           |
|                    | Mounting hole bolt circle diameter         | Φ45 ±0.2 mm                                     |
|                    | Mounting hole quantity and diameter        | 4 holes × Φ mm                                  |
|                    | Mounting hole angular position             | 45° (from horizontal centerline)                |
|                    | Mounting hole angular position             | 45° (from horizontal centerline, opposite side) |
|                    | Envelope square dimension                  | 130 × 130 mm square                             |
| Mechanical View 9  | Y-axis maximum torque value                | 32 N.m                                          |
|                    | Intermittent operation maximum torque      | 28.65 N.m                                       |
|                    | Y-axis scale value                         | 28 N.m                                          |
|                    | Y-axis scale value                         | 24 N.m                                          |
|                    | Operation mode label                       | Intermittent operation mode                     |
|                    | Y-axis scale value                         | 20 N.m                                          |
|                    | Y-axis scale value                         | 16 N.m                                          |
|                    | Y-axis label                               | Torque in Newton-meters                         |
|                    | Y-axis scale value                         | 12 N.m                                          |
|                    | Continuous operation maximum torque        | 9.55 N.m                                        |
|                    | Y-axis scale value                         | 8 N.m                                           |
|                    | Operation mode label                       | Continuous operation mode                       |
|                    | Continuous operation torque endpoint value | 6.37 N.m                                        |
|                    | Y-axis scale value                         | 4 N.m                                           |
|                    | Y-axis origin value                        | 0 N.m                                           |
|                    | X-axis origin value                        | 0 rpm                                           |
|                    | X-axis scale value                         | 1000 rpm                                        |
|                    | X-axis scale value                         | 2000 rpm                                        |
|                    | X-axis scale value                         | 3000 rpm                                        |
|                    | X-axis scale value                         | 4000 rpm                                        |
|                    | X-axis label                               | Speed in revolutions per minute                 |

## Overall Dimensions and Mounting Interface

| PARAMETER   | PUBLISHED VALUE | UNIT |
|-------------|-----------------|------|
| Flange Size | 130             | mm   |

- Confirm the mounting face, locating feature, shaft geometry, fastener engagement and removal clearance against the applicable exact-SKU drawing.
- Mount the motor on a flat, rigid interface and avoid using fasteners to pull a misaligned assembly into position.

## Shaft, Coupling and Load Path

| PARAMETER     | PUBLISHED VALUE | UNIT              |
|---------------|-----------------|-------------------|
| Rotor Inertia | 20.25           | kgcm <sup>2</sup> |

- Align the driven shaft and coupling before tightening; validate radial, axial and moment loads against applicable bearing-load data.
- Do not hammer, uncontrolled press-fit or transmit installation force through the motor bearings.

## Electrical, Feedback and Brake Integration

| PARAMETER                | PUBLISHED VALUE                            | UNIT |
|--------------------------|--------------------------------------------|------|
| Position Feedback Device | Single-turn communication magnetic encoder |      |

- Use only the current winding, feedback, brake and connector definitions for this exact SKU.
- Verify drive compatibility, polarity, current limits, feedback direction and brake sequencing before enabling torque.

## Thermal, Duty and Environmental Conditions

| PARAMETER             | PUBLISHED VALUE | UNIT |
|-----------------------|-----------------|------|
| Rated Torque          | 9.55            | Nm   |
| Operating Temperature | 20 40           | °C   |

- Validate winding and housing temperature under the installed duty cycle, ambient condition, mounting heat path and enclosure airflow.
- Published peak values are transient boundaries and must not be treated as continuous operating ratings.

## Cable Routing, Grounding and EMC

| PARAMETER                | PUBLISHED VALUE                            | UNIT |
|--------------------------|--------------------------------------------|------|
| Position Feedback Device | Single-turn communication magnetic encoder |      |

- Provide strain relief and bend radius through the full machine motion envelope.
- Separate motor power, brake and feedback wiring and terminate shields according to the specified system grounding architecture.

## Commissioning and Motion Validation

| PARAMETER    | PUBLISHED VALUE | UNIT |
|--------------|-----------------|------|
| Rated Speed  | 2000            | rpm  |
| Rated Torque | 9.55            | Nm   |

- Commission at low energy with the transmission unloaded or safely restrained, then confirm direction, feedback polarity, brake final integration, current limit and fault response.
- Validate the complete axis through intended acceleration, speed, load, stop and fault cycles during integration planning.

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## Integration Checklist

- |    |                                                                                    |
|----|------------------------------------------------------------------------------------|
| 01 | Confirm the exact SKU, 2D drawing and applicable wiring data.                      |
| 02 | Verify mounting, shaft, coupling, alignment, fasteners and removal clearance.      |
| 03 | Validate radial and axial loads, inertia, acceleration and credible shock cases.   |
| 04 | Confirm drive, winding, feedback, brake and connector compatibility.               |
| 05 | Set current, speed, acceleration and thermal limits from the installed duty cycle. |
| 06 | Verify cable routing, shielding, grounding, strain relief and bend radius.         |
| 07 | Commission at low energy before validating the full machine cycle.                 |

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[View SKU Product Datasheet](#)   [Request controlled 2D drawing](#)   [Request controlled STEP review](#)   [Request a Quote](#)

### Engineering Use and Verification Notice

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**01.** This Dimensional & Integration Guide applies only to EmbodyStack SKU ES-SM-A01-130D-T9P55NM-2000W-002 and is intended for dimensional evaluation and preliminary integration. It is not a applicable manufacturing drawing, wiring definition, application approval, machinery risk assessment, safety validation or integration planning document. Before design freeze, machining, wiring or energization, verify all dimensions, tolerances, mounting and locating features, load boundaries, electrical interfaces, thermal conditions, cabling, grounding, protection, commissioning and applicable regulatory requirements against the applicable EmbodyStack engineering data for this exact SKU. Where this guide and applicable product documentation differ, the applicable product documentation governs. Validate the complete installed system under intended duty cycles, loads, accelerations, environmental conditions and credible fault cases.