

ENGINEERING DOCUMENTATION

# Rotary Servo Motor

## Dimensional & Integration Guide

| DOCUMENT                          | REVISION / ISSUE       | STATUS                            |
|-----------------------------------|------------------------|-----------------------------------|
| DIG-ES-SM-A02-110D-T4NM-1250W-002 | DRAFT-08 / 27 Aug 2026 | Engineering Integration Reference |

### Integration Overview

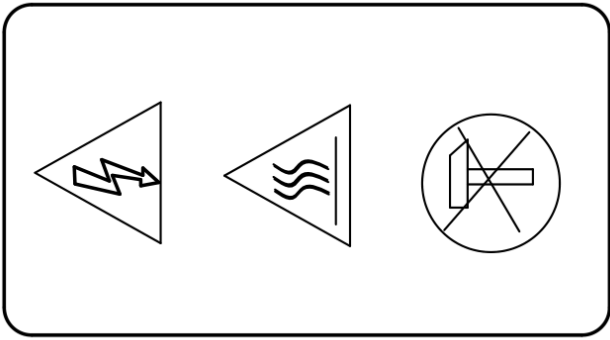
Closed-loop rotary servo motor for specified motion axes. This guide supports mechanical mounting, shaft and coupling integration, feedback and brake planning, cable routing, thermal validation and staged commissioning.

### Key Integration Facts

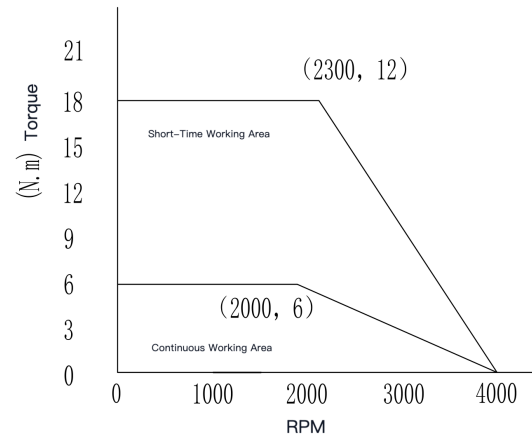
| INTEGRATION ITEM | PUBLISHED VALUE |
|------------------|-----------------|
| Rated Torque     | 4 Nm            |
| Rated Speed      | 2000 rpm        |
| Flange Size      | 110 mm          |

These views present product structure, mounting interfaces and relevant integration geometry for this SKU.





Mechanical View 7



Mechanical View 9

| VIEW              | FIELD                                | VALUE                                              |
|-------------------|--------------------------------------|----------------------------------------------------|
| Mechanical View 1 | Mounting flange square dimension     | 110                                                |
|                   | Mounting hole quantity and diameter  | 4- $\varnothing$                                   |
|                   | Mounting hole pitch circle diameter  | $\varnothing 30 \pm 0.1$                           |
|                   | Mounting hole angular distribution   | 45°                                                |
|                   | Signal connector location identifier | Signal Connector                                   |
|                   | Power connector location identifier  | Power Connector                                    |
|                   | Mounting hole angular position       | 45°                                                |
| Mechanical View 2 | Shaft diameter                       | $\varnothing$                                      |
|                   | Shaft extension length               | 6 mm                                               |
|                   | Main shaft length                    | 32 mm                                              |
|                   | Keyway designation                   | Keyway present                                     |
|                   | Keyway depth                         | 3 mm                                               |
|                   | Key type designation                 | CM6L25                                             |
|                   | Mounting flange diameter             | $\varnothing 50 / -0.035$ mm                       |
|                   | Main shaft diameter                  | $\varnothing 9 / -0.013$ mm                        |
|                   | Mounting face depth                  | 38±1 mm                                            |
|                   | End face step height                 | 3 mm                                               |
|                   | Flange width                         | 11 mm                                              |
|                   | Motor overall length                 | 228±1 mm                                           |
|                   | Maximum outer diameter               | 135 mm maximum                                     |
| Mechanical View 4 | Connector Pin 1 Position Marker      | Pin 1                                              |
|                   | Connector Pin 2 Position Marker      | Pin 2                                              |
|                   | Connector Pin 3 Position Marker      | Pin 3                                              |
|                   | Connector Pin 4 Position Marker      | Pin 4                                              |
|                   | Connector Pin 5 Position Marker      | Pin 5                                              |
|                   | Connector Pin 6 Position Marker      | Pin 6                                              |
| Mechanical View 6 | Connector pin label 1-17             | Pin 1-17                                           |
| Mechanical View 9 | Short-time operating curve point     | Speed 2300 rpm, torque 12 N.m                      |
|                   | Torque axis label                    | Torque in N.m                                      |
|                   | Short-time working area label        | Short-Time Working Area                            |
|                   | Torque scale values                  | Torque scale ticks: 0, 3, 6, 9, 12, 15, 18, 21 N.m |
|                   | Continuous operating curve point     | Speed 2000 rpm, torque 6 N.m                       |
|                   | Continuous working area label        | Continuous Working Area                            |
|                   | Speed scale values                   | Speed scale ticks: 0, 1000, 2000, 3000, 4000 rpm   |
|                   | Speed axis label                     | Speed in rpm                                       |

## Overall Dimensions and Mounting Interface

| PARAMETER   | PUBLISHED VALUE | UNIT |
|-------------|-----------------|------|
| Flange Size | 110             | mm   |

- Confirm the mounting face, locating feature, shaft geometry, fastener engagement and removal clearance against the applicable exact-SKU drawing.
- Mount the motor on a flat, rigid interface and avoid using fasteners to pull a misaligned assembly into position.

## Shaft, Coupling and Load Path

| PARAMETER     | PUBLISHED VALUE | UNIT              |
|---------------|-----------------|-------------------|
| Rotor Inertia | 5.85            | kgcm <sup>2</sup> |

- Align the driven shaft and coupling before tightening; validate radial, axial and moment loads against applicable bearing-load data.
- Do not hammer, uncontrolled press-fit or transmit installation force through the motor bearings.

## Electrical, Feedback and Brake Integration

| PARAMETER                | PUBLISHED VALUE              | UNIT |
|--------------------------|------------------------------|------|
| Position Feedback Device | 2500 PPR incremental encoder |      |

- Use only the current winding, feedback, brake and connector definitions for this exact SKU.
- Verify drive compatibility, polarity, current limits, feedback direction and brake sequencing before enabling torque.

## Thermal, Duty and Environmental Conditions

| PARAMETER             | PUBLISHED VALUE | UNIT |
|-----------------------|-----------------|------|
| Rated Torque          | 4               | Nm   |
| Operating Temperature | 20 40           | °C   |

- Validate winding and housing temperature under the installed duty cycle, ambient condition, mounting heat path and enclosure airflow.
- Published peak values are transient boundaries and must not be treated as continuous operating ratings.

## Cable Routing, Grounding and EMC

| PARAMETER                | PUBLISHED VALUE              | UNIT |
|--------------------------|------------------------------|------|
| Position Feedback Device | 2500 PPR incremental encoder |      |

- Provide strain relief and bend radius through the full machine motion envelope.
- Separate motor power, brake and feedback wiring and terminate shields according to the specified system grounding architecture.

## Commissioning and Motion Validation

| PARAMETER    | PUBLISHED VALUE | UNIT |
|--------------|-----------------|------|
| Rated Speed  | 2000            | rpm  |
| Rated Torque | 4               | Nm   |

- Commission at low energy with the transmission unloaded or safely restrained, then confirm direction, feedback polarity, brake final integration, current limit and fault response.
- Validate the complete axis through intended acceleration, speed, load, stop and fault cycles during integration planning.

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## Integration Checklist

- |    |                                                                                    |
|----|------------------------------------------------------------------------------------|
| 01 | Confirm the exact SKU, 2D drawing and applicable wiring data.                      |
| 02 | Verify mounting, shaft, coupling, alignment, fasteners and removal clearance.      |
| 03 | Validate radial and axial loads, inertia, acceleration and credible shock cases.   |
| 04 | Confirm drive, winding, feedback, brake and connector compatibility.               |
| 05 | Set current, speed, acceleration and thermal limits from the installed duty cycle. |
| 06 | Verify cable routing, shielding, grounding, strain relief and bend radius.         |
| 07 | Commission at low energy before validating the full machine cycle.                 |

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[View SKU Product Datasheet](#)   [Request controlled 2D drawing](#)   [Request controlled STEP review](#)   [Request a Quote](#)

### Engineering Use and Verification Notice

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**01.** This Dimensional & Integration Guide applies only to EmbodyStack SKU ES-SM-A02-110D-T4NM-1250W-002 and is intended for dimensional evaluation and preliminary integration. It is not a applicable manufacturing drawing, wiring definition, application approval, machinery risk assessment, safety validation or integration planning document. Before design freeze, machining, wiring or energization, verify all dimensions, tolerances, mounting and locating features, load boundaries, electrical interfaces, thermal conditions, cabling, grounding, protection, commissioning and applicable regulatory requirements against the applicable EmbodyStack engineering data for this exact SKU. Where this guide and applicable product documentation differ, the applicable product documentation governs. Validate the complete installed system under intended duty cycles, loads, accelerations, environmental conditions and credible fault cases.