

ENGINEERING DOCUMENTATION

Rotary Servo Motor

Dimensional & Integration Guide

DOCUMENT	REVISION / ISSUE	STATUS
DIG-ES-SM-A02-130D-T14P3NM-3000W-002	DRAFT-08 / 27 Aug 2026	Engineering Integration Reference

Integration Overview

Closed-loop rotary servo motor for specified motion axes. This guide supports mechanical mounting, shaft and coupling integration, feedback and brake planning, cable routing, thermal validation and staged commissioning.

Key Integration Facts

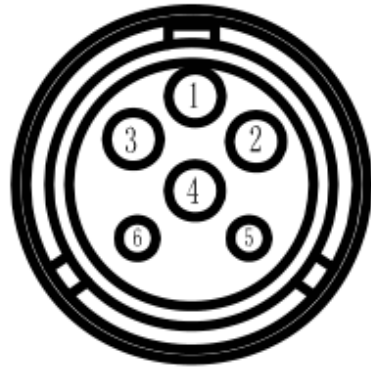
INTEGRATION ITEM	PUBLISHED VALUE
Rated Torque	14.3 N·m
Rated Speed	2000 rpm
Flange Size	130 mm

Product Structure & Views

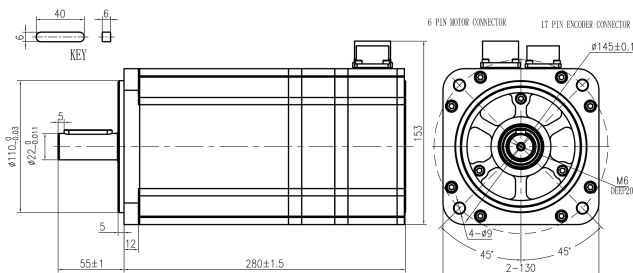
These views present product structure, mounting interfaces and relevant integration geometry for this SKU.



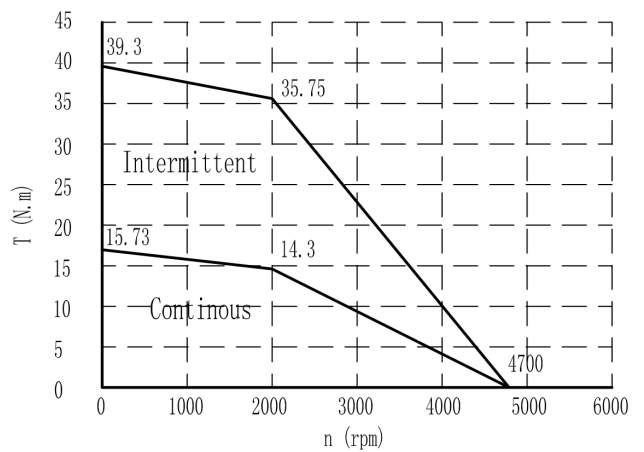
Mechanical View 3



Mechanical View 5



Mechanical View 7



Mechanical View 8

VIEW	FIELD	VALUE
Mechanical View 3	Connector pin label 1-17	Pin 1-17
Mechanical View 5	Pin numbering layout	Six visible pin identifiers arranged on connector front face: top 1, upper right 2, upper left 3, center 4, lower right 5, lower left 6.
Mechanical View 7	Key width	Key width 6 mm
	Key length	Key length 40 mm
	Key height	Key height 6 mm
	Key feature label	Key feature present
	Local shaft/key shoulder length	Local length 5 mm
	Shaft step local length	Local step length 5 mm
	Shaft end diameter	Diameter 22 mm, tolerance +0/-0.011 mm
	Pilot or shaft interface diameter	Diameter 110 mm, tolerance +0/-0.03 mm
	Front shaft extension length	Length 55 mm ±1 mm
	Front flange step length	Step length 12 mm
	Motor body length	Body length 280 mm ±1.5 mm
	Motor body height	Overall body height 153 mm
	Motor connector	6-pin motor connector
	Encoder connector	17-pin encoder connector
	Flange outside diameter	Diameter 145 mm ±0.1 mm
	Threaded hole size and depth	M6 threaded holes, depth 20 mm
	Mounting through-hole quantity and diameter	4 holes, diameter 9 mm
	Mounting hole center spacing	Two-axis mounting hole spacing 130 mm
	Mounting hole angular position	Angular position 45 degrees
Mechanical View 8	Torque axis label	T(N.m)
	Intermittent operation starting torque	39.3 N.m
	Intermittent operation mid-point torque	35.75 N.m
	Continuous operation starting torque	15.73 N.m
	Continuous operation mid-point torque	14.3 N.m
	Maximum speed	4700 rpm
	Intermittent operation zone label	Intermittent
	Continuous operation zone label	Continuous
	Torque Scale	0-45 N.m
	Motor Speed Scale	0-6000 rpm
	Speed axis label	Rotational speed n in rpm

Overall Dimensions and Mounting Interface

PARAMETER	PUBLISHED VALUE	UNIT
Flange Size	130	mm

- Confirm the mounting face, locating feature, shaft geometry, fastener engagement and removal clearance against the applicable exact-SKU drawing.
- Mount the motor on a flat, rigid interface and avoid using fasteners to pull a misaligned assembly into position.

Shaft, Coupling and Load Path

PARAMETER	PUBLISHED VALUE	UNIT
Rotor Inertia	34.9	kgcm ²

- Align the driven shaft and coupling before tightening; validate radial, axial and moment loads against applicable bearing-load data.
- Do not hammer, uncontrolled press-fit or transmit installation force through the motor bearings.

Electrical, Feedback and Brake Integration

PARAMETER	PUBLISHED VALUE	UNIT
Position Feedback Device	2500 PPR incremental encoder	

- Use only the current winding, feedback, brake and connector definitions for this exact SKU.
- Verify drive compatibility, polarity, current limits, feedback direction and brake sequencing before enabling torque.

Thermal, Duty and Environmental Conditions

PARAMETER	PUBLISHED VALUE	UNIT
Rated Torque	14.3	Nm
Operating Temperature	20 40	°C

- Validate winding and housing temperature under the installed duty cycle, ambient condition, mounting heat path and enclosure airflow.
- Published peak values are transient boundaries and must not be treated as continuous operating ratings.

Cable Routing, Grounding and EMC

PARAMETER	PUBLISHED VALUE	UNIT
Position Feedback Device	2500 PPR incremental encoder	

- Provide strain relief and bend radius through the full machine motion envelope.
- Separate motor power, brake and feedback wiring and terminate shields according to the specified system grounding architecture.

Commissioning and Motion Validation

PARAMETER	PUBLISHED VALUE	UNIT
Rated Speed	2000	rpm
Rated Torque	14.3	Nm

- Commission at low energy with the transmission unloaded or safely restrained, then confirm direction, feedback polarity, brake final integration, current limit and fault response.
- Validate the complete axis through intended acceleration, speed, load, stop and fault cycles during integration planning.

Integration Checklist

- | | |
|----|--|
| 01 | Confirm the exact SKU, 2D drawing and applicable wiring data. |
| 02 | Verify mounting, shaft, coupling, alignment, fasteners and removal clearance. |
| 03 | Validate radial and axial loads, inertia, acceleration and credible shock cases. |
| 04 | Confirm drive, winding, feedback, brake and connector compatibility. |
| 05 | Set current, speed, acceleration and thermal limits from the installed duty cycle. |
| 06 | Verify cable routing, shielding, grounding, strain relief and bend radius. |
| 07 | Commission at low energy before validating the full machine cycle. |

[View SKU Product Datasheet](#) [Request controlled 2D drawing](#) [Request controlled STEP review](#) [Request a Quote](#)

Engineering Use and Verification Notice

01. This Dimensional & Integration Guide applies only to EmbodyStack SKU ES-SM-A02-130D-T14P3NM-3000W-002 and is intended for dimensional evaluation and preliminary integration. It is not a applicable manufacturing drawing, wiring definition, application approval, machinery risk assessment, safety validation or integration planning document. Before design freeze, machining, wiring or energization, verify all dimensions, tolerances, mounting and locating features, load boundaries, electrical interfaces, thermal conditions, cabling, grounding, protection, commissioning and applicable regulatory requirements against the applicable EmbodyStack engineering data for this exact SKU. Where this guide and applicable product documentation differ, the applicable product documentation governs. Validate the complete installed system under intended duty cycles, loads, accelerations, environmental conditions and credible fault cases.