

ENGINEERING DOCUMENTATION

Rotary Servo Motor

Dimensional & Integration Guide

DOCUMENT	REVISION / ISSUE	STATUS
DIG-ES-SM-A03-060D-TOP64NM-200W-002	DRAFT-08 / 27 Aug 2026	Engineering Integration Reference

Integration Overview

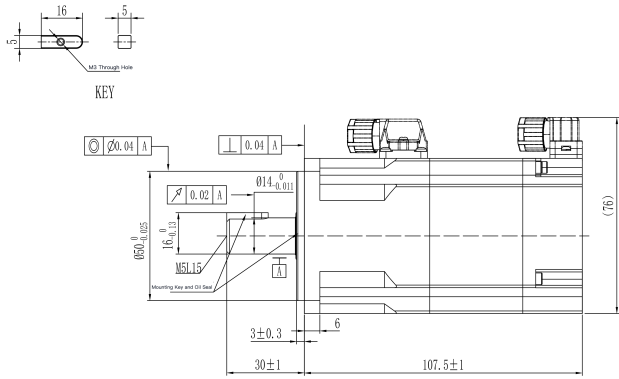
Closed-loop rotary servo motor for specified motion axes. This guide supports mechanical mounting, shaft and coupling integration, feedback and brake planning, cable routing, thermal validation and staged commissioning.

Key Integration Facts

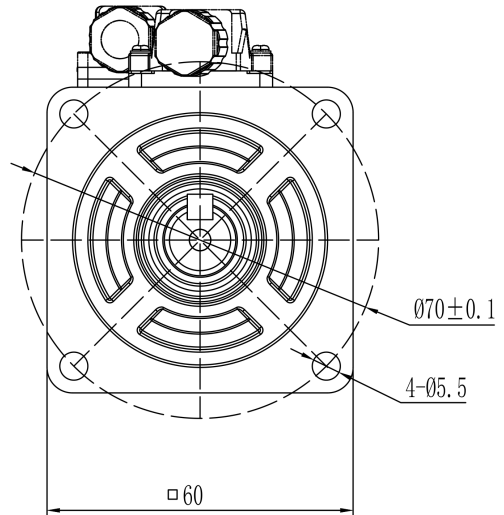
INTEGRATION ITEM	PUBLISHED VALUE
Rated Torque	0.64 Nm
Rated Speed	3000 rpm
Rated Voltage	220 VAC
Flange Size	60 mm

Product Structure & Views

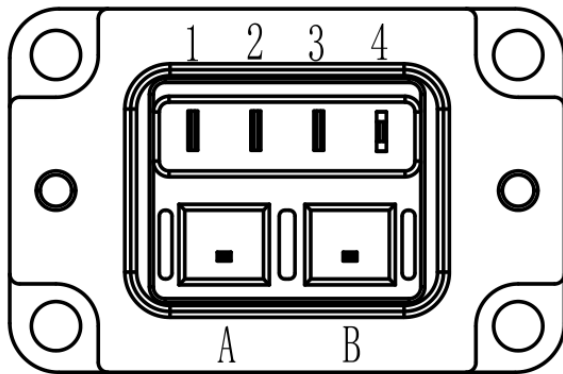
These views present product structure, mounting interfaces and relevant integration geometry for this SKU.



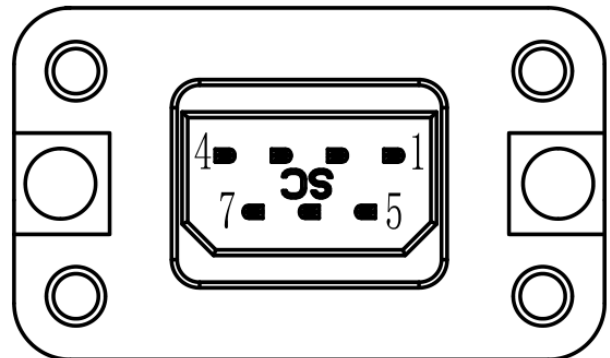
Mechanical View 1



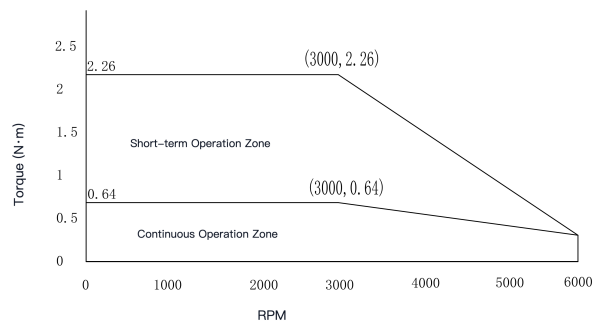
Mechanical View 2



Mechanical View 5



Mechanical View 8



Mechanical View 11

VIEW	FIELD	VALUE
Mechanical View 1	Key slot length	16 mm
	Key slot width or height	5 mm
	M3 through hole	M3 through hole
	Key label	Key feature
	Perpendicularity tolerance to datum A	Perpendicularity 0.04 to datum A
	Geometric tolerance with diameter zone to datum A	Geometric tolerance diameter 0.04 to datum A
	Shaft diameter	Diameter 14 mm, upper deviation 0, lower deviation -0.011
	Runout-style geometric tolerance to datum A	Runout-style tolerance 0.02 to datum A
	Reference envelope height	Reference dimension 76 mm
	Diameter 50 feature	Diameter 50 mm, upper deviation 0, lower deviation -0.025
	Keyway dimension	16 mm, upper deviation 0, lower deviation -0.13
	M5 L15 mounting key/oil seal callout	M5, length/depth 15
	Datum A	Datum A
	Mounting key and oil seal note	Mounting key and oil seal
	Local mounting offset	6 mm
	Local mounting dimension	3 mm ±0.3
	Main body length	107.5 mm ±1
	Mounting end axial length	30 mm ±1
	Key Width	5 mm
Mechanical View 2	Outer diameter	Ø70 ±0.1 mm
	Mounting hole diameter	4 × Ø5.5 mm
	Square side length	160 mm
Mechanical View 5	pin number	Pin 1
	pin number	Pin 2
	pin number	Pin 3
	pin number	Pin 4
	terminal designation	A
	terminal designation	B
Mechanical View 8	Visible feedback connector pinout markings	Visible connector markings: 4, 7, 1, 5
Mechanical View 11	Y-axis torque	Torque axis, unit Nm
	X-axis speed	Rotational speed axis, unit rpm
	Short-term operation zone	Short-term operation zone in torque-speed curve
	Continuous operation zone	Continuous operation zone in torque-speed curve
	Short-term curve point	Speed 3000 rpm, torque 2.26 Nm
	Continuous curve point	Speed 3000 rpm, torque 0.64 Nm

VIEW	FIELD	VALUE
Torque scale ticks	Y-axis torque tick values: 0, 0.5, 0.64, 1, 1.5, 2, 2.26, 2.5 Nm	
Speed scale ticks	X-axis speed tick values: 0, 1000, 2000, 3000, 4000, 5000, 6000 rpm	

Overall Dimensions and Mounting Interface

PARAMETER	PUBLISHED VALUE	UNIT
Flange Size	60	mm

- Confirm the mounting face, locating feature, shaft geometry, fastener engagement and removal clearance against the applicable exact-SKU drawing.
- Mount the motor on a flat, rigid interface and avoid using fasteners to pull a misaligned assembly into position.

Shaft, Coupling and Load Path

PARAMETER	PUBLISHED VALUE	UNIT
Rotor Inertia	0.28 ()	Kg·cm ²

- Align the driven shaft and coupling before tightening; validate radial, axial and moment loads against applicable bearing-load data.
- Do not hammer, uncontrolled press-fit or transmit installation force through the motor bearings.

Electrical, Feedback and Brake Integration

PARAMETER	PUBLISHED VALUE	UNIT
Rated Voltage	220	VAC
Position Feedback Device	17-bit multi-turn communication magnetic absolute encoder	

- Use only the current winding, feedback, brake and connector definitions for this exact SKU.
- Verify drive compatibility, polarity, current limits, feedback direction and brake sequencing before enabling torque.

Thermal, Duty and Environmental Conditions

PARAMETER	PUBLISHED VALUE	UNIT
Rated Torque	0.64	Nm
Operating Temperature	-20 40	°C

- Validate winding and housing temperature under the installed duty cycle, ambient condition, mounting heat path and enclosure airflow.
- Published peak values are transient boundaries and must not be treated as continuous operating ratings.

Cable Routing, Grounding and EMC

PARAMETER	PUBLISHED VALUE	UNIT
Position Feedback Device	17-bit multi-turn communication magnetic absolute encoder	

- Provide strain relief and bend radius through the full machine motion envelope.
- Separate motor power, brake and feedback wiring and terminate shields according to the specified system grounding architecture.

Commissioning and Motion Validation

PARAMETER	PUBLISHED VALUE	UNIT
Rated Speed	3000	rpm
Rated Torque	0.64	Nm

- Commission at low energy with the transmission unloaded or safely restrained, then confirm direction, feedback polarity, brake final integration, current limit and fault response.
- Validate the complete axis through intended acceleration, speed, load, stop and fault cycles during integration planning.

Integration Checklist

- | | |
|----|--|
| 01 | Confirm the exact SKU, 2D drawing and applicable wiring data. |
| 02 | Verify mounting, shaft, coupling, alignment, fasteners and removal clearance. |
| 03 | Validate radial and axial loads, inertia, acceleration and credible shock cases. |
| 04 | Confirm drive, winding, feedback, brake and connector compatibility. |
| 05 | Set current, speed, acceleration and thermal limits from the installed duty cycle. |
| 06 | Verify cable routing, shielding, grounding, strain relief and bend radius. |
| 07 | Commission at low energy before validating the full machine cycle. |

[View SKU Product Datasheet](#) [Request controlled 2D drawing](#) [Request controlled STEP review](#) [Request a Quote](#)

Engineering Use and Verification Notice

01. This Dimensional & Integration Guide applies only to EmbodyStack SKU ES-SM-A03-060D-TOP64NM-200W-002 and is intended for dimensional evaluation and preliminary integration. It is not a applicable manufacturing drawing, wiring definition, application approval, machinery risk assessment, safety validation or integration planning document. Before design freeze, machining, wiring or energization, verify all dimensions, tolerances, mounting and locating features, load boundaries, electrical interfaces, thermal conditions, cabling, grounding, protection, commissioning and applicable regulatory requirements against the applicable EmbodyStack engineering data for this exact SKU. Where this guide and applicable product documentation differ, the applicable product documentation governs. Validate the complete installed system under intended duty cycles, loads, accelerations, environmental conditions and credible fault cases.