ENGINEERING DOCUMENTATION

Rotary Servo Motor

Dimensional & Integration Guide

DOCUMENT	REVISION / ISSUE	STATUS
DIG-ES-SM-A03-060D-T1P27NM-400W-004	DRAFT-08 / 27 Aug 2026	Engineering Integration Reference

Integration Overview

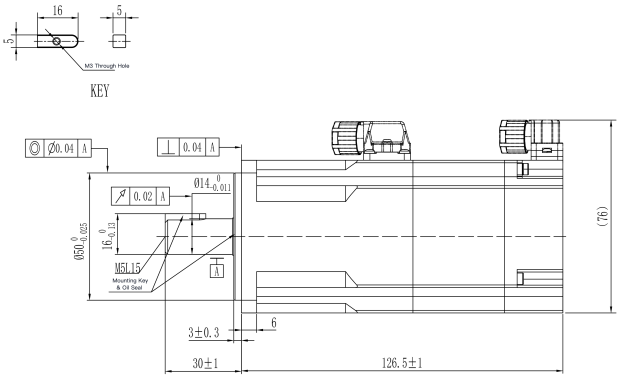
Closed-loop rotary servo motor for specified motion axes. This guide supports mechanical mounting, shaft and coupling integration, feedback and brake planning, cable routing, thermal validation and staged commissioning.

Key Integration Facts

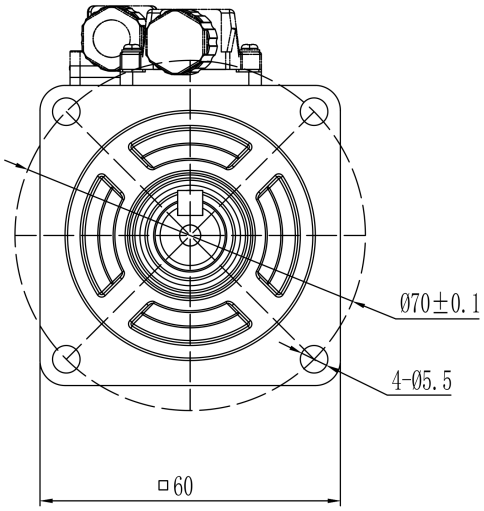
INTEGRATION ITEM	PUBLISHED VALUE
Rated Torque	1.27 N·m
Rated Speed	3000 rpm
Rated Voltage	220 VAC
Flange Size	60 mm

Product Structure & Views

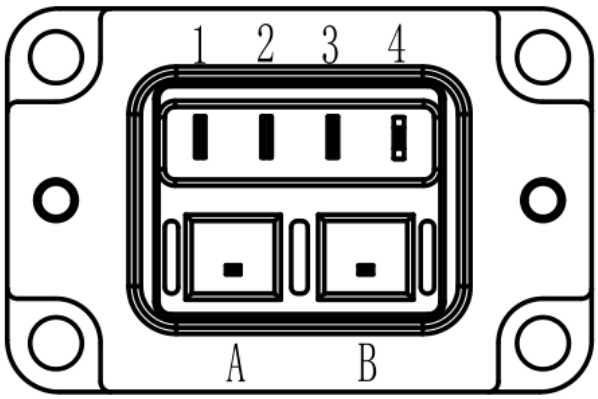
These views present product structure, mounting interfaces and relevant integration geometry for this SKU.



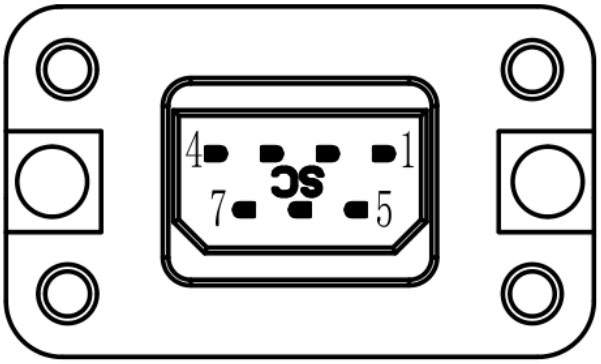
Mechanical View 1



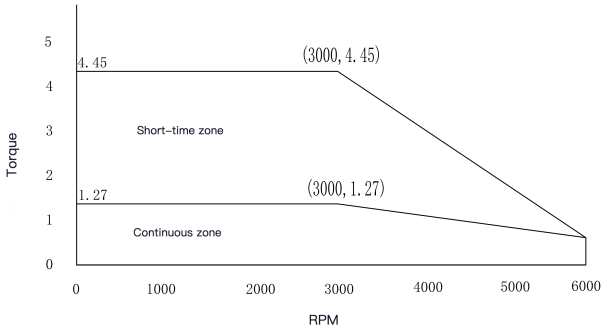
Mechanical View 2



Mechanical View 5



Mechanical View 9



Mechanical View 10

VIEW	FIELD	VALUE
Mechanical View 1	Key feature length	16 mm
	Key feature width	5 mm
	M3 through hole	M3 through hole
	Key feature label	KEY
	Geometric tolerance with diameter tolerance zone to datum A	Diameter tolerance zone 0.04 relative to datum A
	Perpendicularity tolerance to datum A	0.04 relative to datum A
	Shaft diameter	Diameter 14 mm, +0/-0.011 mm
	Geometric tolerance relative to datum A	0.02 relative to datum A
	Reference overall height	76 mm reference
	Diameter 50 feature	Diameter 50 mm, +0/-0.025 mm
	Keyway 16 dimension with tolerance	16 mm, +0/-0.13 mm
	Threaded hole specification	M5 thread, length/depth 15 mm
	Mounting key and oil seal note	Mounting key and oil seal
	Datum A	Datum A
	End step distance	6 mm
	End offset distance	3 mm ±0.3 mm
	Main body length	126.5 mm ±1 mm
	Shaft extension length	30 mm ±1 mm
	Key Width	5 mm
Mechanical View 2	Mounting hole pitch circle diameter	Pitch circle diameter Ø70 ±0.1
	Mounting hole quantity and diameter	4 holes, diameter Ø5.5
	Square flange outside size	Square flange size □60
Mechanical View 5	Connector terminal identifier 2	Connector terminal 2
	Connector terminal identifier 3	Connector terminal 3
	Connector terminal identifier 4	Connector terminal 4
	Connector terminal identifier A	Connector terminal A
	Connector terminal identifier B	Connector terminal B
	Connector Pin 1	Pin 1
Mechanical View 9	Feedback connector pin layout identifiers	Visible feedback connector insert markings: pin identifiers 4, 1, 7, 5 and center marking 3S.
Mechanical View 10	Torque axis tick 5	Torque axis tick = 5
	Short-time zone peak point	Speed = 3000 rpm, torque = 4.45
	Maximum short-time torque callout	Short-time torque level = 4.45
	Torque axis tick 4	Torque axis tick = 4
	Torque axis tick 3	Torque axis tick = 3
	Short-time operating zone label	Short-time operating zone

VIEW	FIELD	VALUE
Vertical axis label	Torque axis	
Torque axis tick 2	Torque axis tick = 2	
Continuous zone rated point	Speed = 3000 rpm, torque = 1.27	
Continuous torque callout	Continuous torque level = 1.27	
Torque axis tick 1	Torque axis tick = 1	
Continuous operating zone label	Continuous operating zone	
Torque axis tick 0	Torque axis tick = 0	
Speed axis tick 4000	Speed axis tick = 4000 rpm	
Speed axis tick 6000	Speed axis tick = 6000 rpm	
Speed axis tick 1000	Speed axis tick = 1000 rpm	
Speed axis tick 5000	Speed axis tick = 5000 rpm	
Speed axis tick 2000	Speed axis tick = 2000 rpm	
Speed axis tick 3000	Speed axis tick = 3000 rpm	
Speed axis tick 0	Speed axis tick = 0 rpm	
Horizontal axis unit label	Speed axis unit = RPM	

Overall Dimensions and Mounting Interface

PARAMETER	PUBLISHED VALUE	UNIT
Flange Size	60	mm

- Confirm the mounting face, locating feature, shaft geometry, fastener engagement and removal clearance against the applicable exact-SKU drawing.
- Mount the motor on a flat, rigid interface and avoid using fasteners to pull a misaligned assembly into position.

Shaft, Coupling and Load Path

PARAMETER	PUBLISHED VALUE	UNIT
Rotor Inertia	0.51( )	Kg·cm2

- Align the driven shaft and coupling before tightening; validate radial, axial and moment loads against applicable bearing-load data.
- Do not hammer, uncontrolled press-fit or transmit installation force through the motor bearings.

Electrical, Feedback and Brake Integration

PARAMETER	PUBLISHED VALUE	UNIT
Rated Voltage	220	VAC
Position Feedback Device	23-bit multi-turn communication optical absolute encoder	

- Use only the current winding, feedback, brake and connector definitions for this exact SKU.
- Verify drive compatibility, polarity, current limits, feedback direction and brake sequencing before enabling torque.

Thermal, Duty and Environmental Conditions

PARAMETER	PUBLISHED VALUE	UNIT
Rated Torque	1.27	N·m
Operating Temperature	-20 40	°C

- Validate winding and housing temperature under the installed duty cycle, ambient condition, mounting heat path and enclosure airflow.
- Published peak values are transient boundaries and must not be treated as continuous operating ratings.

Cable Routing, Grounding and EMC

PARAMETER	PUBLISHED VALUE	UNIT
Position Feedback Device	23-bit multi-turn communication optical absolute encoder	

- Provide strain relief and bend radius through the full machine motion envelope.
- Separate motor power, brake and feedback wiring and terminate shields according to the specified system grounding architecture.

Commissioning and Motion Validation

PARAMETER	PUBLISHED VALUE	UNIT
Rated Speed	3000	rpm
Rated Torque	1.27	N·m

- Commission at low energy with the transmission unloaded or safely restrained, then confirm direction, feedback polarity, brake final integration, current limit and fault response.
- Validate the complete axis through intended acceleration, speed, load, stop and fault cycles during integration planning.

Integration Checklist

01	Confirm the exact SKU, 2D drawing and applicable wiring data.
02	Verify mounting, shaft, coupling, alignment, fasteners and removal clearance.
03	Validate radial and axial loads, inertia, acceleration and credible shock cases.
04	Confirm drive, winding, feedback, brake and connector compatibility.
05	Set current, speed, acceleration and thermal limits from the installed duty cycle.
06	Verify cable routing, shielding, grounding, strain relief and bend radius.
07	Commission at low energy before validating the full machine cycle.

View SKU Product Datasheet Request controlled 2D drawing Request controlled STEP review Request a Quote

Engineering Use and Verification Notice

01. This Dimensional & Integration Guide applies only to EmbodyStack SKU ES-SM-A03-060D-T1P27NM-400W-004 and is intended for dimensional evaluation and preliminary integration. It is not a applicable manufacturing drawing, wiring definition, application approval, machinery risk assessment, safety validation or integration planning document. Before design freeze, machining, wiring or energization, verify all dimensions, tolerances, mounting and locating features, load boundaries, electrical interfaces, thermal conditions, cabling, grounding, protection, commissioning and applicable regulatory requirements against the applicable EmbodyStack engineering data for this exact SKU. Where this guide and applicable product documentation differ, the applicable product documentation governs. Validate the complete installed system under intended duty cycles, loads, accelerations, environmental conditions and credible fault cases.