

ENGINEERING DOCUMENTATION

Rotary Servo Motor

Dimensional & Integration Guide

DOCUMENT	REVISION / ISSUE	STATUS
DIG-ES-SM-A03-060S-TOP64NM-200W-001	DRAFT-08 / 27 Aug 2026	Engineering Integration Reference

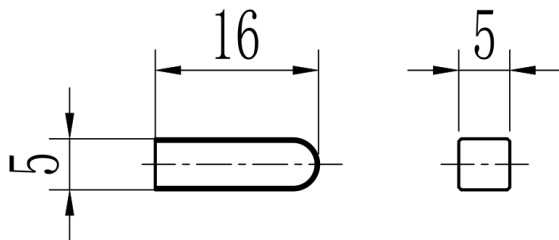
Integration Overview

Closed-loop rotary servo motor for specified motion axes. This guide supports mechanical mounting, shaft and coupling integration, feedback and brake planning, cable routing, thermal validation and staged commissioning.

Key Integration Facts

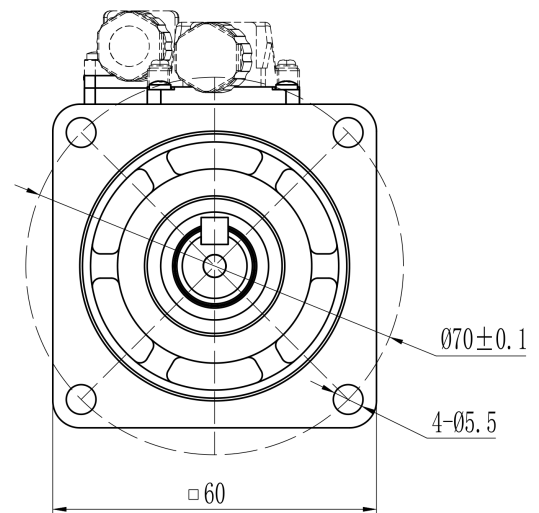
INTEGRATION ITEM	PUBLISHED VALUE
Rated Torque	0.64 Nm
Rated Speed	3000 rpm
Rated Voltage	220 VAC
Flange Size	60 mm

These views present product structure, mounting interfaces and relevant integration geometry for this SKU.

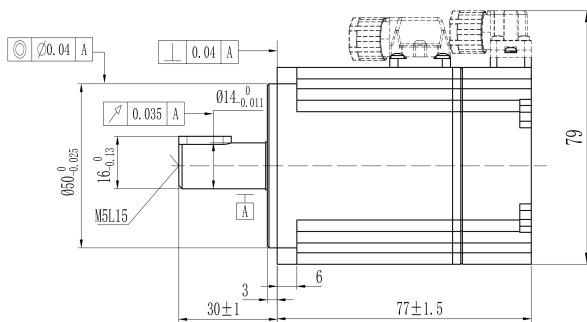


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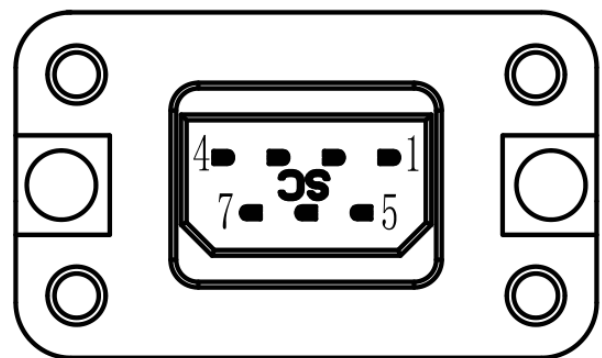
Mechanical View 1



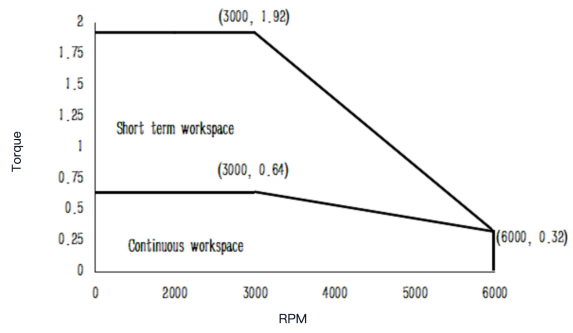
Mechanical View 2



Mechanical View 3



Mechanical View 8



Mechanical View 10

VIEW	FIELD	VALUE
Mechanical View 1	Key length	Key length 16 mm
	Key height	Key height 5 mm
	Key width	Key width 5 mm
	Feature label	Feature labeled KEY
Mechanical View 2	Mounting hole pitch circle diameter	Pitch circle diameter Ø70 ±0.1
	Mounting hole quantity and diameter	4 holes, Ø5.5
	Square flange mounting size	Square flange size 60
Mechanical View 3	Shaft axis positional tolerance	Positional tolerance Ø0.04 relative to datum A
	Perpendicularity tolerance	Perpendicularity tolerance 0.04 relative to datum A
	Shaft diameter	Diameter 14 with tolerance +0/-0.011
	Runout tolerance	Runout tolerance 0.035 relative to datum A
	Pilot diameter	Diameter 50 with tolerance +0/-0.025
	Keyway width	Width 16 with tolerance +0/-0.13
	Datum A	Datum feature A
	Threaded hole specification	M5 thread, depth/length 15
	Step length	Length 6
	Face offset length	Length 3
	Motor body length	Length 77 ±1.5
	Shaft extension length	Length 30 ±1
	Overall height	Overall height 79
	Connector pin number	Pin 5
	Connector pin number	Pin label: 1
	Connector pin number	Pin label: 4
	Connector pin number	Pin label: 7
Mechanical View 10	Torque axis label	Torque axis; unit not specified in OCR source
	Speed axis label	Speed axis in RPM
	Short-term workspace region	Short-term operating region label
	Continuous workspace region	Continuous operating region label
	Maximum short-term torque point	3000 RPM, torque 1.92
	Rated continuous torque point	3000 RPM, torque 0.64
	High-speed continuous torque point	6000 RPM, torque 0.32
	Torque scale tick labels	Y-axis tick labels from 0 to 2
	Speed scale tick labels	X-axis tick labels from 0 to 6000 RPM

Overall Dimensions and Mounting Interface

PARAMETER	PUBLISHED VALUE	UNIT
Flange Size	60	mm

- Confirm the mounting face, locating feature, shaft geometry, fastener engagement and removal clearance against the applicable exact-SKU drawing.
- Mount the motor on a flat, rigid interface and avoid using fasteners to pull a misaligned assembly into position.

Shaft, Coupling and Load Path

PARAMETER	PUBLISHED VALUE	UNIT
Rotor Inertia	0.174 ()	Kg·cm ²

- Align the driven shaft and coupling before tightening; validate radial, axial and moment loads against applicable bearing-load data.
- Do not hammer, uncontrolled press-fit or transmit installation force through the motor bearings.

Electrical, Feedback and Brake Integration

PARAMETER	PUBLISHED VALUE	UNIT
Rated Voltage	220	VAC
Position Feedback Device	17-bit multi-turn communication magnetic absolute encoder	

- Use only the current winding, feedback, brake and connector definitions for this exact SKU.
- Verify drive compatibility, polarity, current limits, feedback direction and brake sequencing before enabling torque.

Thermal, Duty and Environmental Conditions

PARAMETER	PUBLISHED VALUE	UNIT
Rated Torque	0.64	Nm
Operating Temperature	-20 40	°C

- Validate winding and housing temperature under the installed duty cycle, ambient condition, mounting heat path and enclosure airflow.
- Published peak values are transient boundaries and must not be treated as continuous operating ratings.

Cable Routing, Grounding and EMC

PARAMETER	PUBLISHED VALUE	UNIT
Position Feedback Device	17-bit multi-turn communication magnetic absolute encoder	

- Provide strain relief and bend radius through the full machine motion envelope.
- Separate motor power, brake and feedback wiring and terminate shields according to the specified system grounding architecture.

Commissioning and Motion Validation

PARAMETER	PUBLISHED VALUE	UNIT
Rated Speed	3000	rpm
Rated Torque	0.64	Nm

- Commission at low energy with the transmission unloaded or safely restrained, then confirm direction, feedback polarity, brake final integration, current limit and fault response.
- Validate the complete axis through intended acceleration, speed, load, stop and fault cycles during integration planning.

Integration Checklist

- | | |
|----|--|
| 01 | Confirm the exact SKU, 2D drawing and applicable wiring data. |
| 02 | Verify mounting, shaft, coupling, alignment, fasteners and removal clearance. |
| 03 | Validate radial and axial loads, inertia, acceleration and credible shock cases. |
| 04 | Confirm drive, winding, feedback, brake and connector compatibility. |
| 05 | Set current, speed, acceleration and thermal limits from the installed duty cycle. |
| 06 | Verify cable routing, shielding, grounding, strain relief and bend radius. |
| 07 | Commission at low energy before validating the full machine cycle. |

[View SKU Product Datasheet](#) [Request controlled 2D drawing](#) [Request controlled STEP review](#) [Request a Quote](#)

Engineering Use and Verification Notice

01. This Dimensional & Integration Guide applies only to EmbodyStack SKU ES-SM-A03-060S-TOP64NM-200W-001 and is intended for dimensional evaluation and preliminary integration. It is not a applicable manufacturing drawing, wiring definition, application approval, machinery risk assessment, safety validation or integration planning document. Before design freeze, machining, wiring or energization, verify all dimensions, tolerances, mounting and locating features, load boundaries, electrical interfaces, thermal conditions, cabling, grounding, protection, commissioning and applicable regulatory requirements against the applicable EmbodyStack engineering data for this exact SKU. Where this guide and applicable product documentation differ, the applicable product documentation governs. Validate the complete installed system under intended duty cycles, loads, accelerations, environmental conditions and credible fault cases.