ENGINEERING DOCUMENTATION

Rotary Servo Motor

Dimensional & Integration Guide

DOCUMENT	REVISION / ISSUE	STATUS
DIG-ES-SM-A03-180G-T28NM-4400W-001	DRAFT-08 / 27 Aug 2026	Engineering Integration Reference

Integration Overview

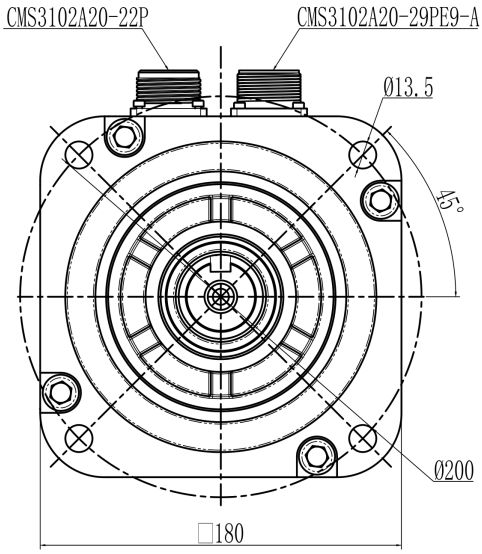
Closed-loop rotary servo motor for specified motion axes. This guide supports mechanical mounting, shaft and coupling integration, feedback and brake planning, cable routing, thermal validation and staged commissioning.

Key Integration Facts

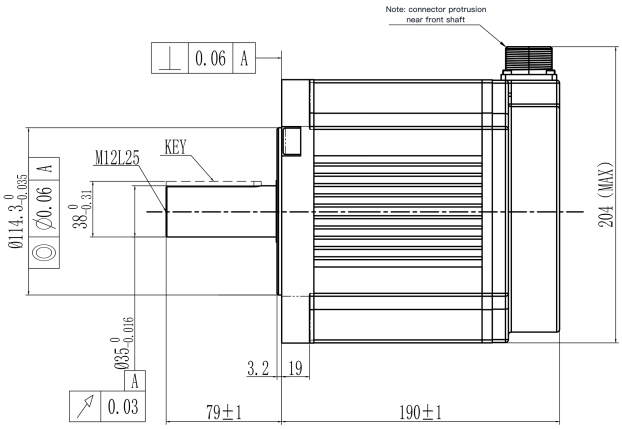
INTEGRATION ITEM	PUBLISHED VALUE
Rated Torque	28 N·m
Rated Speed	1500 rpm
Rated Voltage	380 VAC
Flange Size	180 mm

Product Structure & Views

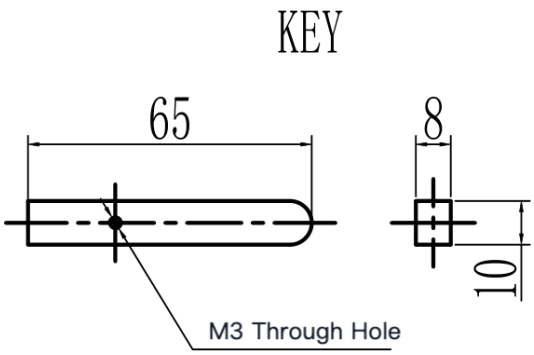
These views present product structure, mounting interfaces and relevant integration geometry for this SKU.



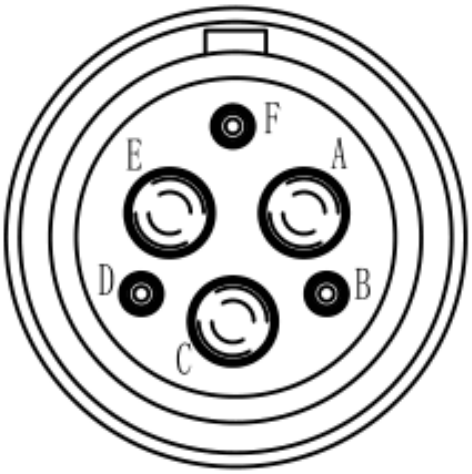
Mechanical View 1



Mechanical View 2



Mechanical View 3



Mechanical View 5

Mechanical View 7

VIEW	FIELD	VALUE
Mechanical View 1	Mounting hole diameter	Ø13.5 mm
	Flange bolt circle diameter	Ø200 mm
	Square flange side length	180 mm
	Mounting hole angular position	45 degrees
Mechanical View 2	Installation note	Connector protrusion positioned near front shaft
	Position tolerance	Position tolerance 0.06 with datum A
	Keyway identifier	Keyway present
	Mounting bolt specification	M12 thread, L25 length
	Housing length maximum	204 mm maximum
	Mounting flange diameter	Ø114.3 +0/-0.035 mm
	Shaft length	38 +0/-0.31 mm
	Shaft diameter	Ø35 +0/-0.016 mm
	Keyway width	3.2 mm
	Keyway length	19 mm
	Datum A	Datum A reference
	Surface profile tolerance	Surface profile 0.03 with datum A
	Overall length	190±1 mm
	Housing length	79±1 mm
Mechanical View 3	Keyway length	65 mm
	Keyway width	8 mm
	Keyway depth	10 mm
	Through hole specification	M3 clearance hole
	Keyway designation	KEY
Mechanical View 5	Connector pin position F	Pin position F
	Connector pin position E	Pin position E
	Connector pin position A	Pin position A
	Connector pin position D	Pin position D
	Connector pin position B	Pin position B
	Connector pin position C	Pin C
Mechanical View 7	Connector designation	20-29P
	Connector Contact Letter Designation	A, B, C, D, ...

Overall Dimensions and Mounting Interface

PARAMETER	PUBLISHED VALUE	UNIT
Flange Size	180	mm

- Confirm the mounting face, locating feature, shaft geometry, fastener engagement and removal clearance against the applicable exact-SKU drawing.
- Mount the motor on a flat, rigid interface and avoid using fasteners to pull a misaligned assembly into position.

Shaft, Coupling and Load Path

PARAMETER	PUBLISHED VALUE	UNIT
Rotor Inertia	73.5 ( )	Kg·cm2

- Align the driven shaft and coupling before tightening; validate radial, axial and moment loads against applicable bearing-load data.
- Do not hammer, uncontrolled press-fit or transmit installation force through the motor bearings.

Electrical, Feedback and Brake Integration

PARAMETER	PUBLISHED VALUE	UNIT
Rated Voltage	380	VAC
Position Feedback Device	17-bit multi-turn communication magnetic absolute encoder	

- Use only the current winding, feedback, brake and connector definitions for this exact SKU.
- Verify drive compatibility, polarity, current limits, feedback direction and brake sequencing before enabling torque.

Thermal, Duty and Environmental Conditions

PARAMETER	PUBLISHED VALUE	UNIT
Rated Torque	28	N·m
Operating Temperature	20 40	°C

- Validate winding and housing temperature under the installed duty cycle, ambient condition, mounting heat path and enclosure airflow.
- Published peak values are transient boundaries and must not be treated as continuous operating ratings.

Cable Routing, Grounding and EMC

PARAMETER	PUBLISHED VALUE	UNIT
Position Feedback Device	17-bit multi-turn communication magnetic absolute encoder	

- Provide strain relief and bend radius through the full machine motion envelope.
- Separate motor power, brake and feedback wiring and terminate shields according to the specified system grounding architecture.

Commissioning and Motion Validation

PARAMETER	PUBLISHED VALUE	UNIT
Rated Speed	1500	rpm
Rated Torque	28	N·m

- Commission at low energy with the transmission unloaded or safely restrained, then confirm direction, feedback polarity, brake final integration, current limit and fault response.
- Validate the complete axis through intended acceleration, speed, load, stop and fault cycles during integration planning.

Integration Checklist

01	Confirm the exact SKU, 2D drawing and applicable wiring data.
02	Verify mounting, shaft, coupling, alignment, fasteners and removal clearance.
03	Validate radial and axial loads, inertia, acceleration and credible shock cases.
04	Confirm drive, winding, feedback, brake and connector compatibility.
05	Set current, speed, acceleration and thermal limits from the installed duty cycle.
06	Verify cable routing, shielding, grounding, strain relief and bend radius.
07	Commission at low energy before validating the full machine cycle.

View SKU Product Datasheet Request controlled 2D drawing Request controlled STEP review Request a Quote

Engineering Use and Verification Notice

01. This Dimensional & Integration Guide applies only to EmbodyStack SKU ES-SM-A03-180G-T28NM-4400W-001 and is intended for dimensional evaluation and preliminary integration. It is not a applicable manufacturing drawing, wiring definition, application approval, machinery risk assessment, safety validation or integration planning document. Before design freeze, machining, wiring or energization, verify all dimensions, tolerances, mounting and locating features, load boundaries, electrical interfaces, thermal conditions, cabling, grounding, protection, commissioning and applicable regulatory requirements against the applicable EmbodyStack engineering data for this exact SKU. Where this guide and applicable product documentation differ, the applicable product documentation governs. Validate the complete installed system under intended duty cycles, loads, accelerations, environmental conditions and credible fault cases.