

ENGINEERING DOCUMENTATION

Rotary Servo Motor

Dimensional & Integration Guide

DOCUMENT	REVISION / ISSUE	STATUS
DIG-ES-SM-L01-080S-V48-TTBDNM-1000W-001	DRAFT-08 / 27 Aug 2026	Engineering Integration Reference

Integration Overview

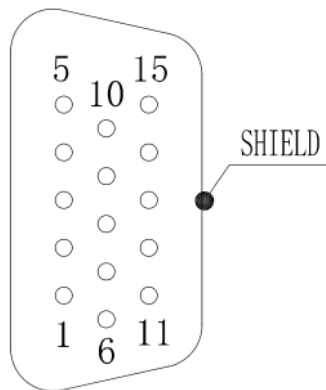
Closed-loop rotary servo motor for specified motion axes. This guide supports mechanical mounting, shaft and coupling integration, feedback and brake planning, cable routing, thermal validation and staged commissioning.

Key Integration Facts

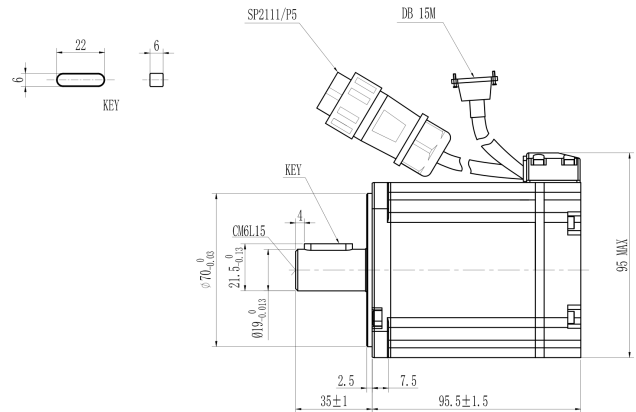
INTEGRATION ITEM	PUBLISHED VALUE
Rated Speed	3000 rpm
Rated Voltage	48 VDC
Flange Size	80 mm

Product Structure & Views

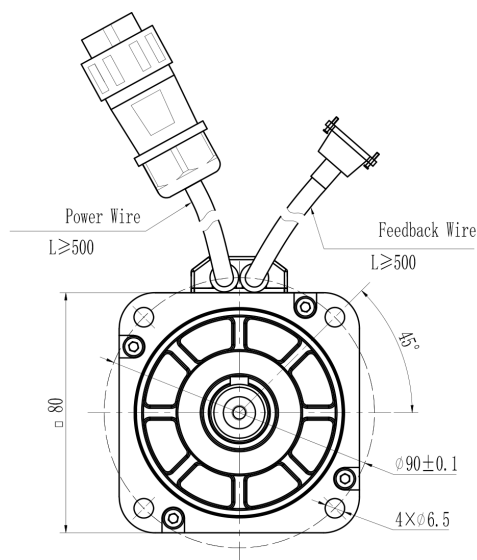
These views present product structure, mounting interfaces and relevant integration geometry for this SKU.



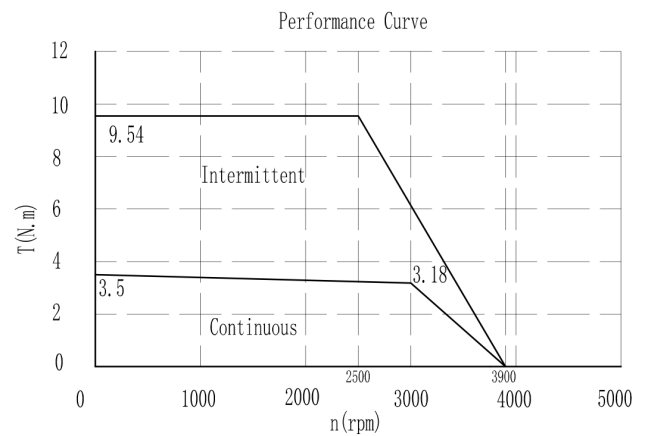
Mechanical View 3



Mechanical View 4



Mechanical View 5



Mechanical View 7

VIEW	FIELD	VALUE
Mechanical View 3	Feedback Connector Pin 5	Pin 5
	Feedback Connector Pin 15	Pin 15
	Feedback Connector Pin 10	Pin 10
	Shield Connection	Shield terminal
	Feedback Connector Pin 1	Pin 1
	Feedback Connector Pin 11	Pin 11
	Feedback Connector Pin 6	Pin 6
Mechanical View 4	DB15M Connector	DB15M
	SP2111/P5 Connector	SP2111/P5
	Keyway Length	22 mm
	Keyway Width	6 mm
	Keyway Depth	6 mm
	Keyway Label	Keyway
	CM6L15 Connector	CM6L15
	Shaft Diameter with Tolerance	Ø70 0/-0.03 mm
	Shaft Length with Tolerance	21.5 0/-0.13 mm
	Hole Diameter with Tolerance	Ø19 0/-0.013 mm
	Maximum Height	95 mm MAX
	Mounting Dimension 1	2.5 mm
	Mounting Dimension 2	7.5 mm
	Mounting Dimension with Tolerance	35±1 mm
	Overall Length with Tolerance	95.5±1.5 mm
	Mechanical Dimension	4 mm
Mechanical View 5	Power wire minimum length	L ≥500 mm
	Feedback wire minimum length	L ≥500 mm
	Mounting flange square dimension	80 × 80 mm square flange
	Mounting hole pitch circle diameter	Ø90 ±0.1 mm
	Mounting hole diameter and quantity	4 × Ø6.5 mm holes
	Mounting hole angular position	45°
Mechanical View 7	Chart title	Performance curve
	Torque axis	Torque T in N.m
	Speed axis	Rotational speed n in rpm
	Intermittent torque plateau	Intermittent torque is 9.54 N.m up to 2500 rpm
	Intermittent zero-torque endpoint	Intermittent curve descends to 0 N.m at 3900 rpm
	Continuous starting torque	Continuous torque starts at 3.5 N.m
	Continuous torque knee point	Continuous curve knee torque is 3.18 N.m near 3000 rpm

VIEW	FIELD	VALUE
Speed scale tick labels	Speed axis tick labels: 0, 1000, 2000, 3000, 4000, 5000 rpm	
Torque scale tick labels	Torque axis tick labels: 0, 2, 4, 6, 8, 10, 12 N.m	

Overall Dimensions and Mounting Interface

PARAMETER	PUBLISHED VALUE	UNIT
Flange Size	80	mm

- Confirm the mounting face, locating feature, shaft geometry, fastener engagement and removal clearance against the applicable exact-SKU drawing.
- Mount the motor on a flat, rigid interface and avoid using fasteners to pull a misaligned assembly into position.

Shaft, Coupling and Load Path

- Align the driven shaft and coupling before tightening; validate radial, axial and moment loads against applicable bearing-load data.
- Do not hammer, uncontrolled press-fit or transmit installation force through the motor bearings.

Electrical, Feedback and Brake Integration

PARAMETER	PUBLISHED VALUE	UNIT
Rated Voltage	48	VDC

- Use only the current winding, feedback, brake and connector definitions for this exact SKU.
- Verify drive compatibility, polarity, current limits, feedback direction and brake sequencing before enabling torque.

Thermal, Duty and Environmental Conditions

- Validate winding and housing temperature under the installed duty cycle, ambient condition, mounting heat path and enclosure airflow.
- Published peak values are transient boundaries and must not be treated as continuous operating ratings.

Cable Routing, Grounding and EMC

- Provide strain relief and bend radius through the full machine motion envelope.
- Separate motor power, brake and feedback wiring and terminate shields according to the specified system grounding architecture.

Commissioning and Motion Validation

PARAMETER	PUBLISHED VALUE	UNIT
Rated Speed	3000	rpm

- Commission at low energy with the transmission unloaded or safely restrained, then confirm direction, feedback polarity, brake final integration, current limit and fault response.
- Validate the complete axis through intended acceleration, speed, load, stop and fault cycles during integration planning.

Integration Checklist

- | | |
|----|--|
| 01 | Confirm the exact SKU, 2D drawing and applicable wiring data. |
| 02 | Verify mounting, shaft, coupling, alignment, fasteners and removal clearance. |
| 03 | Validate radial and axial loads, inertia, acceleration and credible shock cases. |
| 04 | Confirm drive, winding, feedback, brake and connector compatibility. |
| 05 | Set current, speed, acceleration and thermal limits from the installed duty cycle. |
| 06 | Verify cable routing, shielding, grounding, strain relief and bend radius. |
| 07 | Commission at low energy before validating the full machine cycle. |

[View SKU Product Datasheet](#) [Request controlled 2D drawing](#) [Request controlled STEP review](#) [Request a Quote](#)

Engineering Use and Verification Notice

01. This Dimensional & Integration Guide applies only to EmbodyStack SKU ES-SM-L01-080S-V48-TTBDNM-1000W-001 and is intended for dimensional evaluation and preliminary integration. It is not a applicable manufacturing drawing, wiring definition, application approval, machinery risk assessment, safety validation or integration planning document. Before design freeze, machining, wiring or energization, verify all dimensions, tolerances, mounting and locating features, load boundaries, electrical interfaces, thermal conditions, cabling, grounding, protection, commissioning and applicable regulatory requirements against the applicable EmbodyStack engineering data for this exact SKU. Where this guide and applicable product documentation differ, the applicable product documentation governs. Validate the complete installed system under intended duty cycles, loads, accelerations, environmental conditions and credible fault cases.