

ENGINEERING DOCUMENTATION

Hybrid Rotary Stepper Motor

Dimensional & Integration Guide

DOCUMENT	REVISION / ISSUE	STATUS
DIG-ES-ST-17H2034-050-4BL	DRAFT-08 / 28 Aug 2026	Engineering Integration Reference

Integration Overview

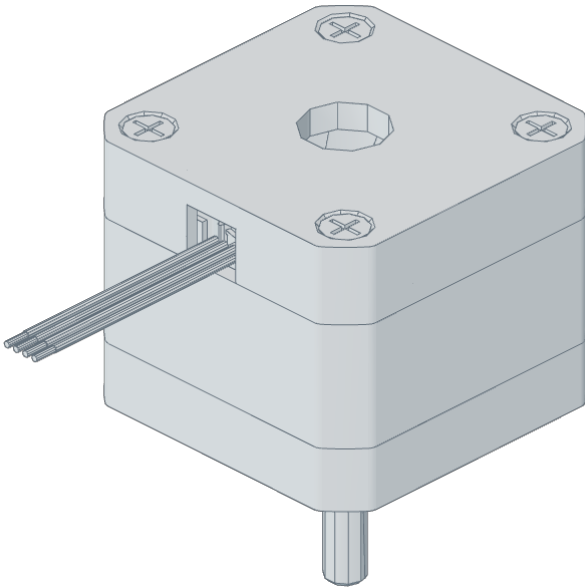
Hybrid stepper motor for indexed positioning and specified rotary motion. This guide supports mounting, shaft, load-path, drive-current, phase, thermal, cable and commissioning planning for ES-ST-17H2034-050-4BL.

Key Integration Facts

INTEGRATION ITEM	VALUE
Holding Torque	0.25 N·m
Rotor Inertia	25 g·cm ²
Temperature Rise	80 °C
Number of Phases	2
Phase Resistance	15 Ω ±10% Ω
Continuous Rated Current	0.5 A
Phase Inductance	21 mH ±20% mH
Insulation Class	B

3D Orientation Reference

This axonometric reference provides a quick orientation check for the motor or actuator body, output interface and mounting relationship of ES-ST-17H2034-050-4BL.



Axonometric Orientation View

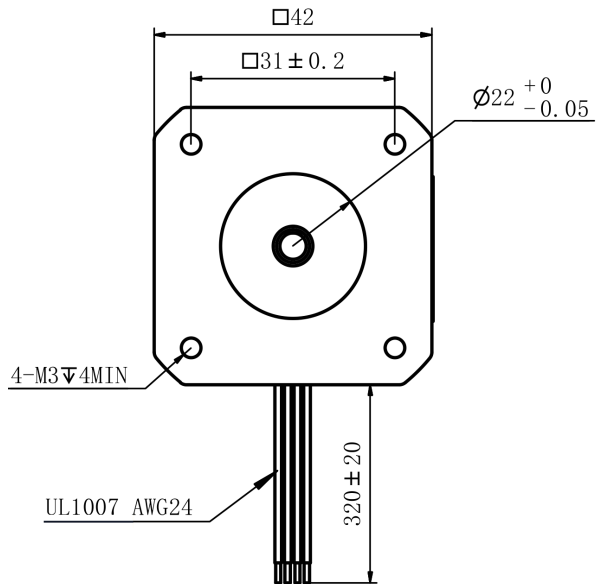
Orientation reference only. Use the exact-SKU parameter table and mechanical drawing for dimensions, hole geometry, fits and machining decisions.

Exact-SKU Interface Cross-Reference

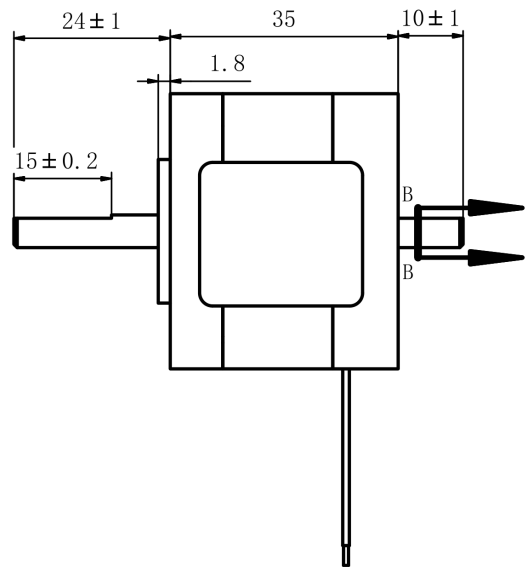
INTEGRATION TOPIC	EXACT-SKU REFERENCE
Motor envelope and output orientation	Body Length: 35 mm. Confirm interface geometry, fits and installation details in the exact-SKU mechanical drawing.
Drive and motion boundaries	Continuous Rated Current: 0.5 A; Holding Torque: 0.25 Nm; Step Angle: 1.8 °. Confirm interface geometry, fits and installation details in the exact-SKU mechanical drawing.
Installed load and thermal reference	Rotor Inertia: 25 gcm ² ; Weight: 0.23 kg; Temperature Rise: 80 °C; Insulation Class: B. Confirm interface geometry, fits and installation details in the exact-SKU mechanical drawing.

Product Structure & Views

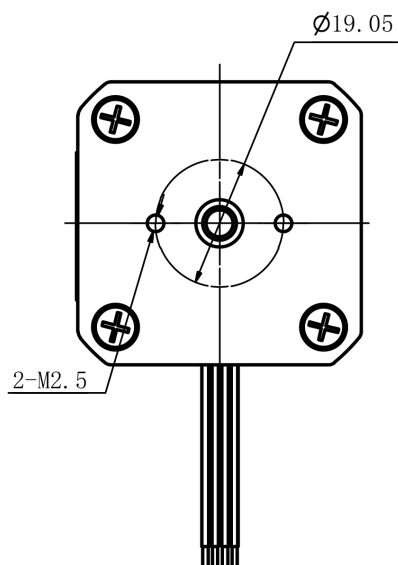
These views present product structure, mounting interfaces and relevant integration geometry for this SKU.



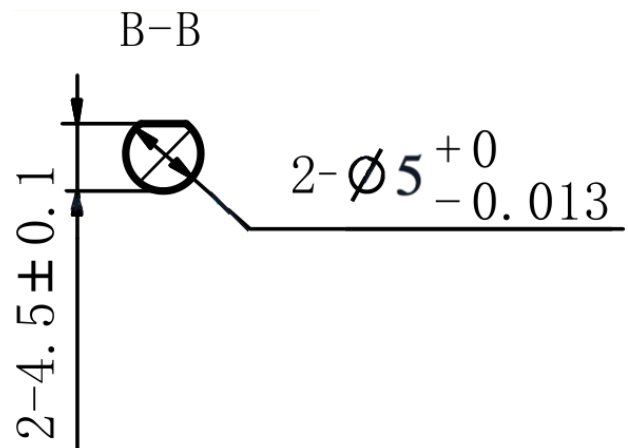
Mechanical View 1



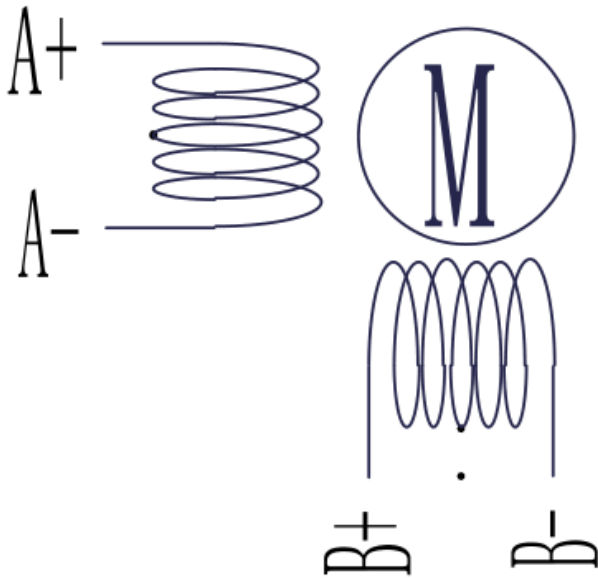
Mechanical View 2



Mechanical View 3



Mechanical View 4



Mechanical View 8

VIEW	FIELD	VALUE
Mechanical View 1	Mounting flange square dimension	42×42 mm square
	Mounting hole pattern square	31±0.2 mm square PCD
	Output shaft diameter with tolerance	Ø2 +0/-0.05 mm
	Mounting threaded holes with countersink depth	4×M3 tapped holes, countersink depth ≥4 mm
Mechanical View 3	Right section length	10±1
	Middle section length	35
	Left section length	24±1
	Upper boss height	1.8
	Left mounting boss length	15±0.2
	Section B-B marker upper	B
	Section B-B marker lower	B
Mechanical View 4	Output shaft diameter	Ø19.05
	Mounting screw hole specification	2 places, M2.5 thread
Mechanical View 8	Section identifier	B-B
	Hole diameter with tolerance	2-Φ +0/-0.013
	Mounting hole spacing	2-4.5±0.1

Technical Specifications

PARAMETER	VALUE	UNIT
Holding Torque	0.25	Nm
Rotor Inertia	25	gcm ²
Temperature Rise	80	°C
Number of Phases	2	
Phase Resistance	15 Ω ±10%	Ω
Continuous Rated Current	0.5	A
Phase Inductance	21 mH ±20%	mH
Insulation Class	B	
Insulation Resistance	100 M Ω (500 VDC)	M Ω
Step Angle	1.8	°
Body Length	35	mm
Weight	0.23	kg
Motor Weight	230	g

Mounting, Shaft and Load Path

- Support the complete mounting face, preserve locating features and verify fastener engagement without distorting the housing.
- Align the shaft and coupling before tightening, and validate radial load, axial load, overhung distance, belt tension, inertia and shock for the installed mechanism.

Drive, Electrical and Motion Integration

- Set phase current, microstep, acceleration and speed for the actual load inertia, resonance behavior and installed thermal condition.
- Use applicable wiring data for conductor identity, polarity, phase pairing, shielding and grounding; do not infer these from the product view.

Thermal, Cable and Commissioning Conditions

- Validate housing and winding temperature over the intended operating cycle, ambient condition, mounting heat path and enclosure airflow.
- Provide strain relief and service clearance, then commission at reduced energy and verify direction, current limits, motion response, temperature and fault behavior.

Integration Checklist

- | | |
|----|---|
| 01 | Confirm the exact-SKU drawing and parameter set. |
| 02 | Verify mounting geometry, locating features, shaft engagement, coupling alignment and service clearance. |
| 03 | Validate torque, speed, inertia, radial and axial loads, overhung distance and shock. |
| 04 | Set drive, current, motion, wiring, grounding and thermal boundaries from applicable product documentation. |
| 05 | Commission at reduced energy and verify direction, motion response, temperature and fault behavior. |

[View SKU Product Datasheet](#) [Request controlled 2D drawing](#) [Request controlled STEP review](#) [Request a Quote](#)

Engineering Use and Verification Notice

01. This Dimensional & Integration Guide applies only to EmbodyStack SKU ES-ST-17H2034-050-4BL and is intended for dimensional evaluation and preliminary integration. It is not a applicable manufacturing drawing, motor or actuator application approval, wiring definition, drive-selection approval, machinery risk assessment, safety validation or production authorization. Before design freeze, installation or energization, verify all dimensions, mounting and locating features, moving envelopes, shaft or output geometry, permissible loads, alignment, supply and current limits, wiring, motion profile, duty cycle, thermal condition, cable routing, environmental boundaries, maintenance and fault response against the applicable EmbodyStack engineering data for this exact SKU. Validate the complete installed system under intended operating and fault conditions.