ENGINEERING DOCUMENTATION

Hybrid Rotary Stepper Motor

Dimensional & Integration Guide

DOCUMENT	REVISION / ISSUE	STATUS
DIG-ES-ST-17H2041-100-4BL	DRAFT-08 / 28 Aug 2026	Engineering Integration Reference

Integration Overview

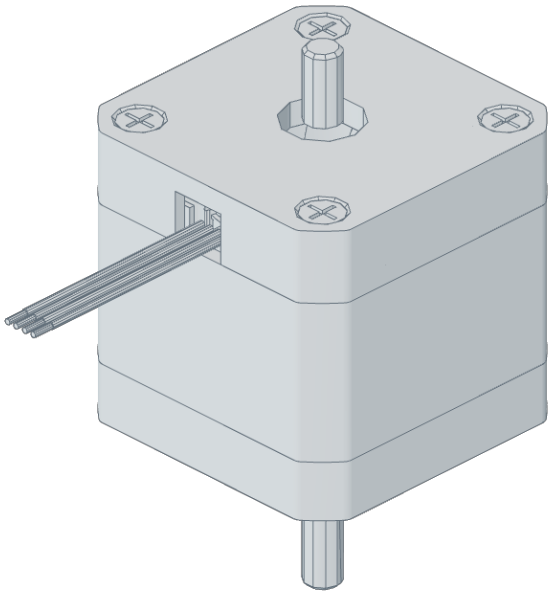
Hybrid stepper motor for indexed positioning and specified rotary motion. This guide supports mounting, shaft, load-path, drive-current, phase, thermal, cable and commissioning planning for ES-ST-17H2041-100-4BL.

Key Integration Facts

INTEGRATION ITEM	VALUE
Holding Torque	0.4 N·m
Rotor Inertia	54 g·cm²
Temperature Rise	80 °C
Number of Phases	2
Phase Resistance	4.3 Ω±10% Ω
Continuous Rated Current	1 A
Phase Inductance	8 mH ±20% mH
Insulation Class	B

3D Orientation Reference

This axonometric reference provides a quick orientation check for the motor or actuator body, output interface and mounting relationship of ES-ST-17H2041-100-4BL.



Axonometric Orientation View

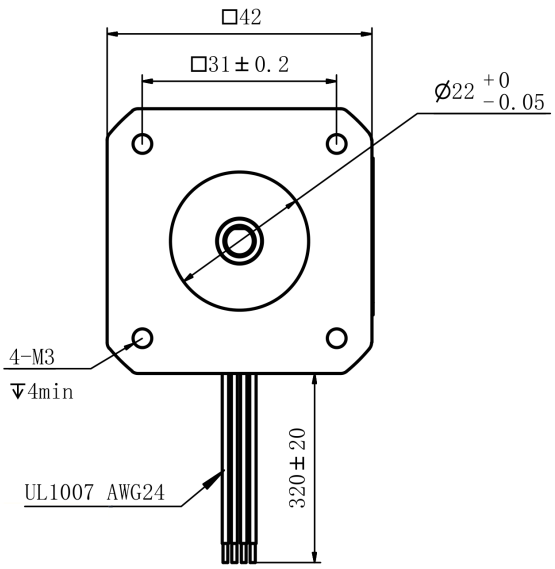
Orientation reference only. Use the exact-SKU parameter table and mechanical drawing for dimensions, hole geometry, fits and machining decisions.

Exact-SKU Interface Cross-Reference

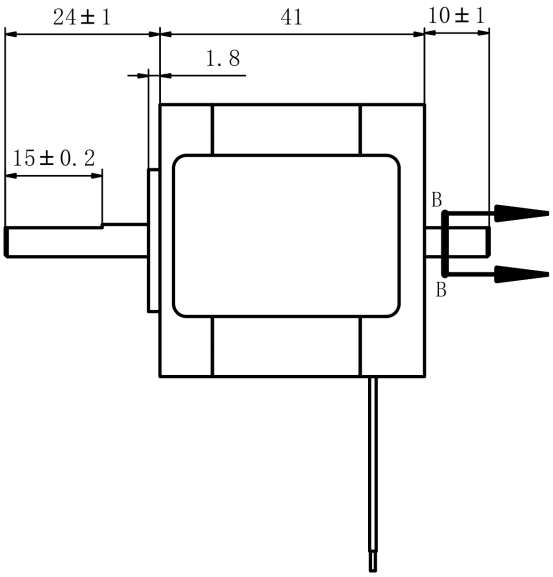
INTEGRATION TOPIC	EXACT-SKU REFERENCE
Motor envelope and output orientation	Body Length: 41 mm. Confirm interface geometry, fits and installation details in the exact-SKU mechanical drawing.
Drive and motion boundaries	Continuous Rated Current: 1 A; Holding Torque: 0.4 N·m; Step Angle: 1.8 °. Confirm interface geometry, fits and installation details in the exact-SKU mechanical drawing.
Installed load and thermal reference	Rotor Inertia: 54 g·cm²; Weight: 0.3 kg; Temperature Rise: 80 °C; Insulation Class: B. Confirm interface geometry, fits and installation details in the exact-SKU mechanical drawing.

Product Structure & Views

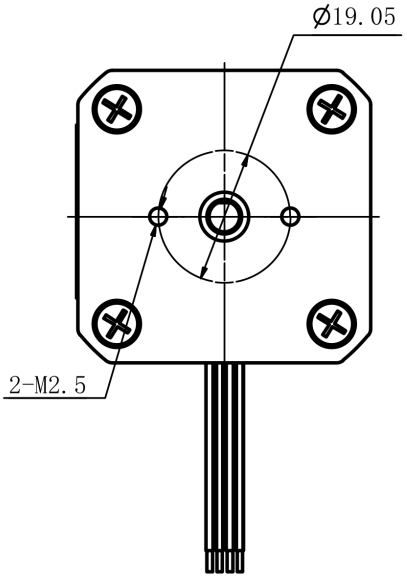
These views present product structure, mounting interfaces and relevant integration geometry for this SKU.



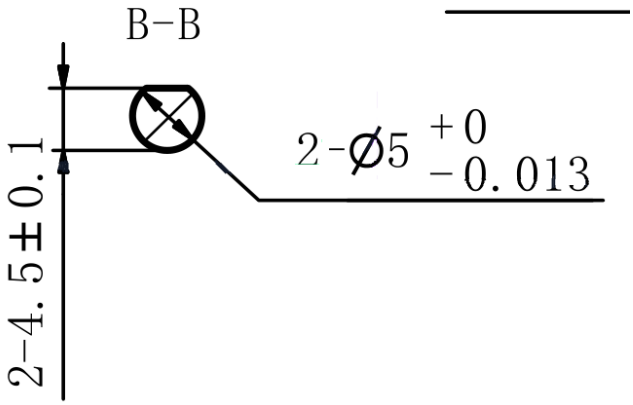
Mechanical View 1



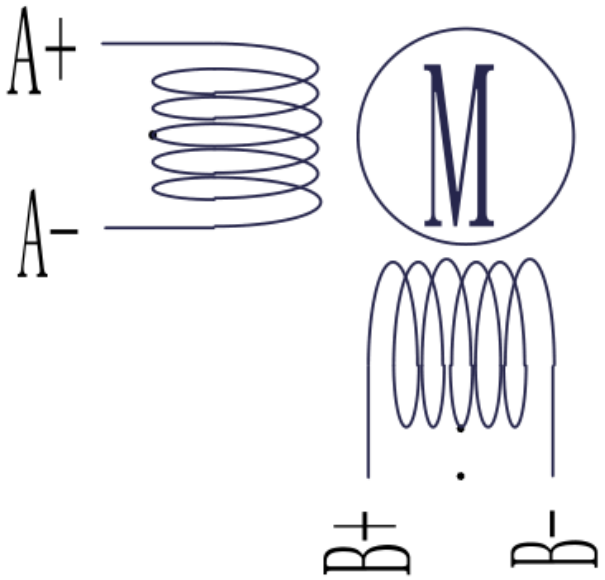
Mechanical View 2



Mechanical View 3



Mechanical View 4



Mechanical View 8

VIEW	FIELD	VALUE
Mechanical View 1	Motor faceplate overall dimension	42 mm square
	Motor faceplate center boss dimension	31±0.2 mm square
	Output shaft diameter with tolerance	Φ2 +0/-0.05 mm
	Mounting hole specification	4× M3 threaded holes
	Surface roughness	Ra ≤4 μm minimum
Mechanical View 3	Overall length (left section)	24±1
	Overall length (middle section)	41
	Overall length (right section)	10±1
	Mounting bracket vertical offset	1.8
	Mounting bracket horizontal width	15±0.2
	Section datum (upper)	B
	Section datum (lower)	B
Mechanical View 4	Output shaft diameter	Φ9.05 mm
	Mounting threaded hole specification and quantity	2× M2.5 threaded holes
Mechanical View 8	Section identifier	B-B
	Two holes diameter with tolerance	2-ϕ5 +0/-0.013
	Two mounting holes center distance with tolerance	2-4.5±0.1

Technical Specifications

PARAMETER	VALUE	UNIT
Holding Torque	0.4	N·m
Rotor Inertia	54	g·cm²
Temperature Rise	80	°C
Number of Phases	2	
Phase Resistance	4.3 Ω±10%	Ω
Continuous Rated Current	1	A
Phase Inductance	8 mH ±20%	mH
Insulation Class	B	
Insulation Resistance	100 MΩ(500 VDC)	MΩ
Step Angle	1.8	°
Body Length	41	mm
Weight	0.3	kg
Motor Weight	300	g

Mounting, Shaft and Load Path

- Support the complete mounting face, preserve locating features and verify fastener engagement without distorting the housing.
- Align the shaft and coupling before tightening, and validate radial load, axial load, overhung distance, belt tension, inertia and shock for the installed mechanism.

Drive, Electrical and Motion Integration

- Set phase current, microstep, acceleration and speed for the actual load inertia, resonance behavior and installed thermal condition.
- Use applicable wiring data for conductor identity, polarity, phase pairing, shielding and grounding; do not infer these from the product view.

Thermal, Cable and Commissioning Conditions

- Validate housing and winding temperature over the intended operating cycle, ambient condition, mounting heat path and enclosure airflow.
- Provide strain relief and service clearance, then commission at reduced energy and verify direction, current limits, motion response, temperature and fault behavior.

Integration Checklist

01	Confirm the exact-SKU drawing and parameter set.
02	Verify mounting geometry, locating features, shaft engagement, coupling alignment and service clearance.
03	Validate torque, speed, inertia, radial and axial loads, overhung distance and shock.
04	Set drive, current, motion, wiring, grounding and thermal boundaries from applicable product documentation.
05	Commission at reduced energy and verify direction, motion response, temperature and fault behavior.

View SKU Product Datasheet Request controlled 2D drawing Request controlled STEP review Request a Quote

Engineering Use and Verification Notice

01. This Dimensional & Integration Guide applies only to EmbodyStack SKU ES-ST-17H2041-100-4BL and is intended for dimensional evaluation and preliminary integration. It is not a applicable manufacturing drawing, motor or actuator application approval, wiring definition, drive-selection approval, machinery risk assessment, safety validation or production authorization. Before design freeze, installation or energization, verify all dimensions, mounting and locating features, moving envelopes, shaft or output geometry, permissible loads, alignment, supply and current limits, wiring, motion profile, duty cycle, thermal condition, cable routing, environmental boundaries, maintenance and fault response against the applicable EmbodyStack engineering data for this exact SKU. Validate the complete installed system under intended operating and fault conditions.